

a Lecture on

Practical Aspects of Optimization

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HERE ARE MY CORRECTIONS. I WANT TO SEE IT AGAIN BEFORE YOU SUBMIT IT.



MAKES CORRECTIONS

THE ENDLESS CYCLE?

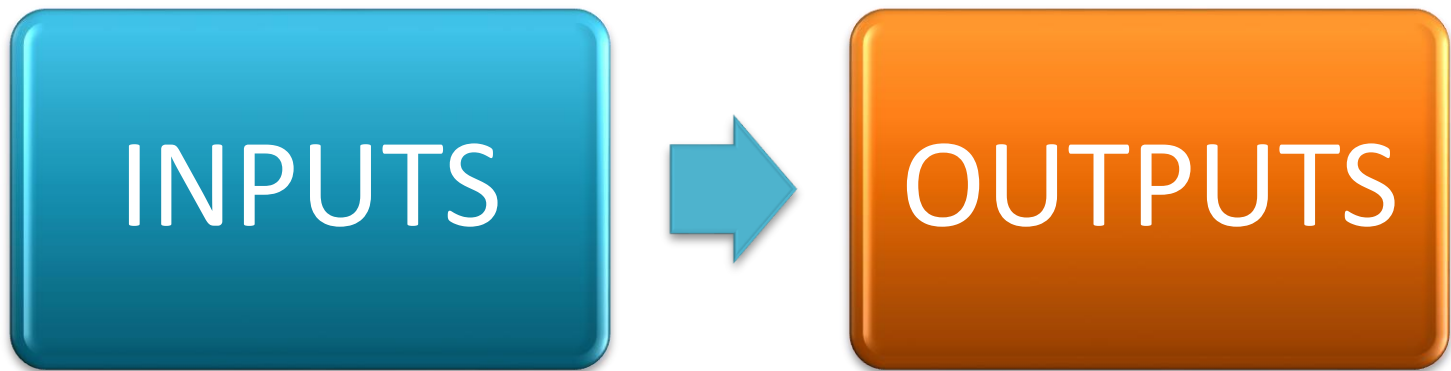


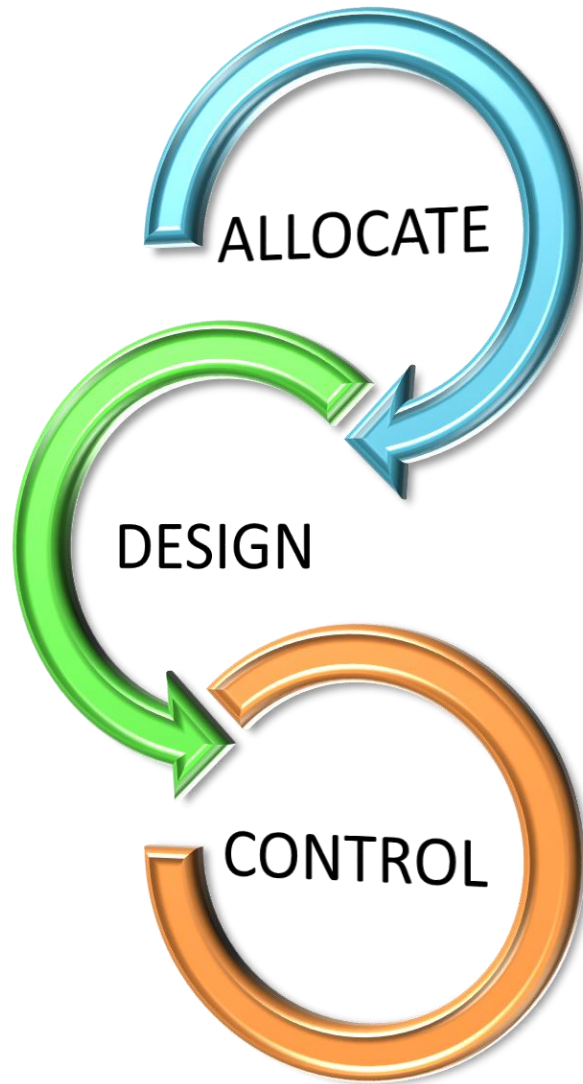
MAKES EDITS

HERE'S THE LATEST DRAFT.

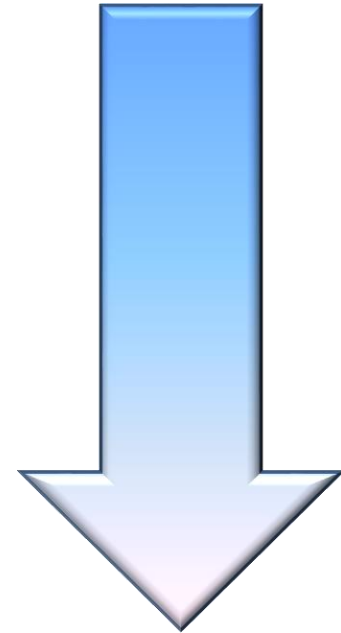
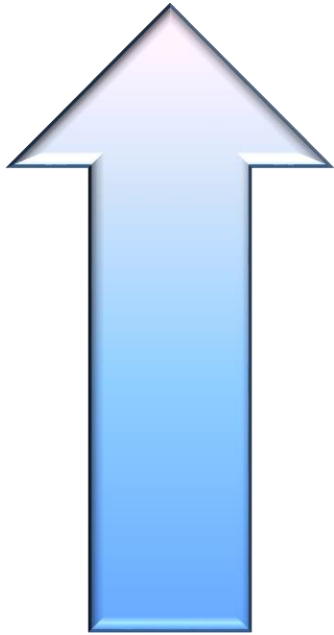


What is Optimization ?

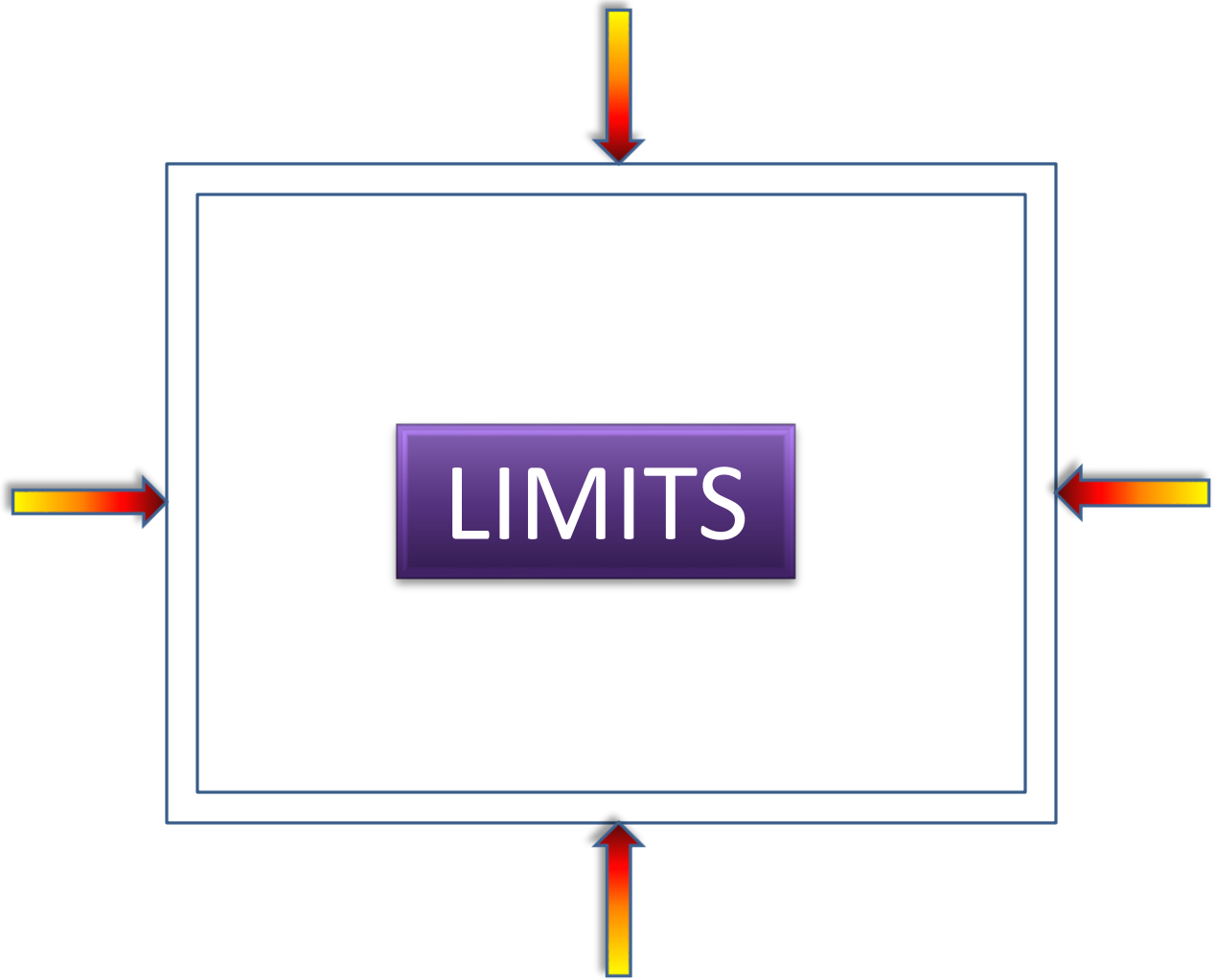




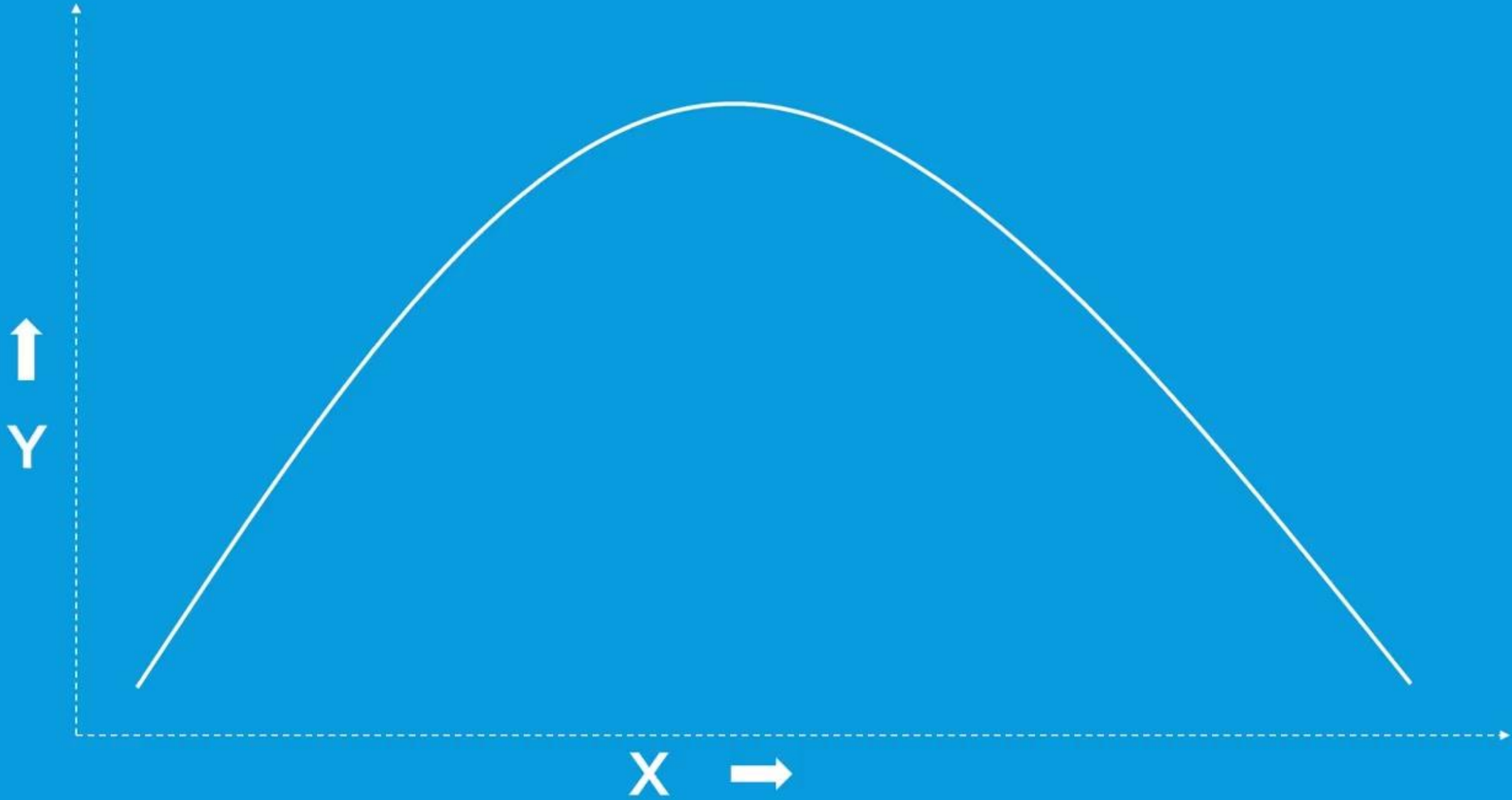
MAXIMIZE

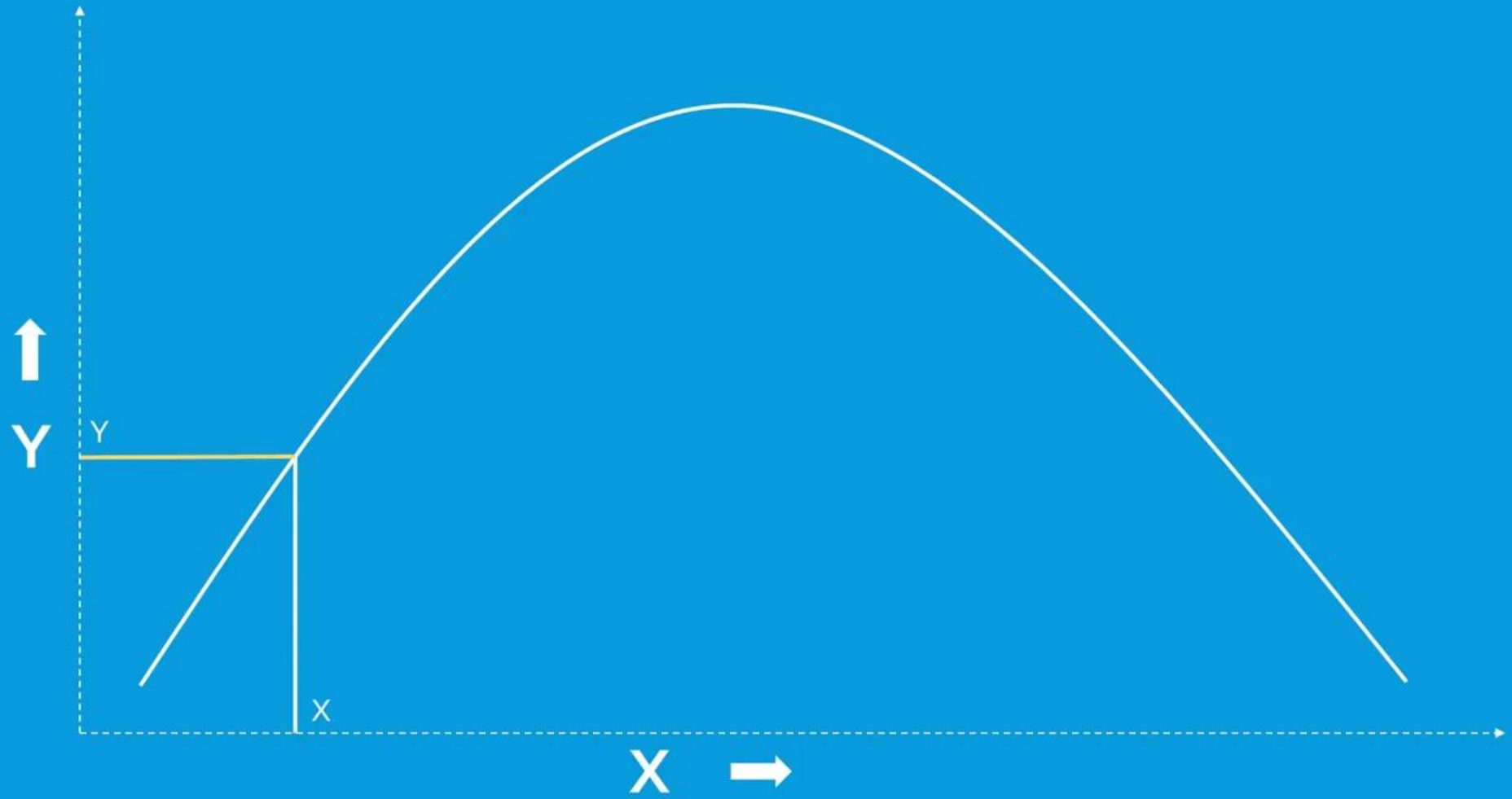


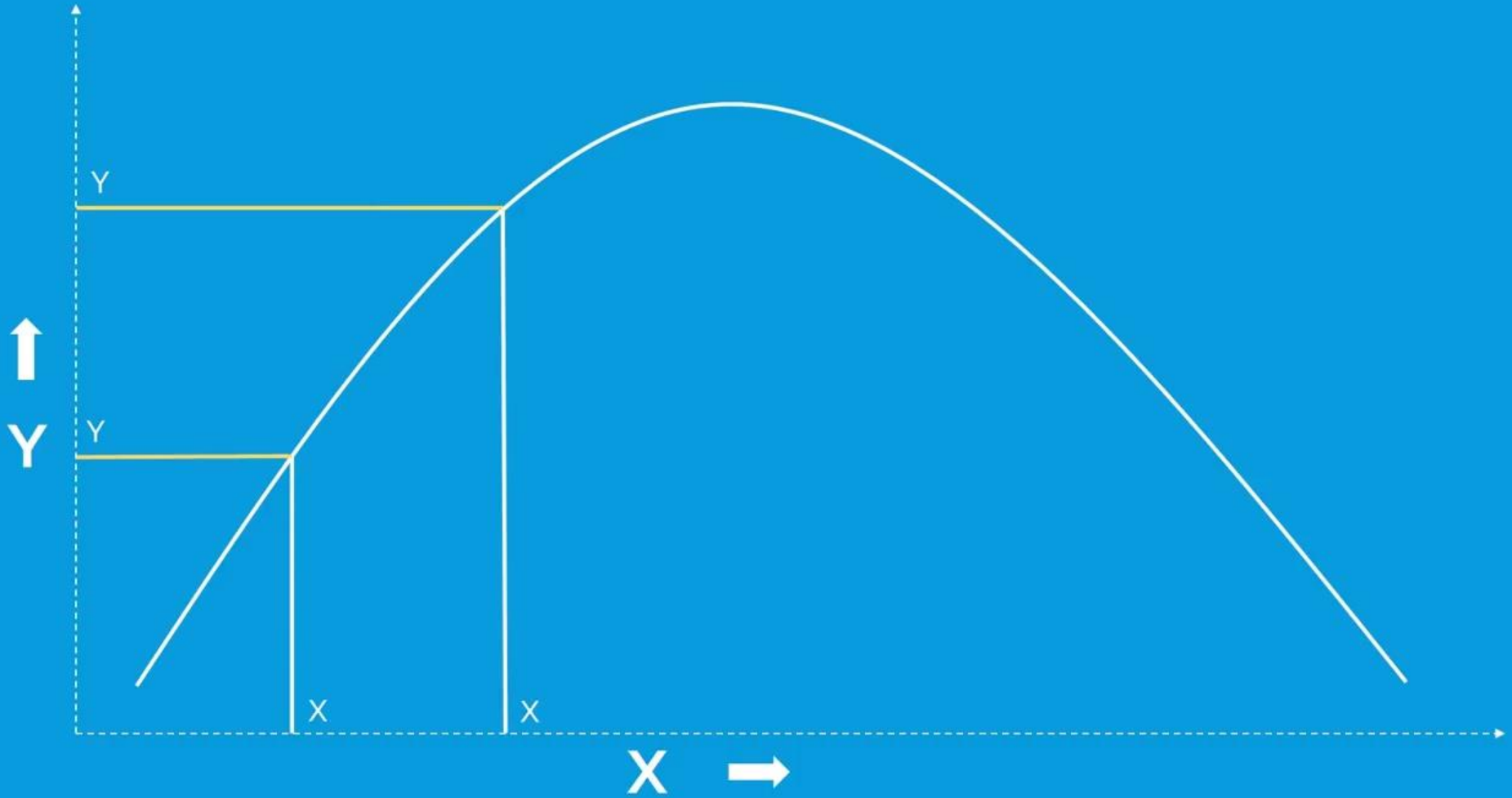
MINIMIZE

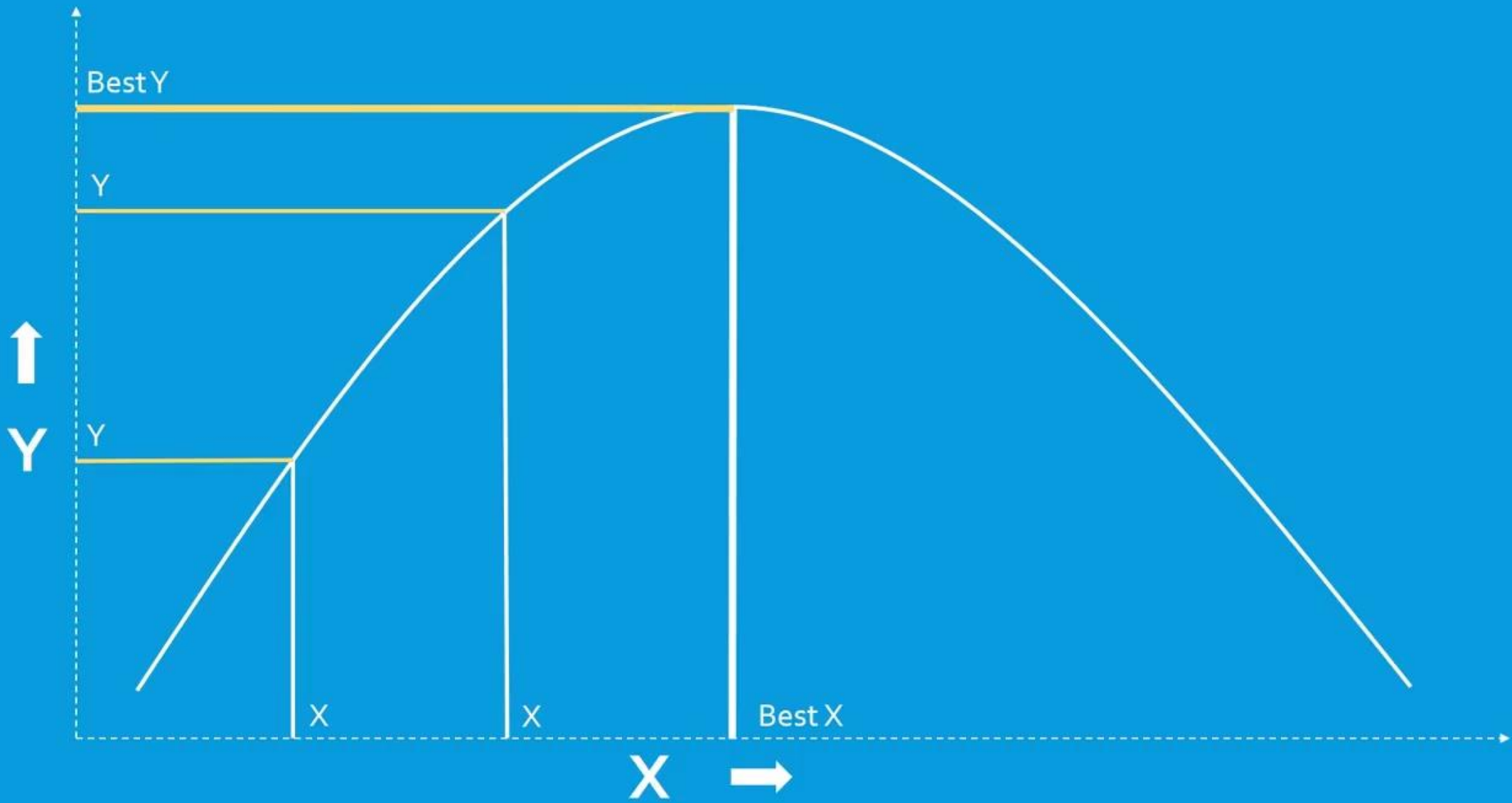






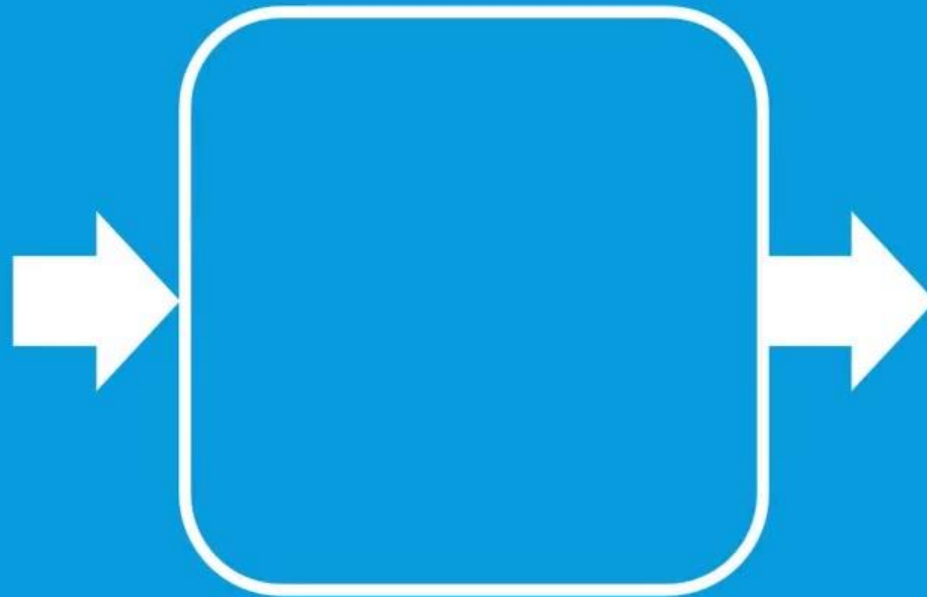






OPTIMIZATION ALGORITHM

Warehouse Placement



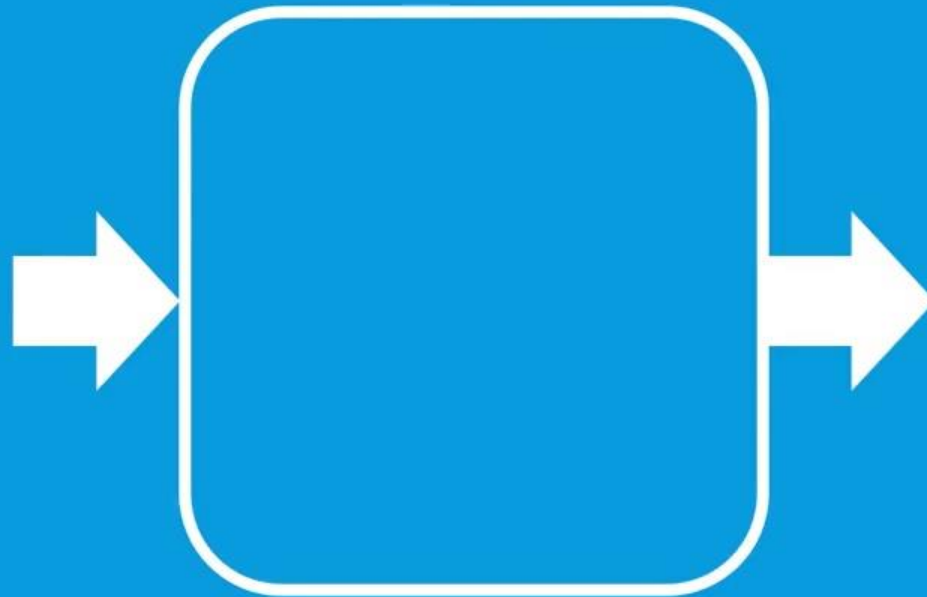
Warehouse Placement

Warehouse
Location



Minimize
Shipment
Time

Bridge Construction



Bridge Construction

Design



Maximize
Load
Bearing

Strategy Games



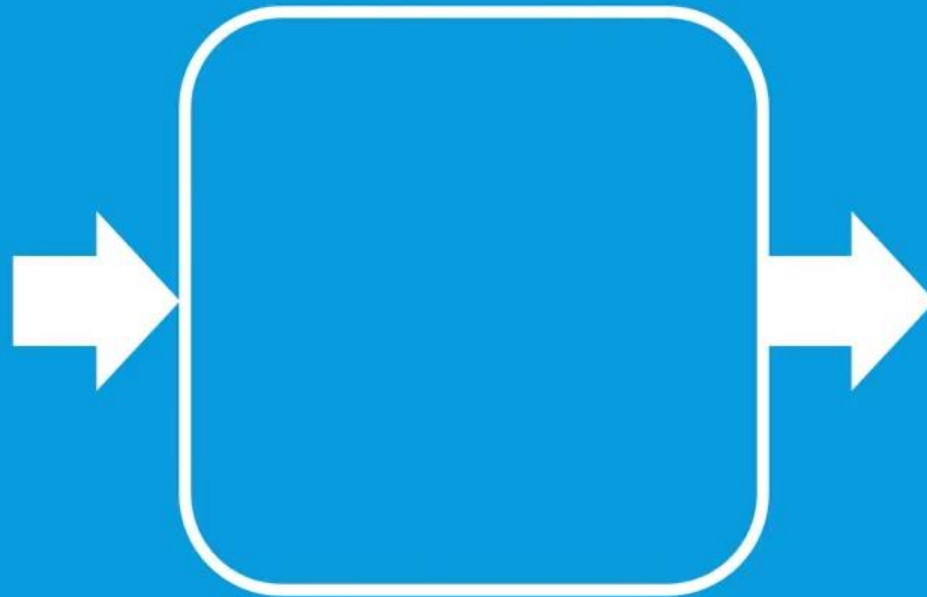
Strategy Games

Build
Order



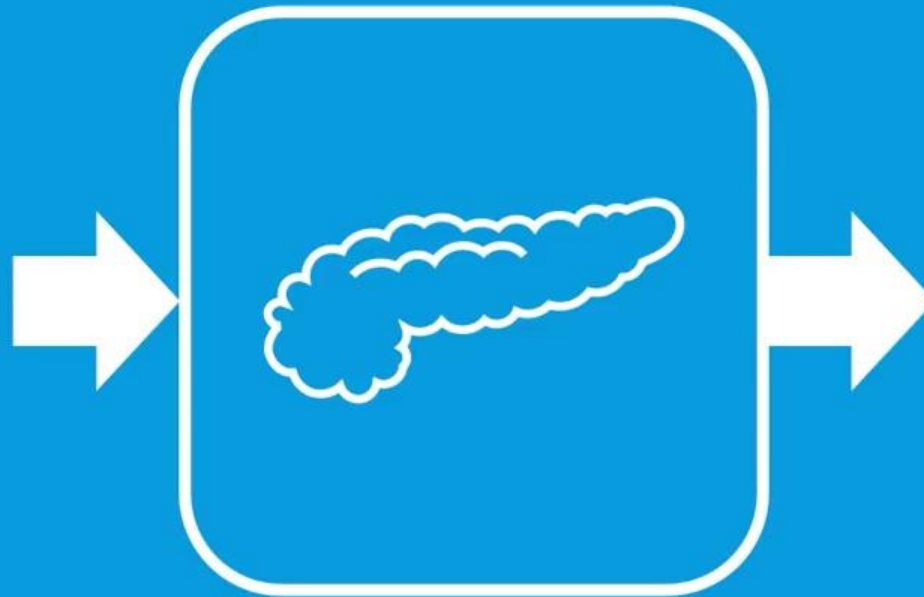
Maximize
Army
Strength

Artificial Pancreas



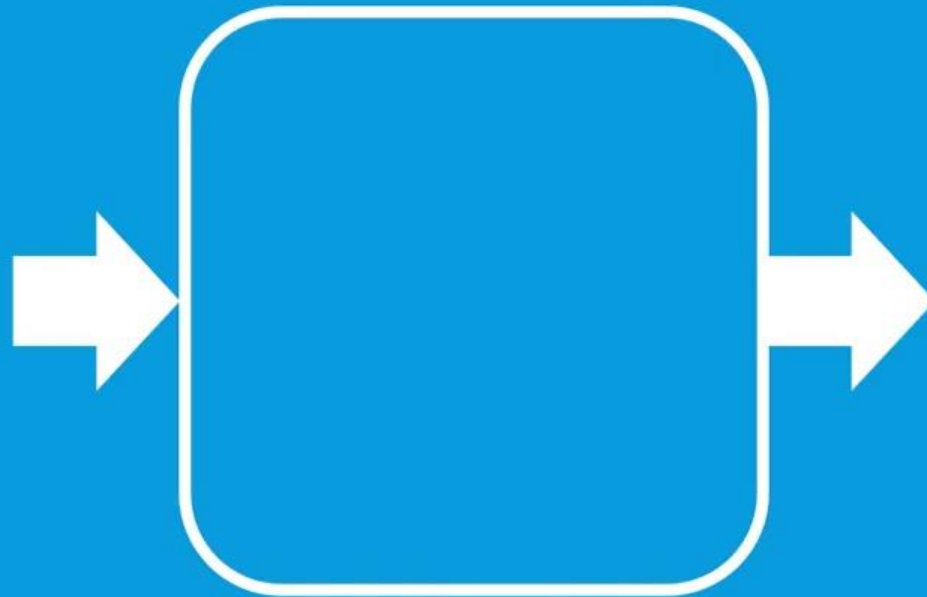
Artificial Pancreas

Insulin
Delivery



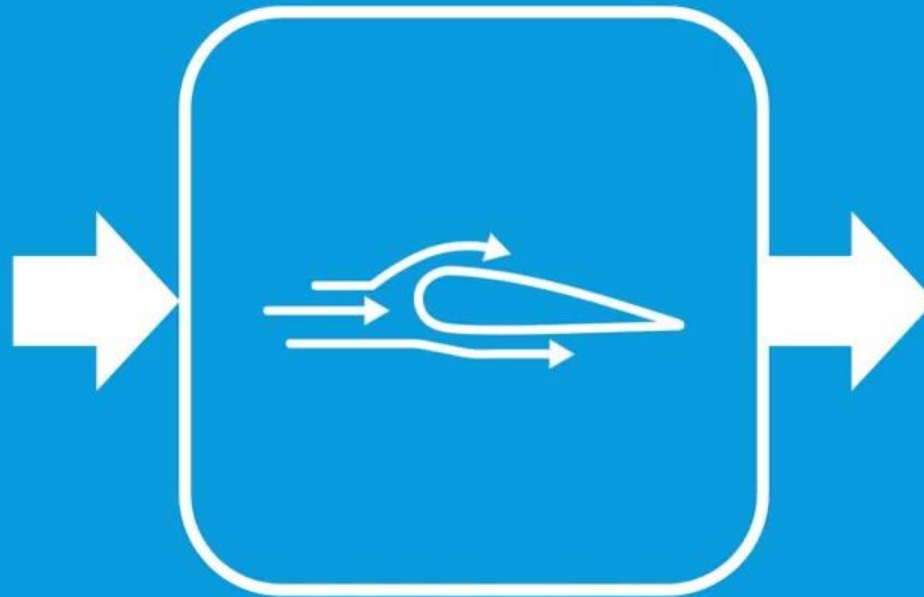
Minimize
Blood
Sugar
Deviations

Airplane Design



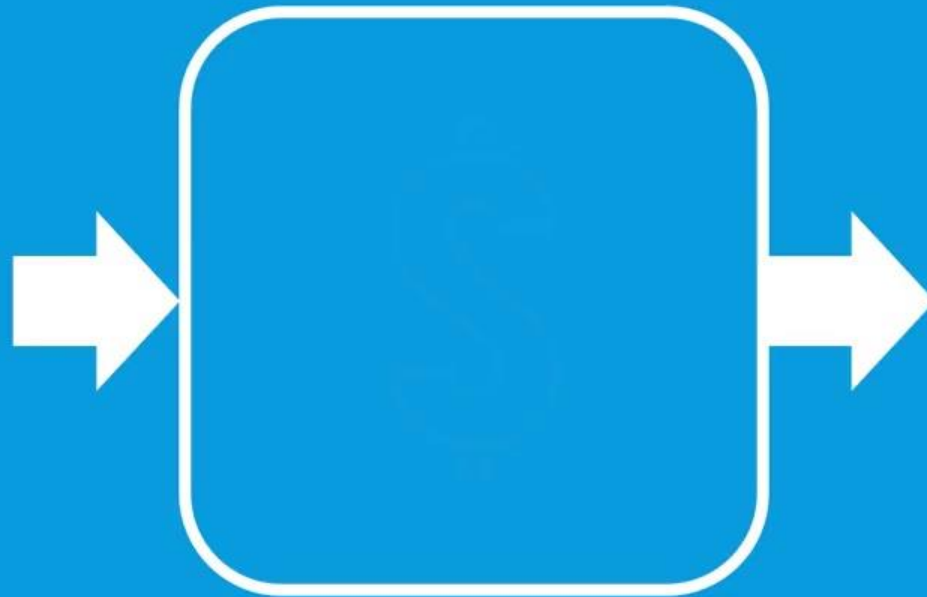
Airplane Design

Wing
Design



**Minimize
Weight**

Stock Market



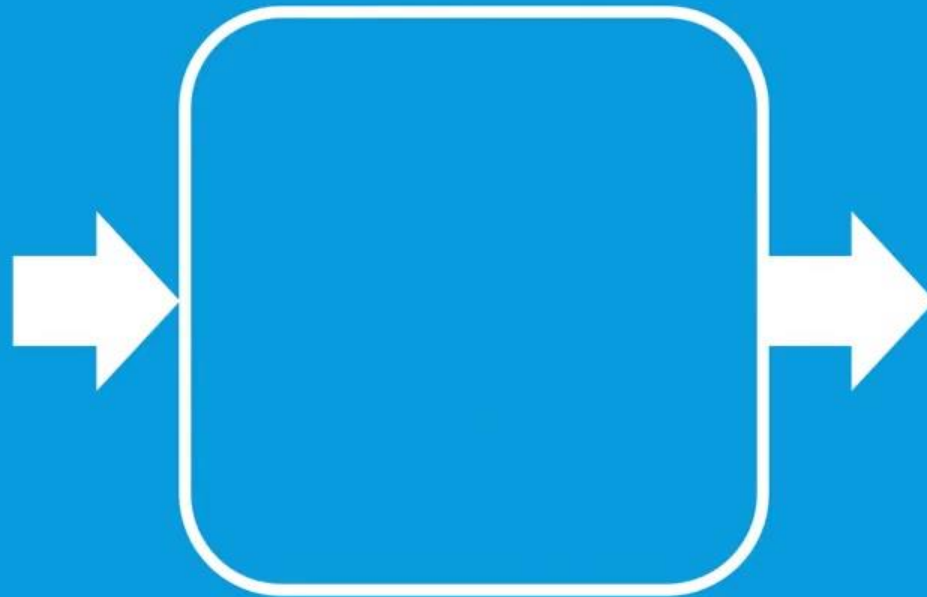
Stock Market

Stock
Portfolio



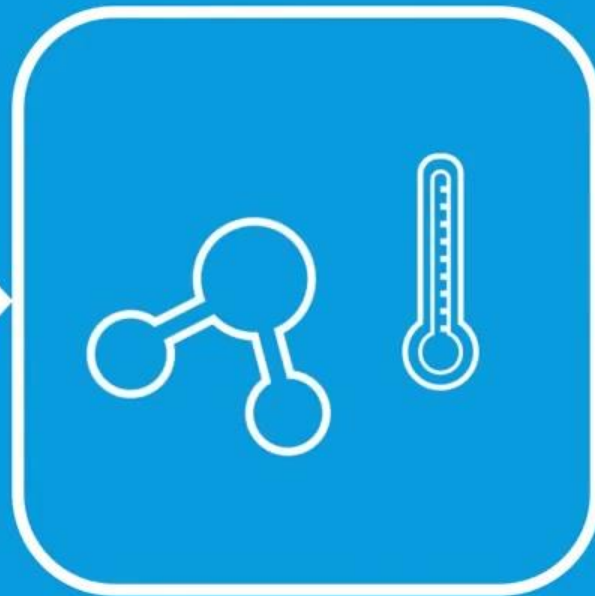
Maximize
Returns

Chemical Reactions



Chemical Reactions

Reactor
Temperature



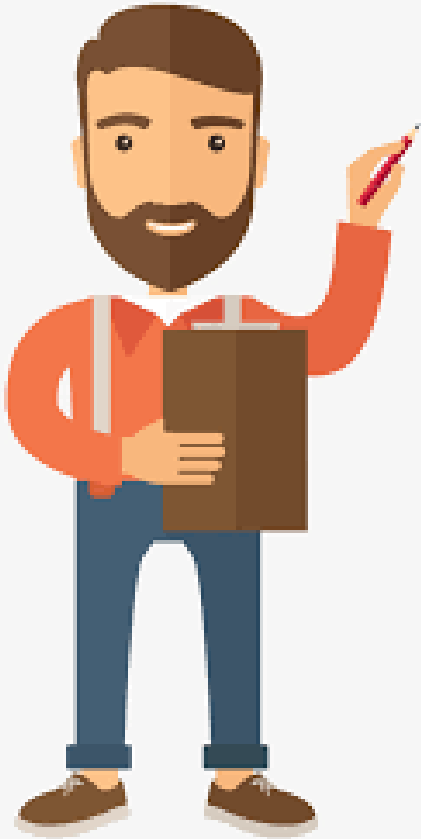
Maximize
Product
Purity



Optimization



SUMMARY



1.

Helps find the inputs that gives the best outputs

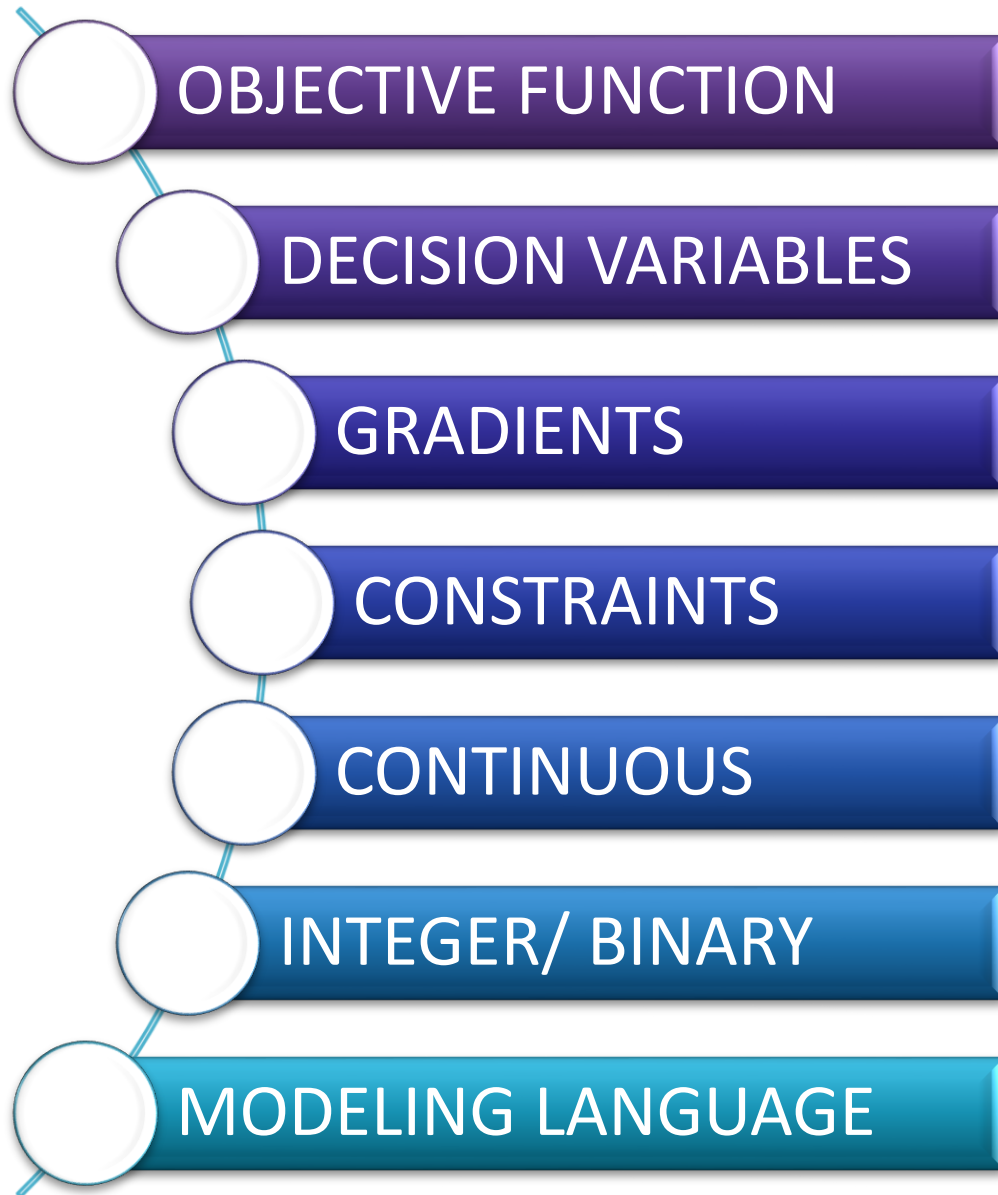
2.

Usually requires an optimization algorithm

3.

Applicable to many disciplines

**WORDS
WHICH
CAN
DESCRIBE
THE
IDEA
OF
OPTIMIZATION**



OBJECTIVE FUNCTION

**IS THE VALUE WE
ARE TRYING TO OPTIMIZE**

OBJECTIVE FUNCTION

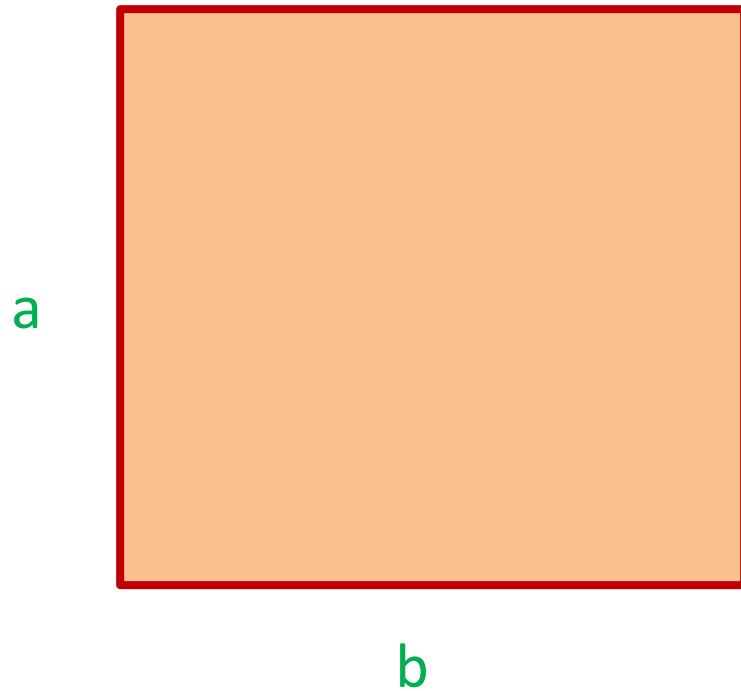


a

b

$$\text{AREA} = a \times b$$

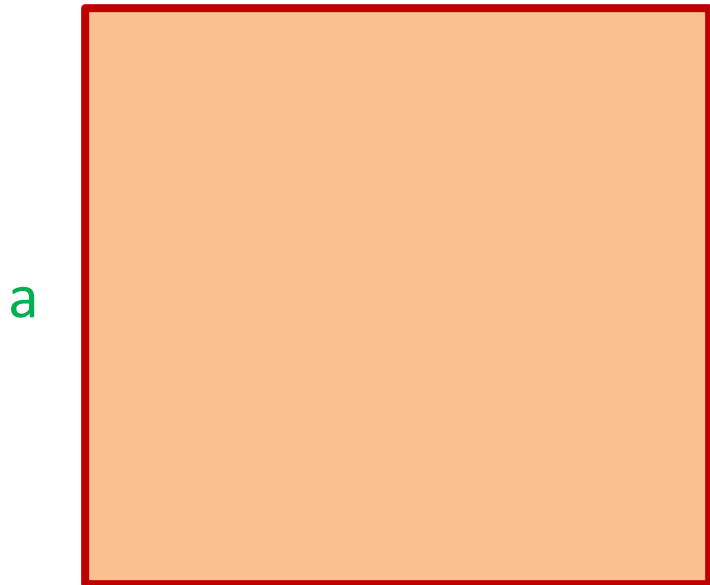
OBJECTIVE FUNCTION



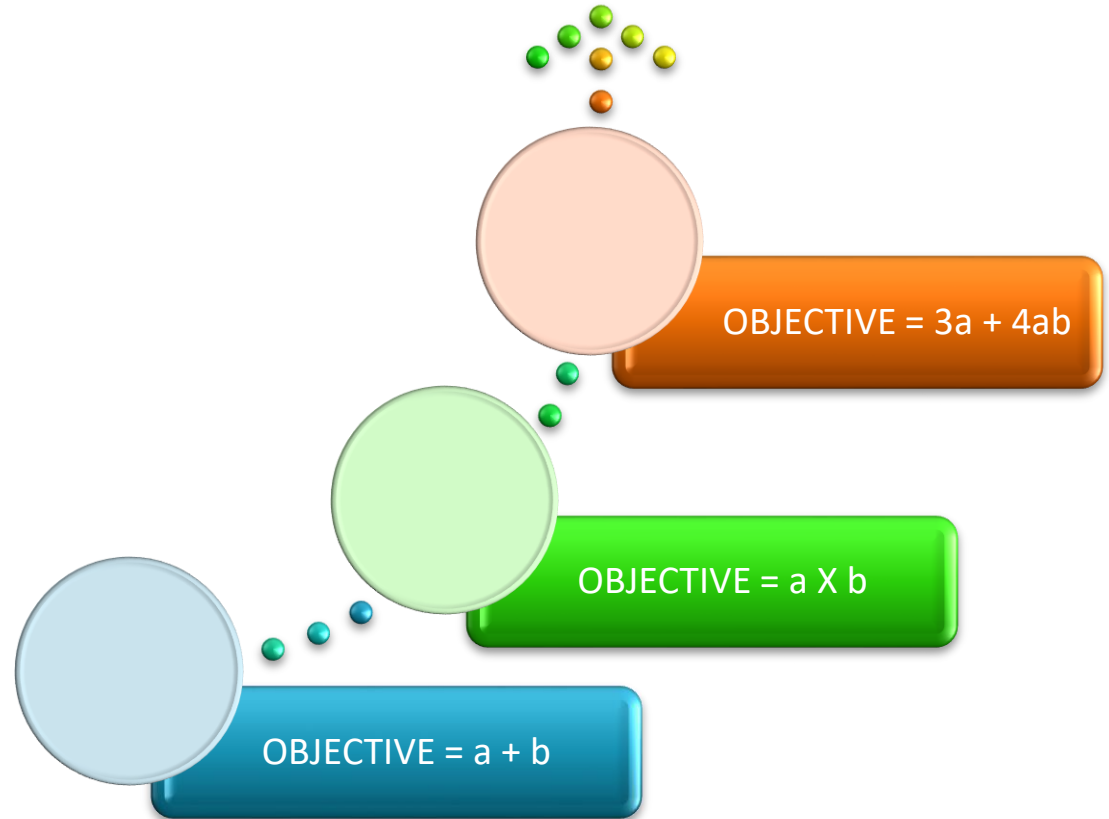
$$\text{AREA} = a \times b$$

OBJECTIVE FUNCTION

OBJECTIVES CAN BE.....



b



OBJECTIVE FUNCTION



Minimize $f(x)$

x

OBJECTIVE FUNCTION



COST



SPEED



WEIGHT



PROFIT



WASTE

DECISION VARIABLES

ARE THE VALUES

THE OPTIMIZER CAN CHANGE

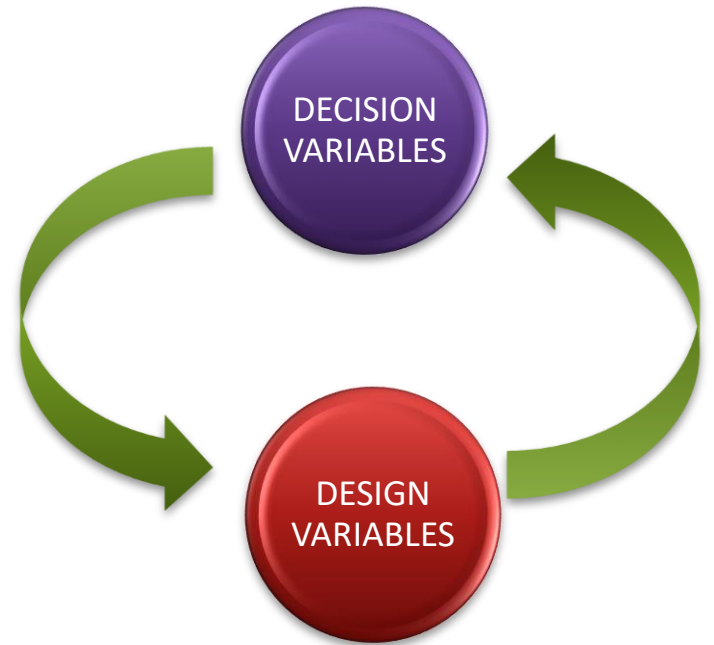
DECISION VARIABLES

$$\text{AREA} = a \times b$$

a



b



DECISION VARIABLES



Minimize $f(x)$

DECISION VARIABLES

Minimize $f(x_1, x_2, x_3, \dots)$

SUMMARY



OBJECTIVE FUNCTION :

VALUE WHICH WE ARE TRYING TO OPTIMIZE

EITHER MINIMIZED OR MAXIMIZED

DECISION VARIABLES :

THE VALUES THAT OPTIMIZER CAN CHANGE

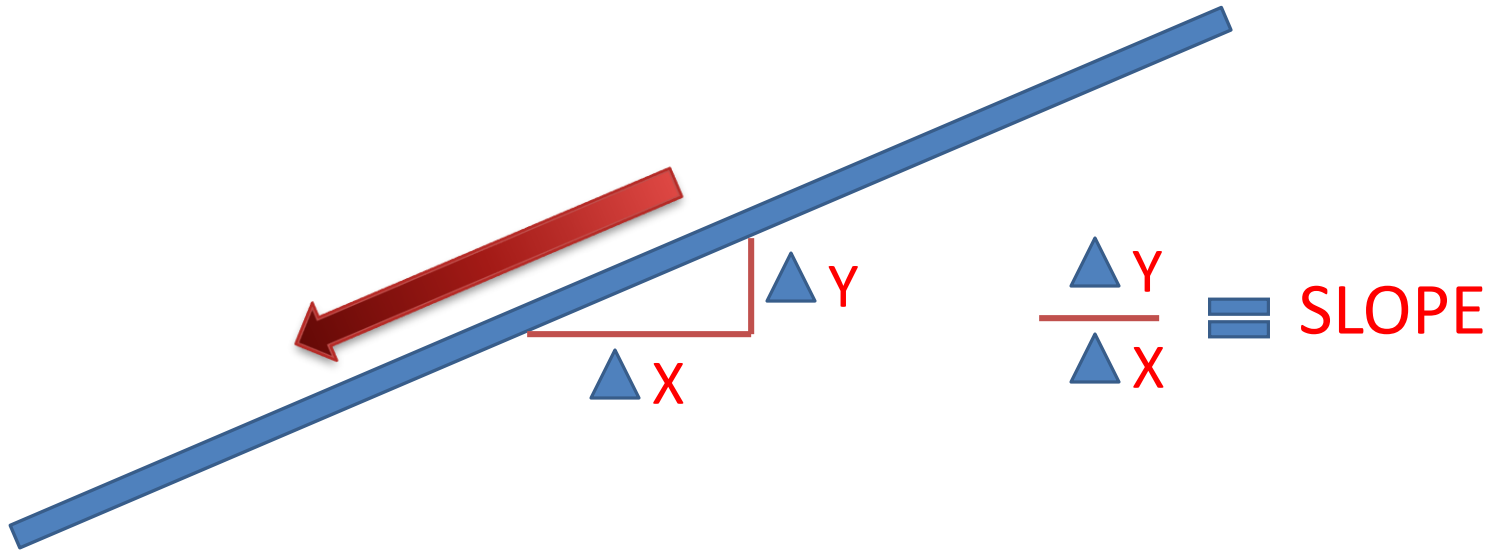
GRADIENTS

GRADIENTS

SLOPE OF THE FUNCTION

GRADIENTS

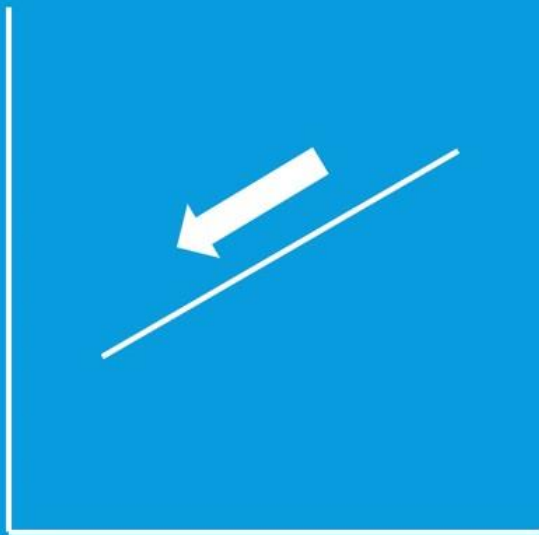
GRADIENTS



GRADIENTS

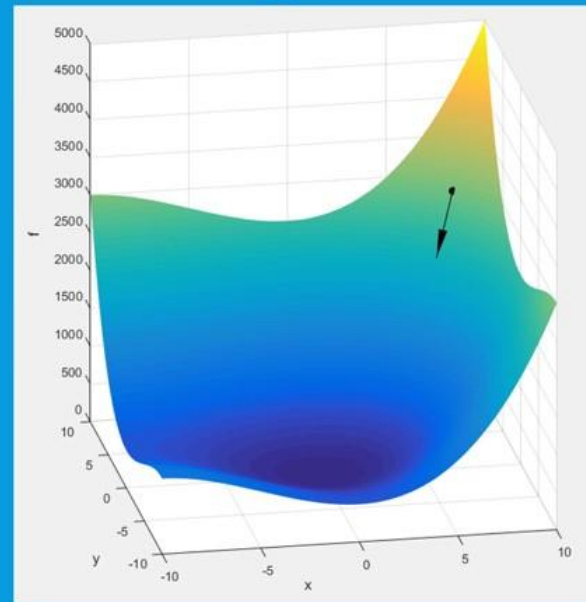
GRADIENTS

2D



Slope $\frac{df}{dx}$

3D



Gradient ∇f

GRADIENTS

GRADIENTS

NUMERICAL

ANALYTICAL

AUTOMATIC

DIFFERENTIATION

∇f

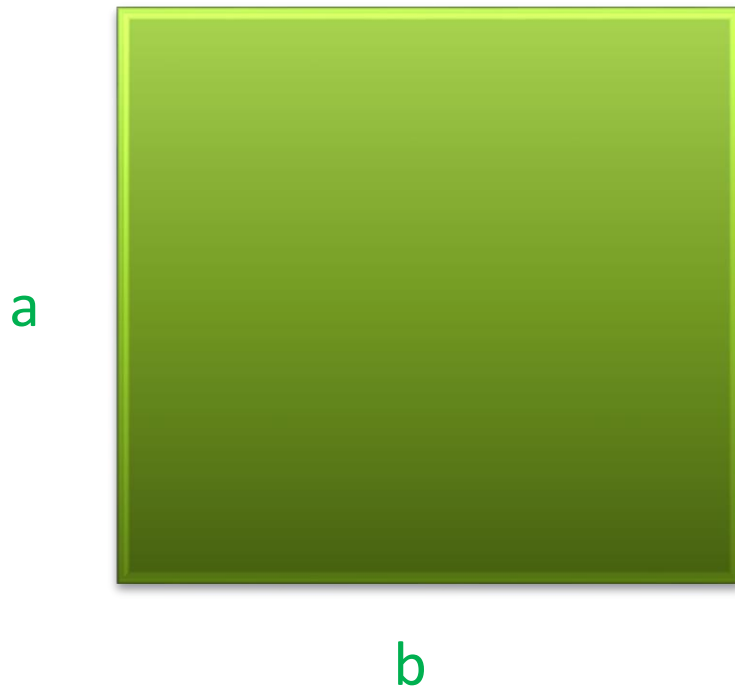
CONSTRAINTS

WHERE THE OPTIMIZER CANNOT GO



CONSTRAINTS

$$\text{AREA} = a \times b$$



INEQUALITY CONSTRAINT

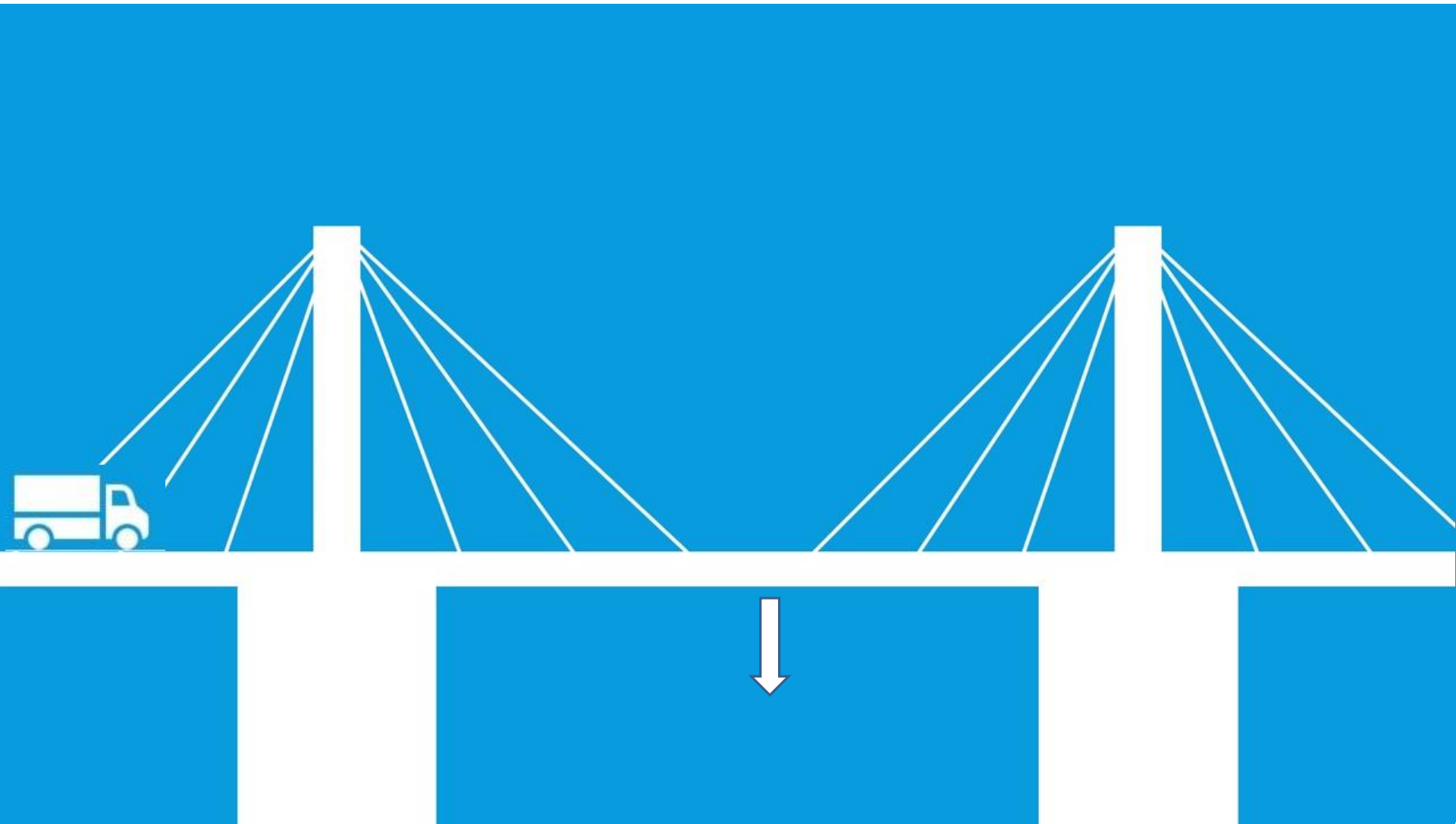
$$a \times b \leq 5$$

EQUALITY CONSTRAINT

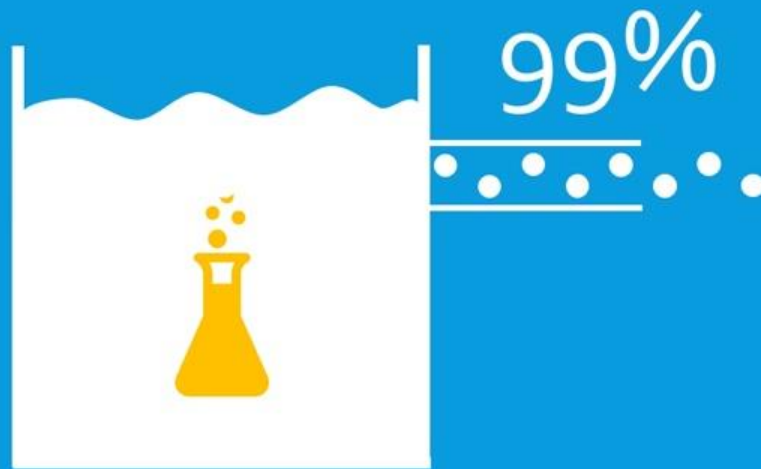
$$a + b = 5$$

$$\frac{ab}{a + b} = 3$$

CONSTRAINTS



CONSTRAINTS

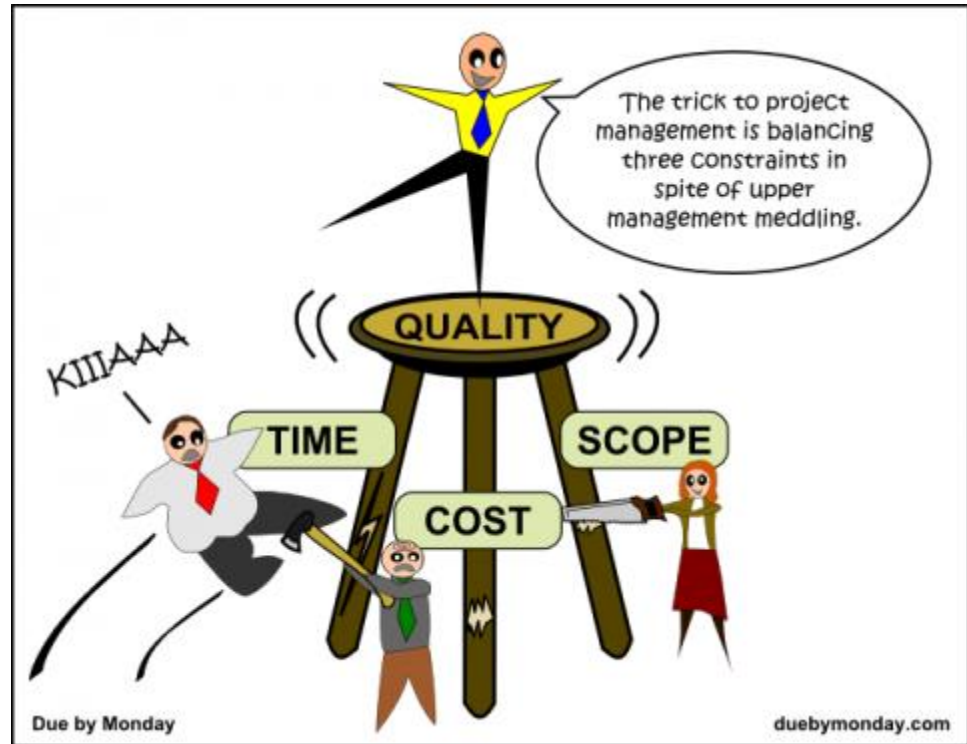


CONSTRAINTS



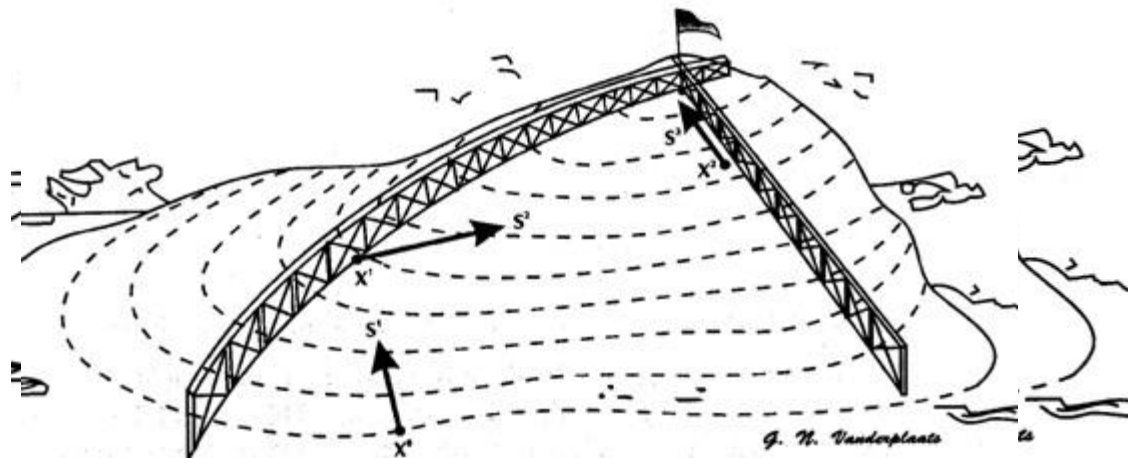
"There were some budget constraints on that one."

BUDGET CONSTRAINT



CONSTRAINTS

THE OPTIMIZATION PROCESS



CONTINUOUS VARIABLES



CONTINUOUS



DISCRETE



BINARY

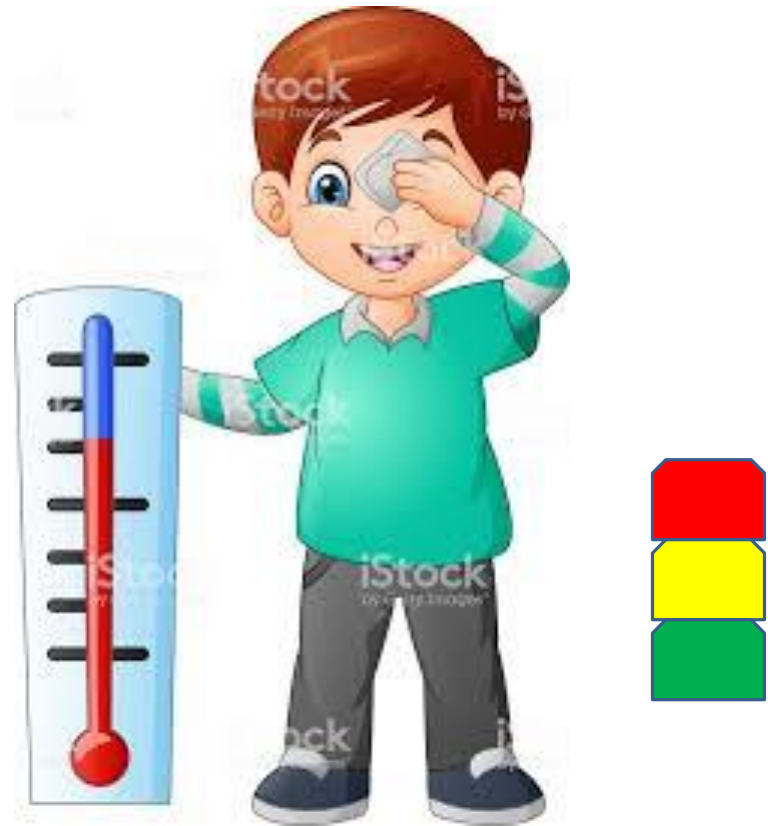
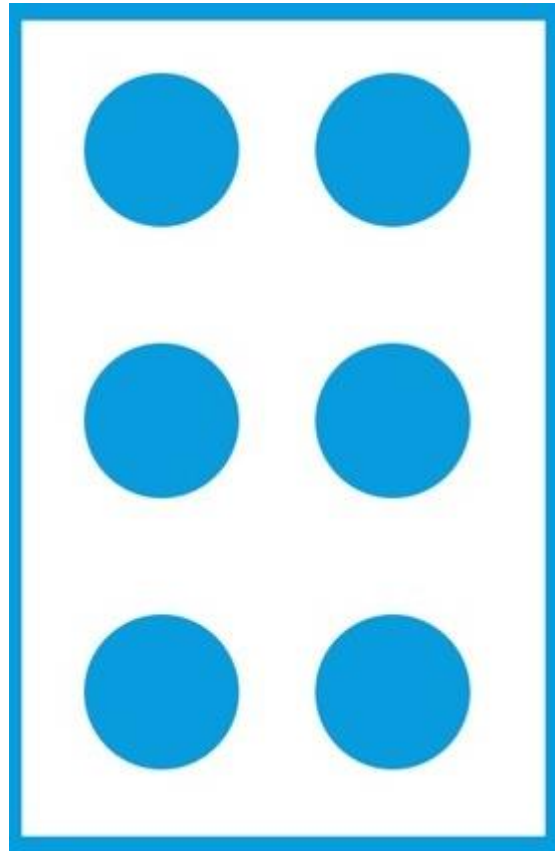
CONTINUOUS VARIABLES

20 KMPH



50 KMPH

DISCRETE VARIABLES



BINARY VARIABLES



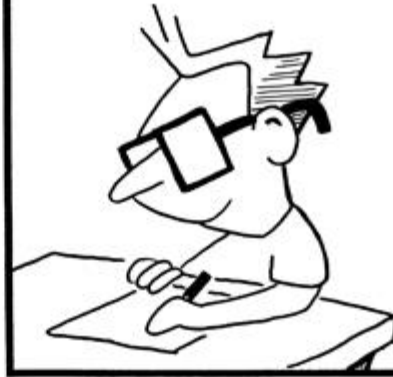
$$3+4=34$$



$$7+2=72$$

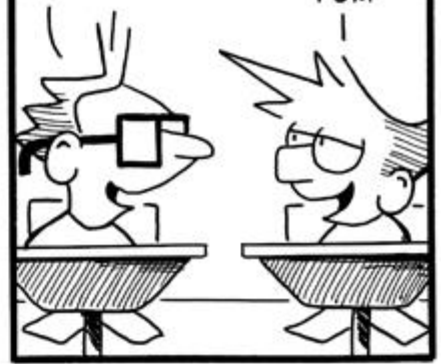


$$6+5=65$$



WOW, THANKS
FOR SHOWING ME
THIS SIMPLIFIED
METHOD OF
ADDITION.

WHAT ARE
FRIENDS
FOR.



OBTAINING DERIVATIVES

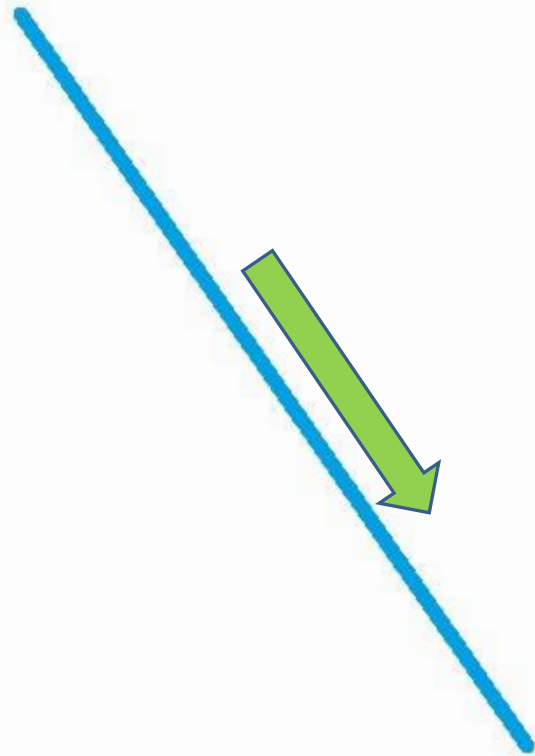
SYMBOLIC

NUMERICAL

AUTOMATIC

DIFFERENTIATION

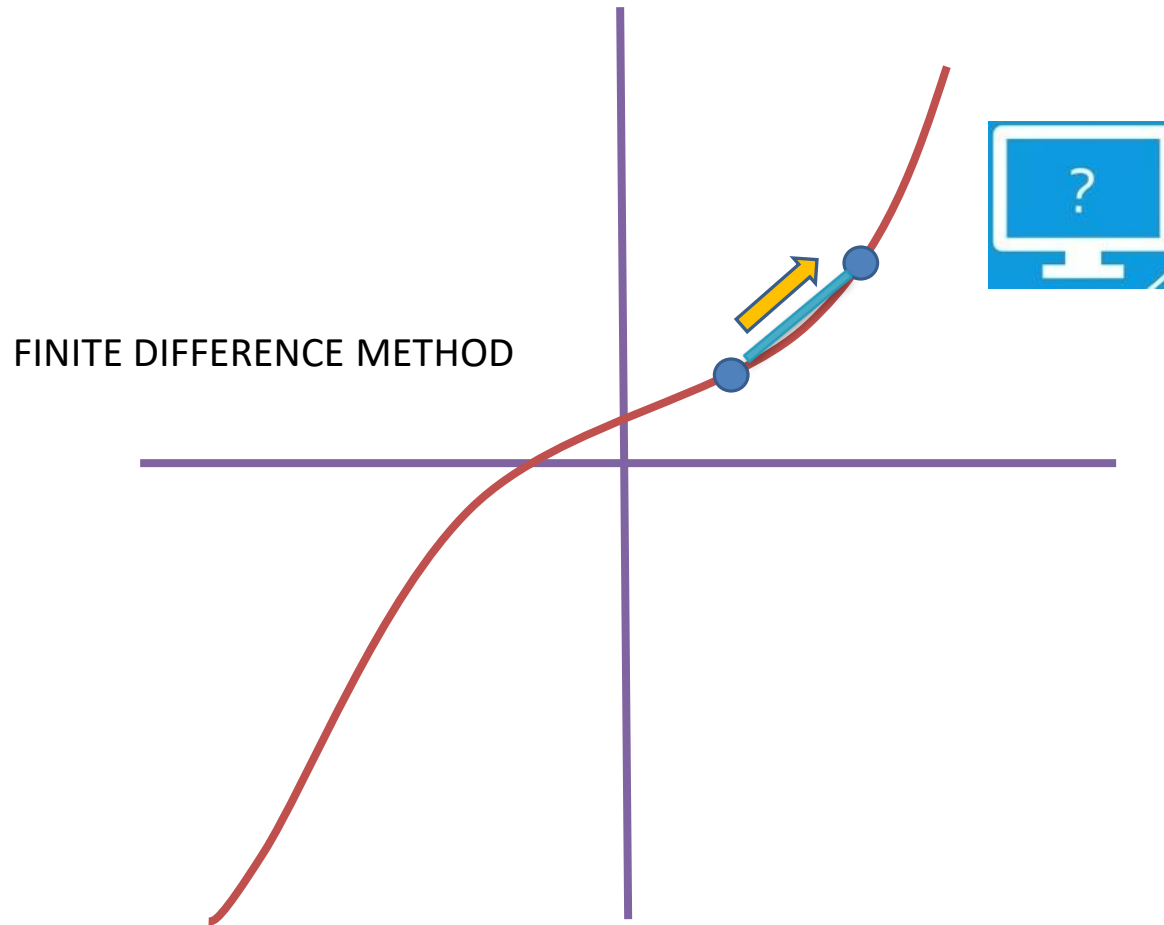
OBTAINING DERIVATIVES



SYMBOLIC DIFFERENTIATION

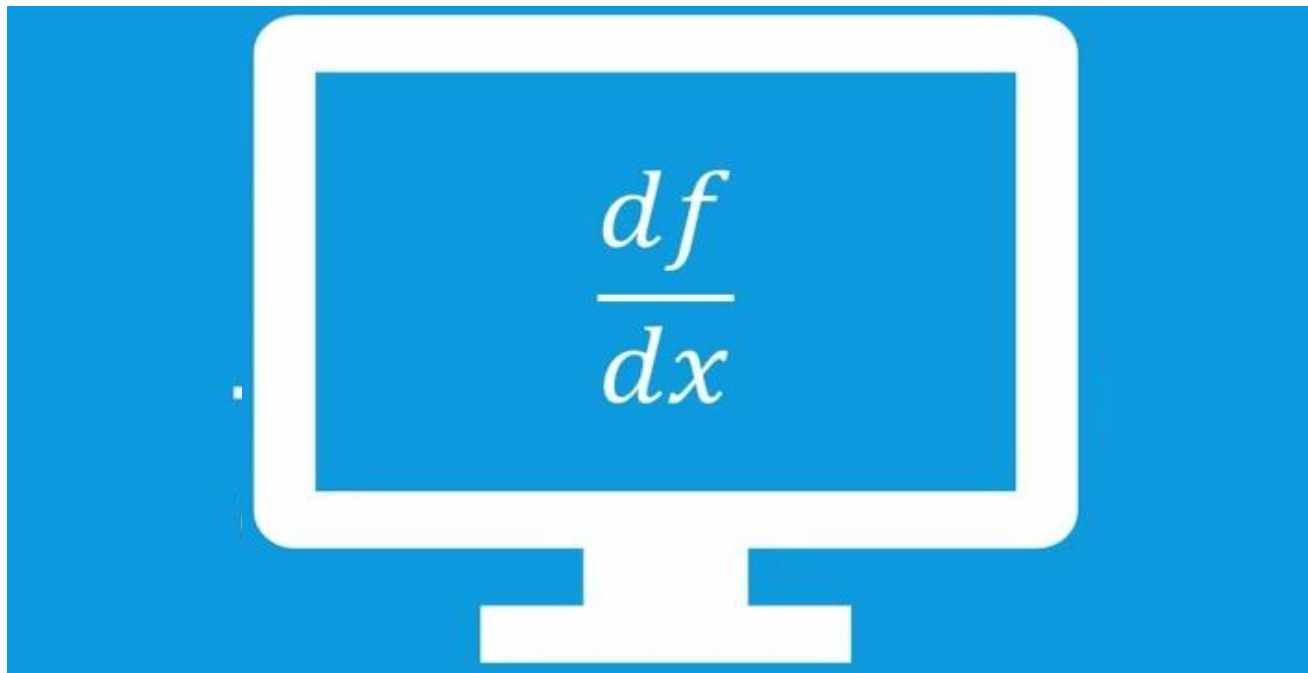
8.7015

NUMERICAL DIFFERENTIATION

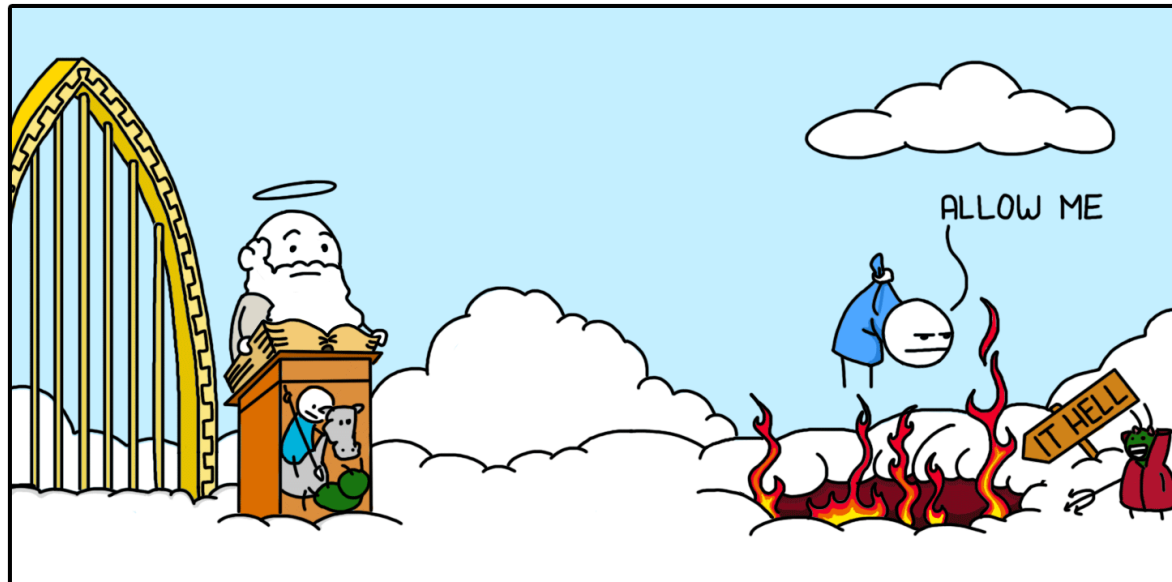
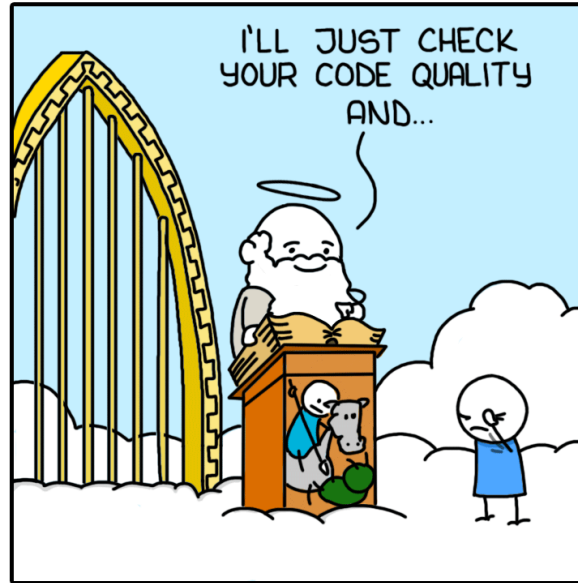
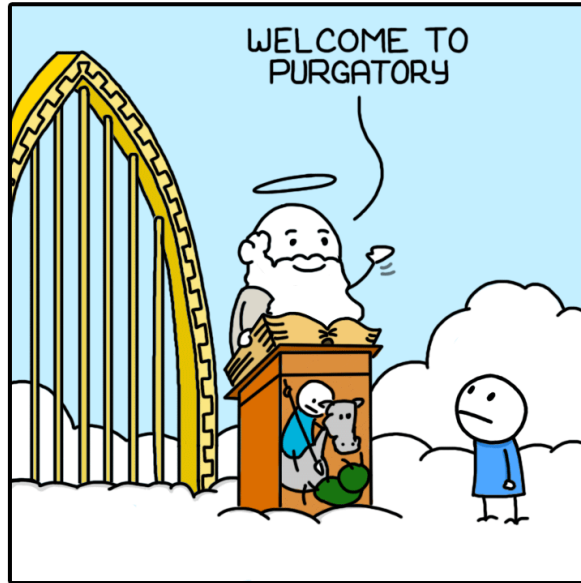


AUTOMATIC DIFFERENTIATION

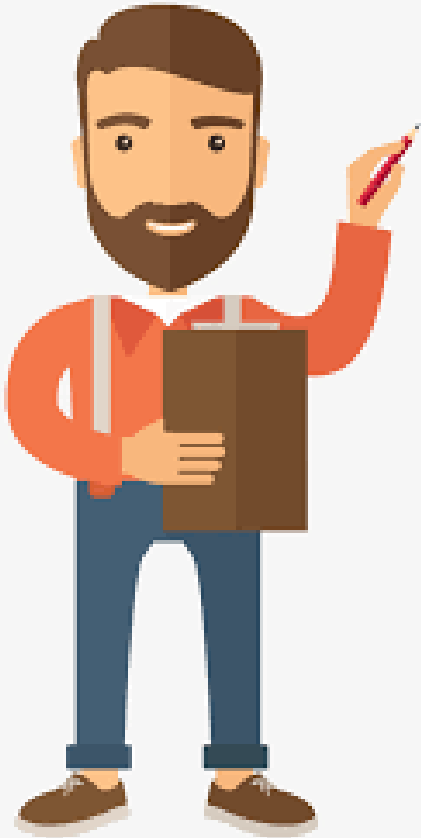
SIMILAR TO SYMBOLIC DIFFERENTIATION



LAST PUSH



SUMMARY



SYMBOLIC DIFFERENTIATION:

- PROBLEM INSIGHT
- SLOW

NUMERICAL DIFFERENTIATION:

- EASY IMPLEMENTATION
- INACCURATE

AUTOMATIC DIFFERENTIATION:

- ACCURATE
- MORE DIFFICULT TO IMPLEMENT

GRADIENT

**GRADIENT
BASED
ALGORITHMS**

**GRADIENT
FREE
ALGORITHMS**

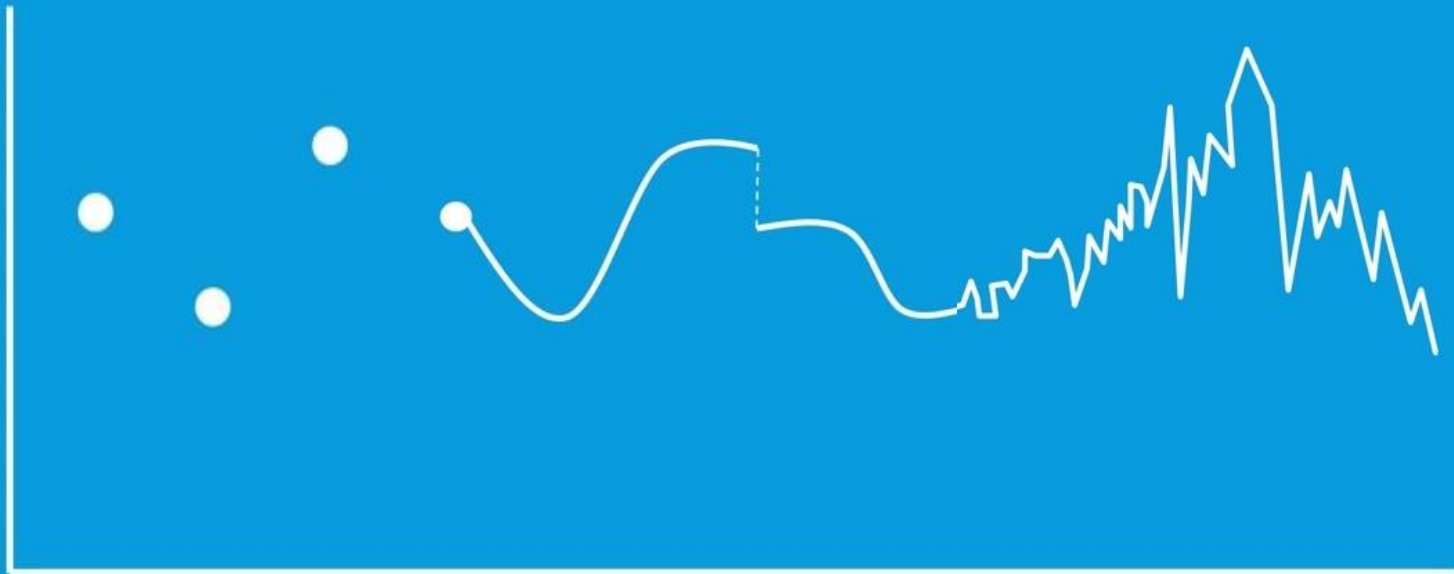
GRADIENT FREE ALGORITHM

NO DERIVATIVES NEEDED

$$\frac{df^n}{dx} \text{ or } f' \text{ or } \dot{f}$$

GRADIENT FREE ALGORITHM

~~$\frac{df}{dx}$~~



GRADIENT FREE ALGORITHM

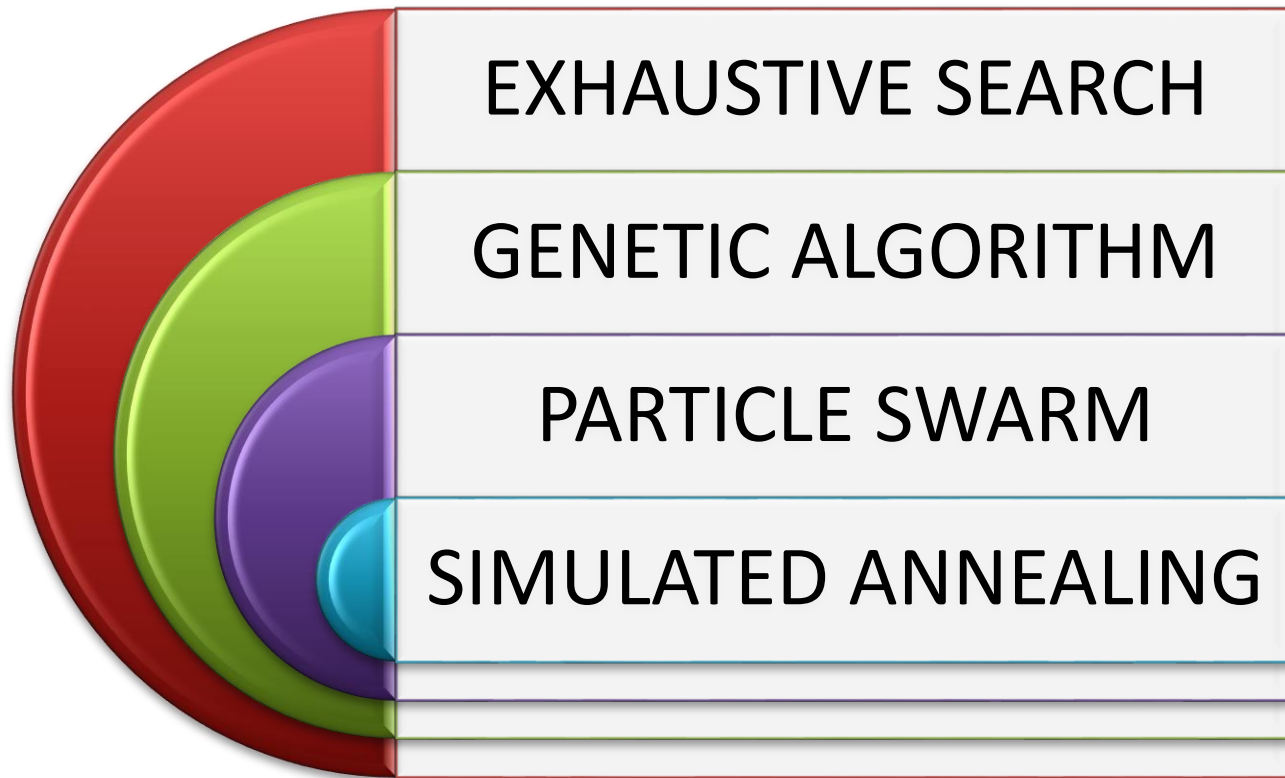


Gradient Free

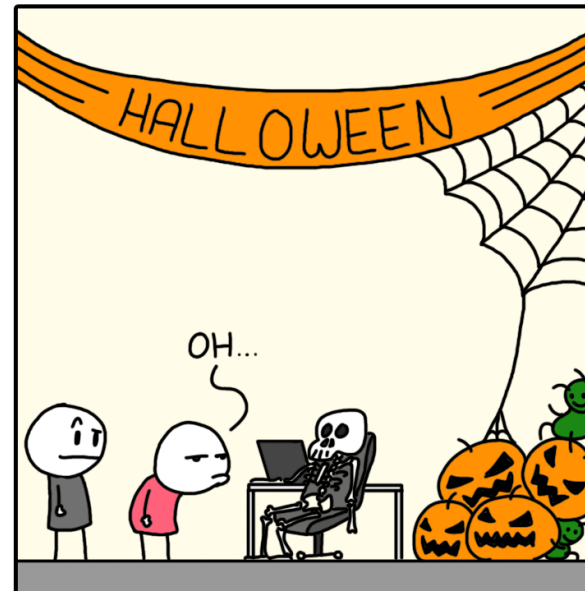
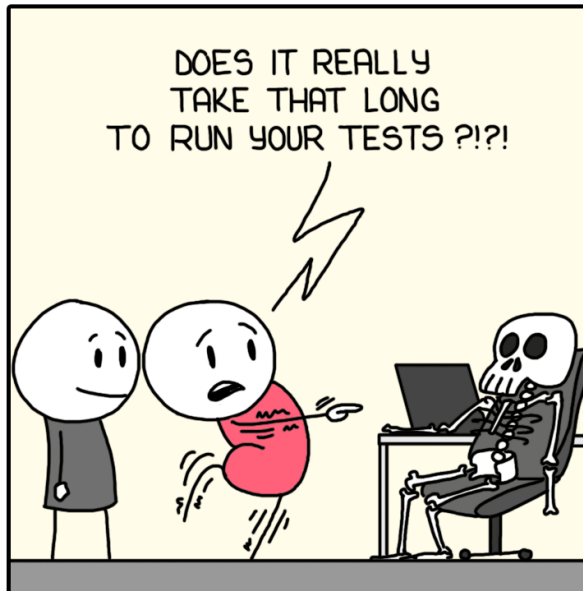
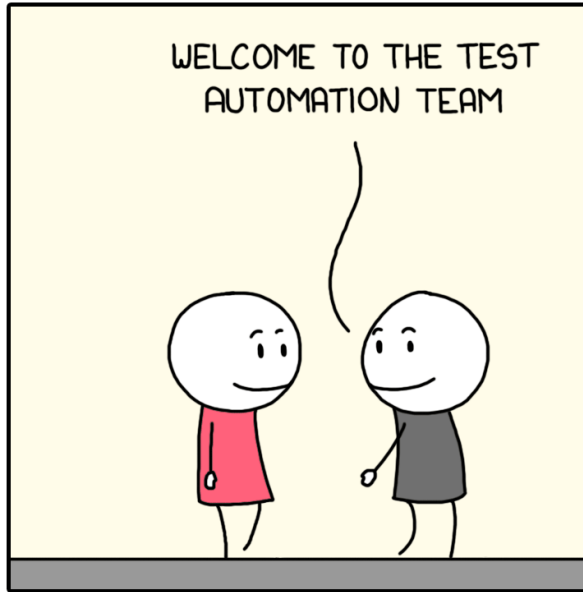


Gradient Based

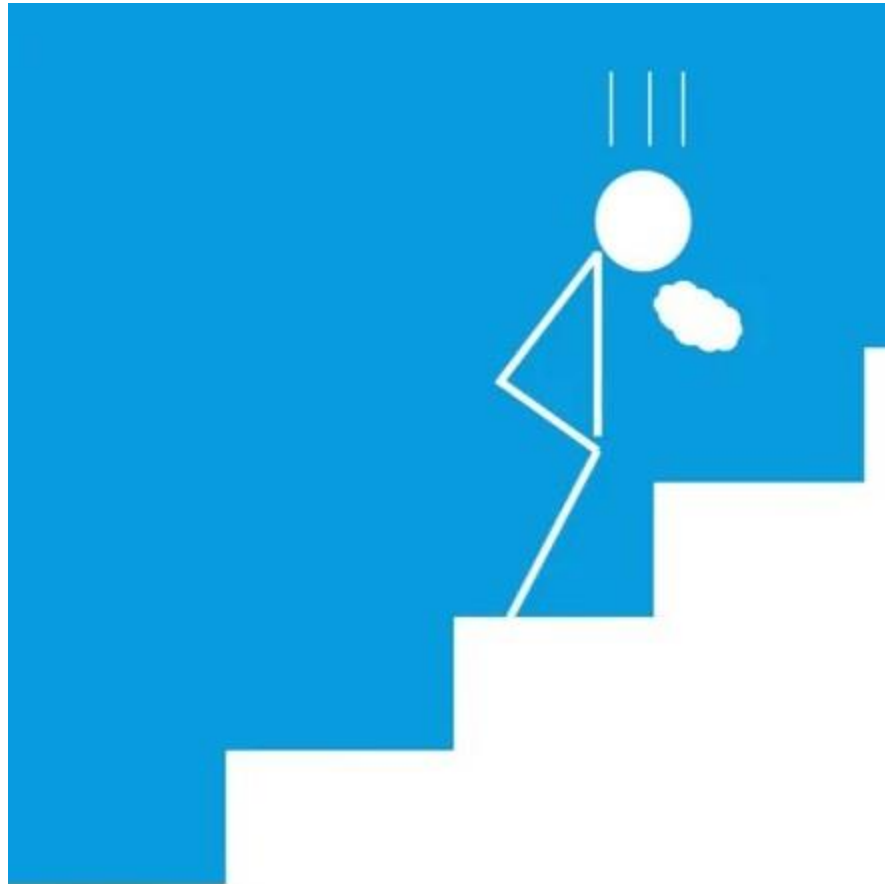
GRADIENT FREE ALGORITHM



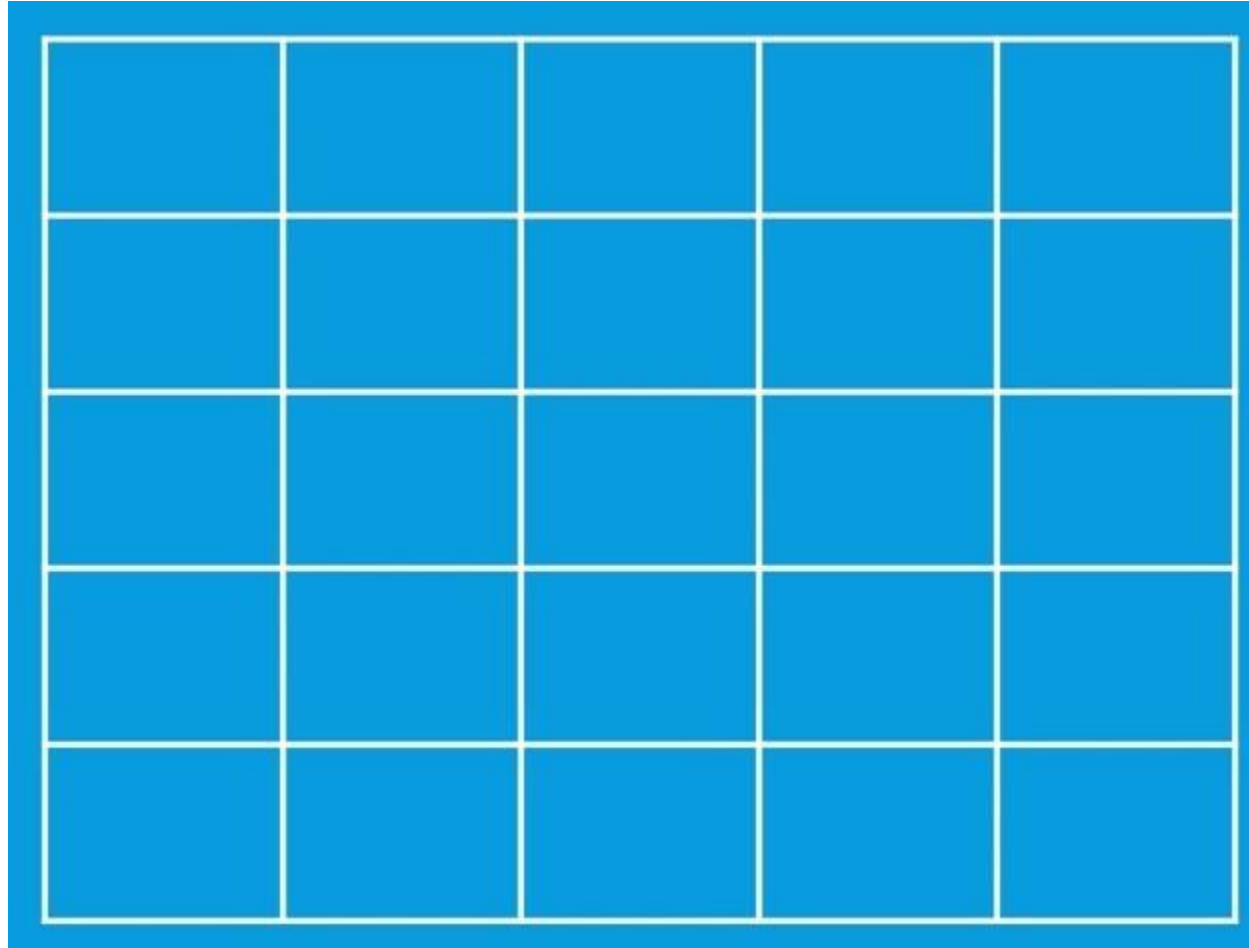
TESTS OPTIMIZATION



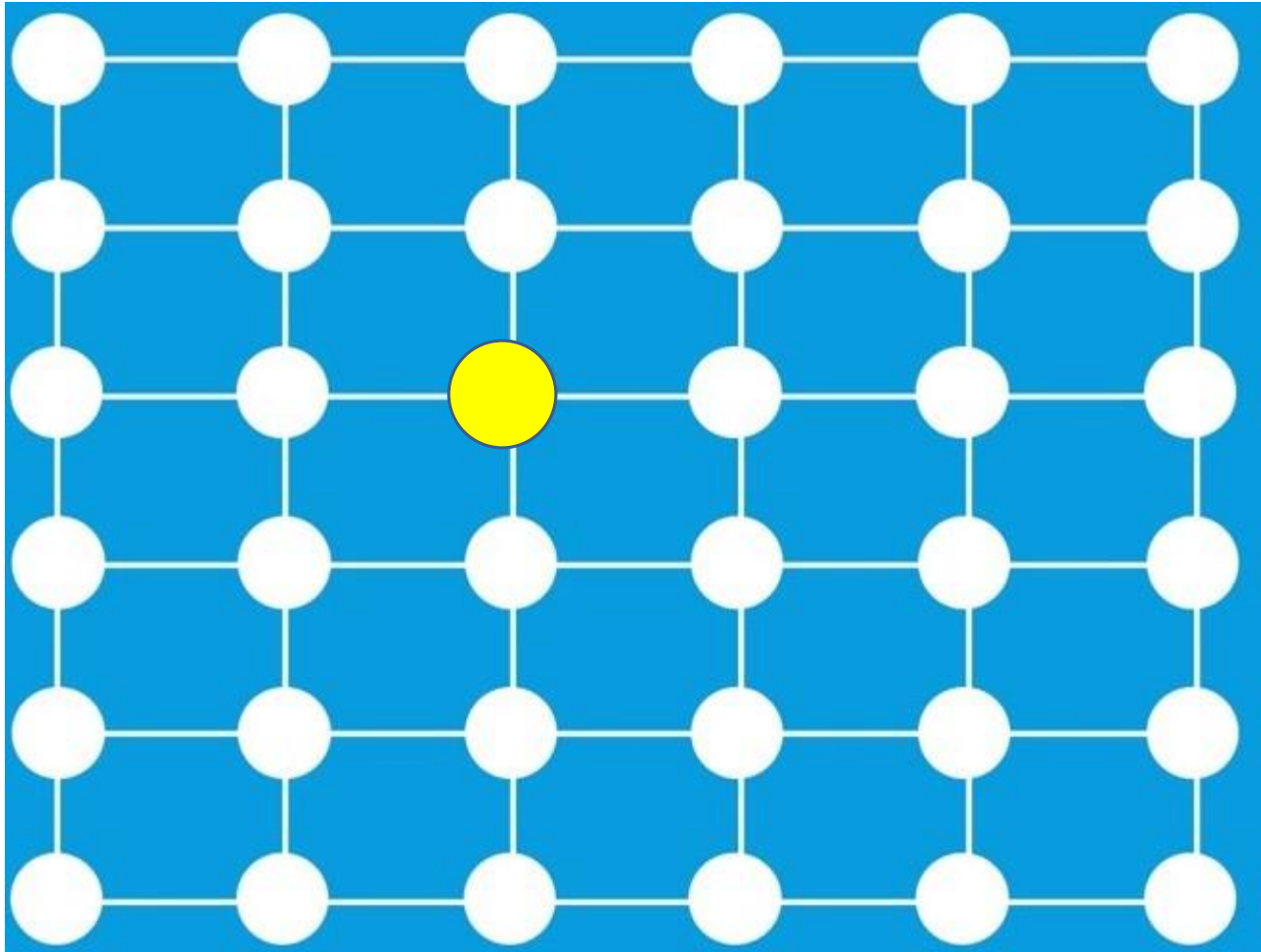
EXHAUSTIVE SEARCH ALGORITHM



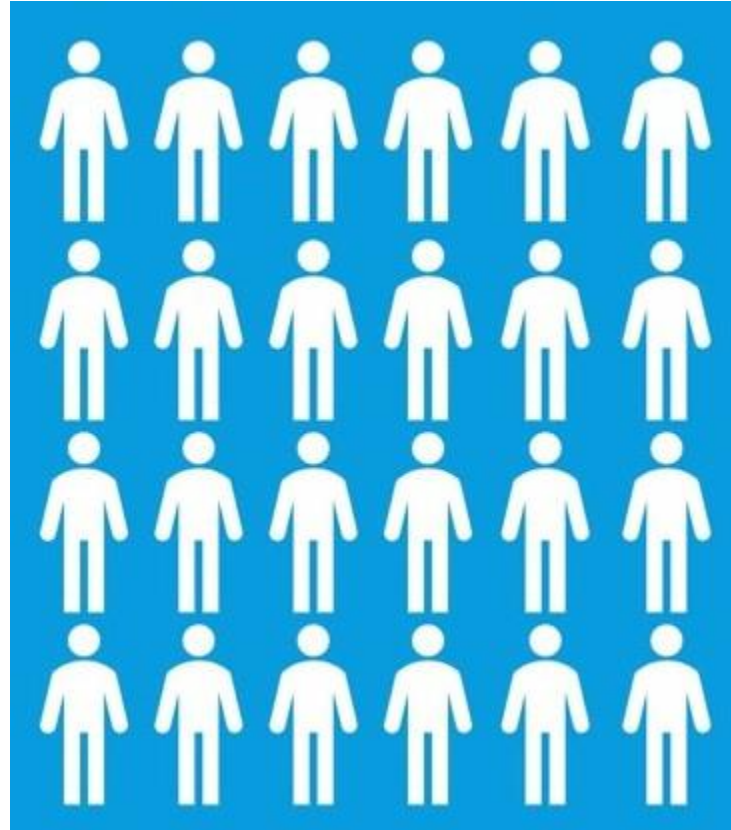
EXHAUSTIVE SEARCH ALGORITHM



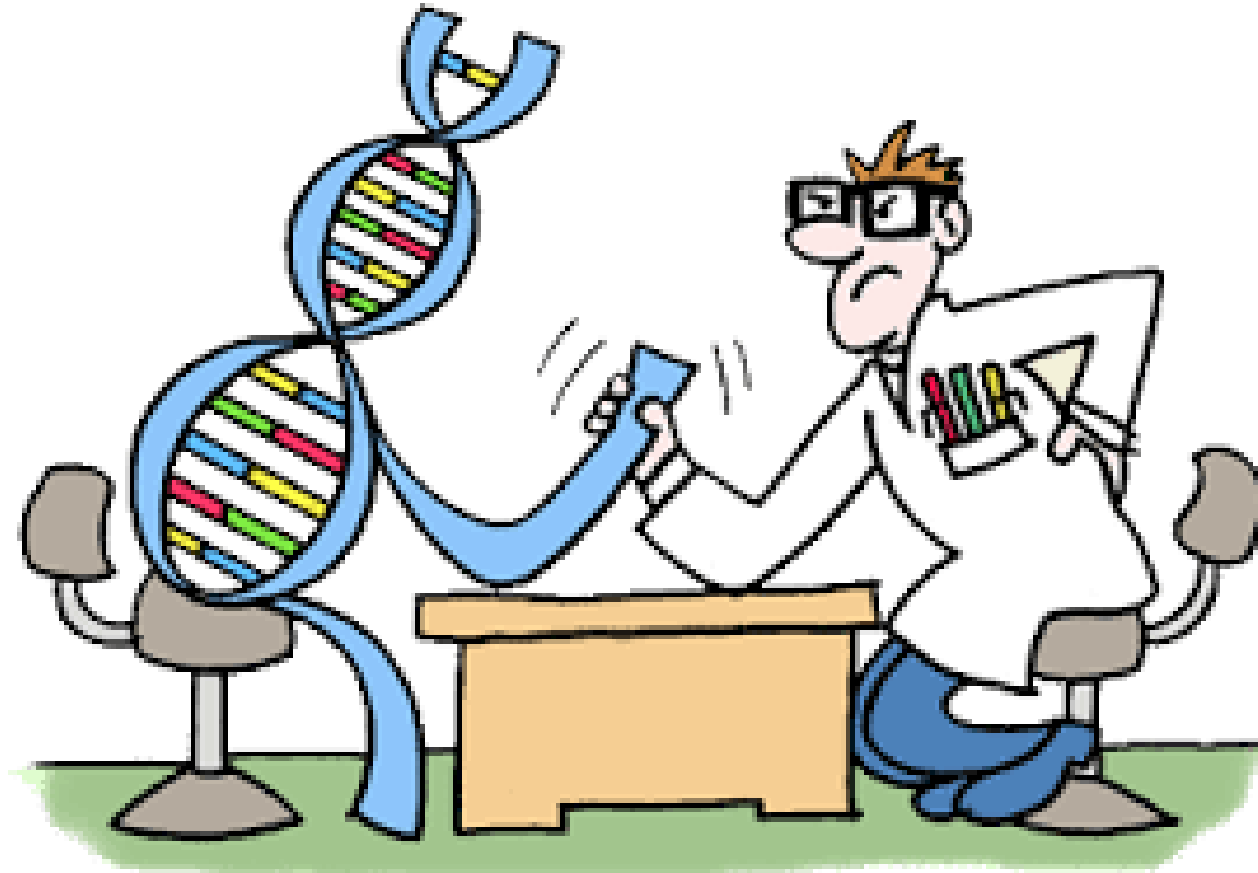
EXHAUSTIVE SEARCH ALGORITHM



GENETIC ALGORITHM



GENETIC ALGORITHM



WHY GA WORKS?

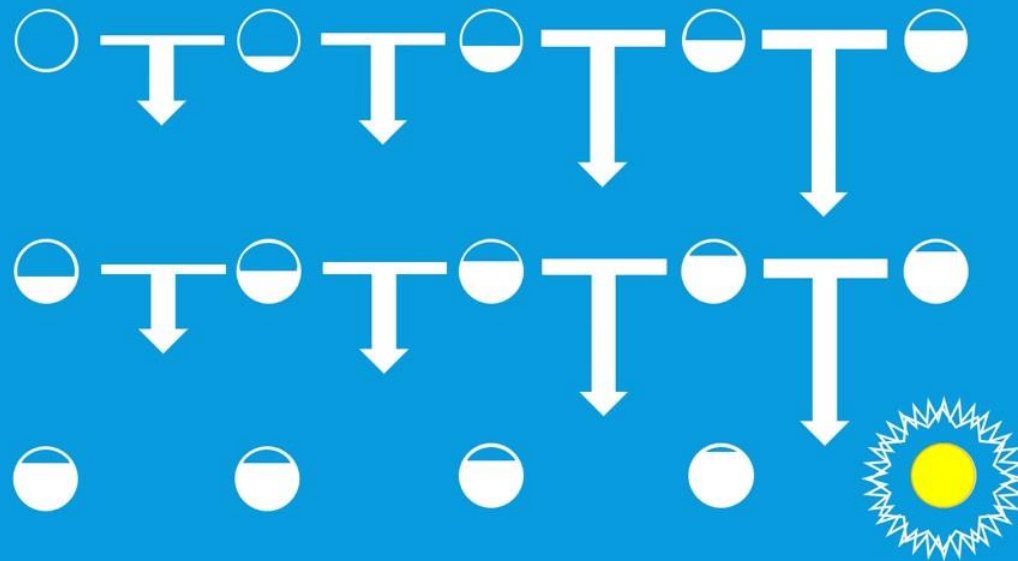
Mutation + Selection = Improvement!



Crossover + Selection = Innovation!

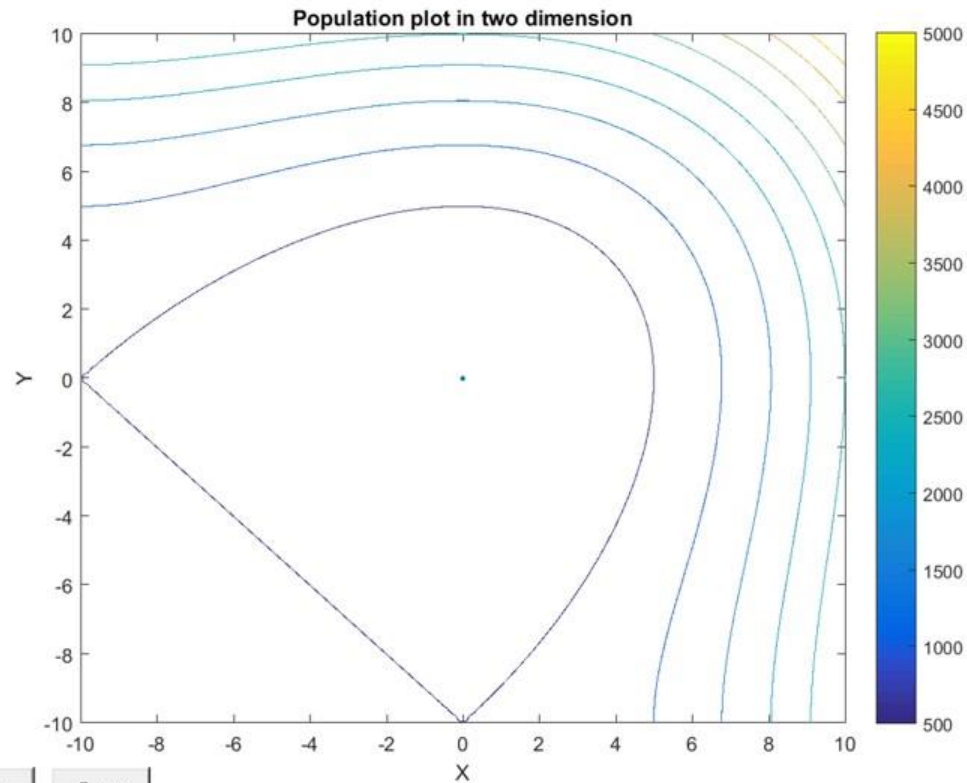


GENETIC ALGORITHM



GENETIC ALGORITHM

$$f(x, y) = x^3 + 15x^2 + y^3 + 15y^2$$

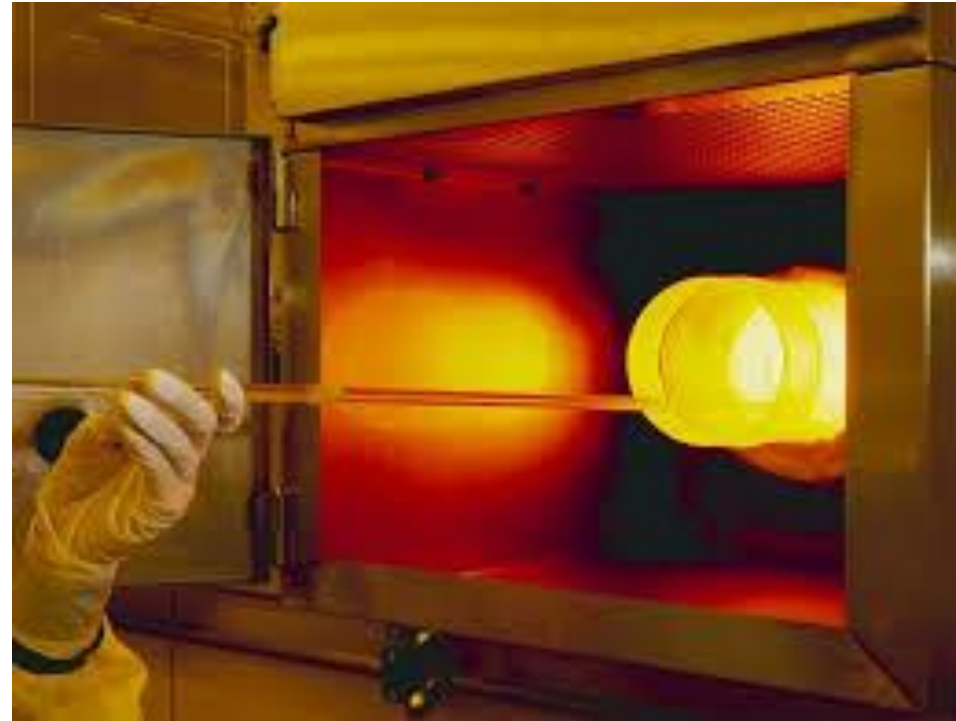


PARTICLE SWARM

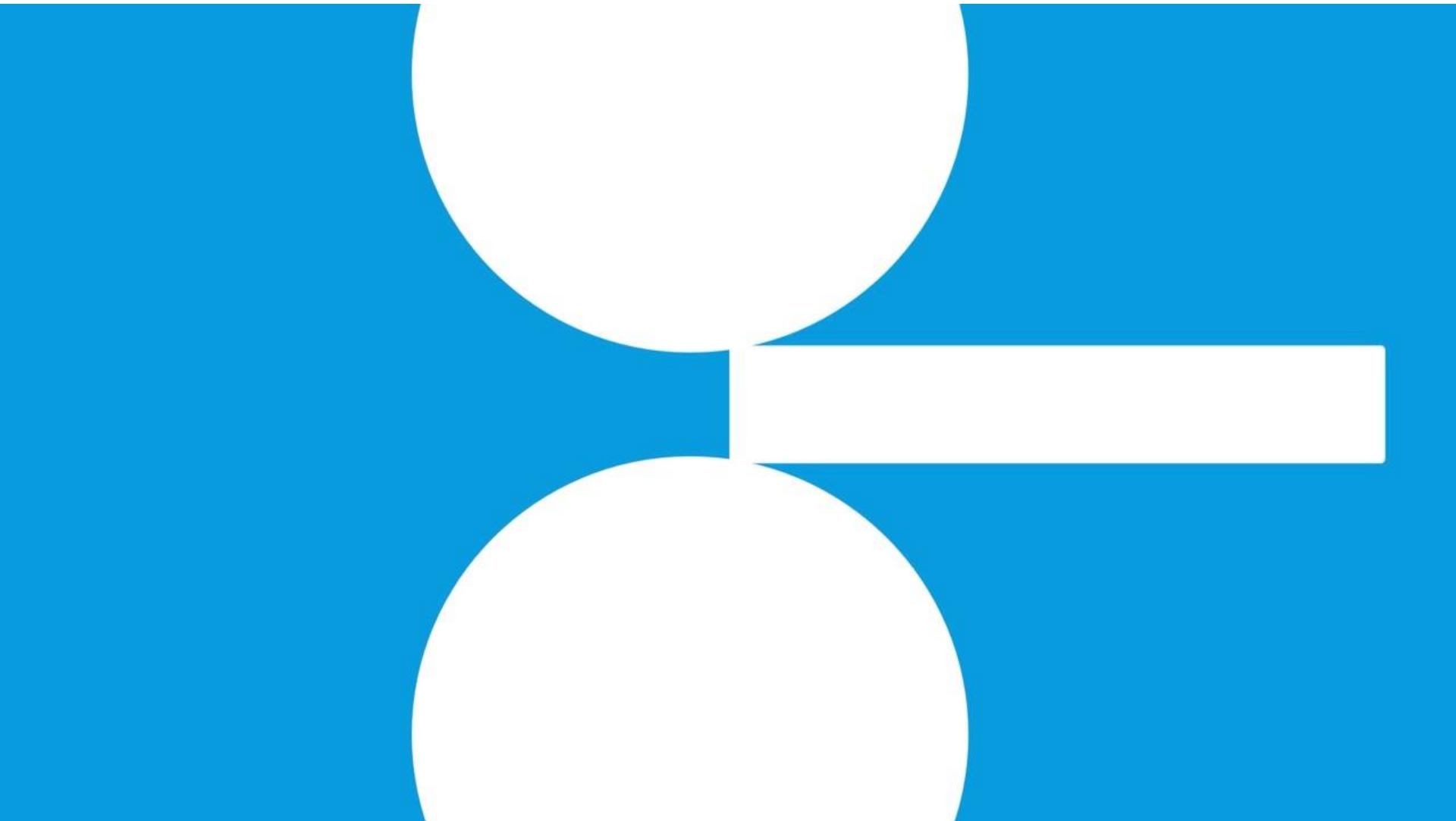


GRADIENT FREE ALGORITHM

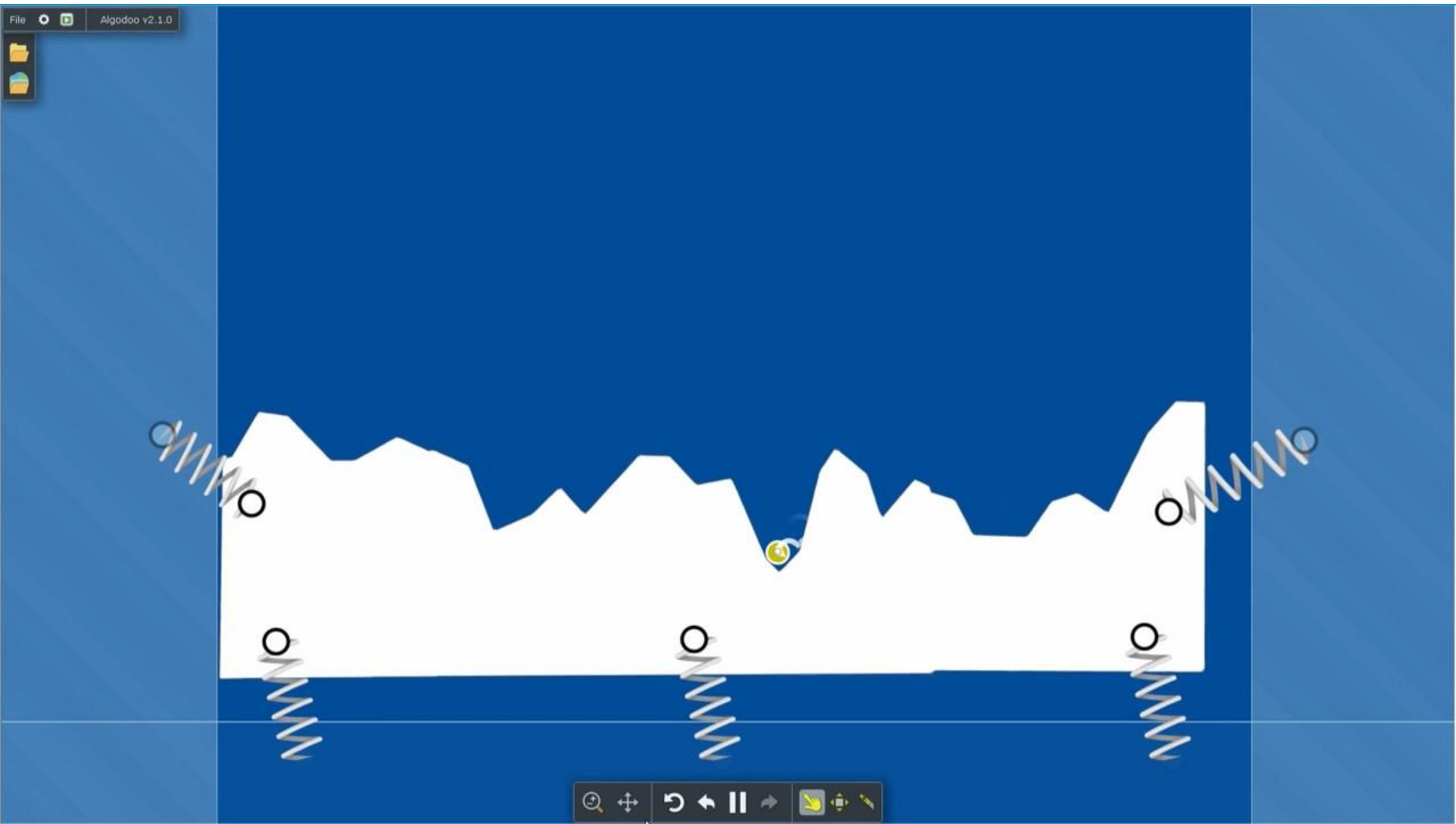
**SIMULATED
ANNEALING**



SIMULATED ANNEALING



SIMULATED ANNEALING



OTHER GRADIENT FREE ALGORITHM BASED ON NATURAL PROCESSES

- ANT COLONY OPTIMIZATION
- PARTICLE SWARM
- HARMONY SEARCH
- ARTIFICIAL BEE COLONY
- BEES ALGORITHM
- SHUFFLED FROG
- IMPERIALISTIC COMPETITIVE
- RIVER FORMATION DYNAMICS
- INTELLIGENT WATER DROPS ALGO.
- GRAVITATIONAL SEARCH ALGO.
- BAT ALGO.
- FLOWER FORMATION
- CUTTLE FISH ALGO.



**HAPPINESS IS
ASSUMING THE
WORLD IS LINEAR**

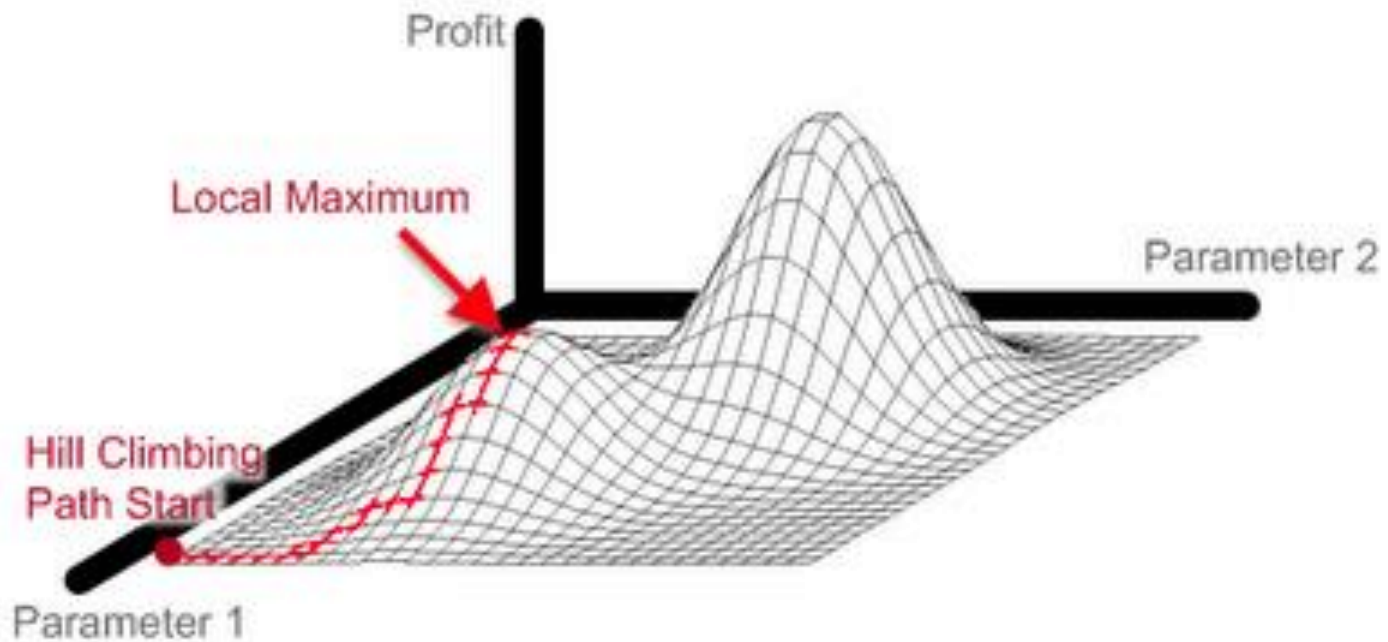


Optimality criteria

- a) **Local Optimal Point:** A point/solution or solution x^* is said to be local optimal point if there exist no point in the neighbourhood of x^* which is better than x^* .
- b) **Global Optimal Point:** If there exists no point in the entire search space which is better than x^{**} .

A "local" maximum [in contrast to a "global" maximum] is a point that's higher than what's around it but not actually the highest.

The problem with hill climbing is that it gets stuck on "local-maxima"



Improving Results and Optimization

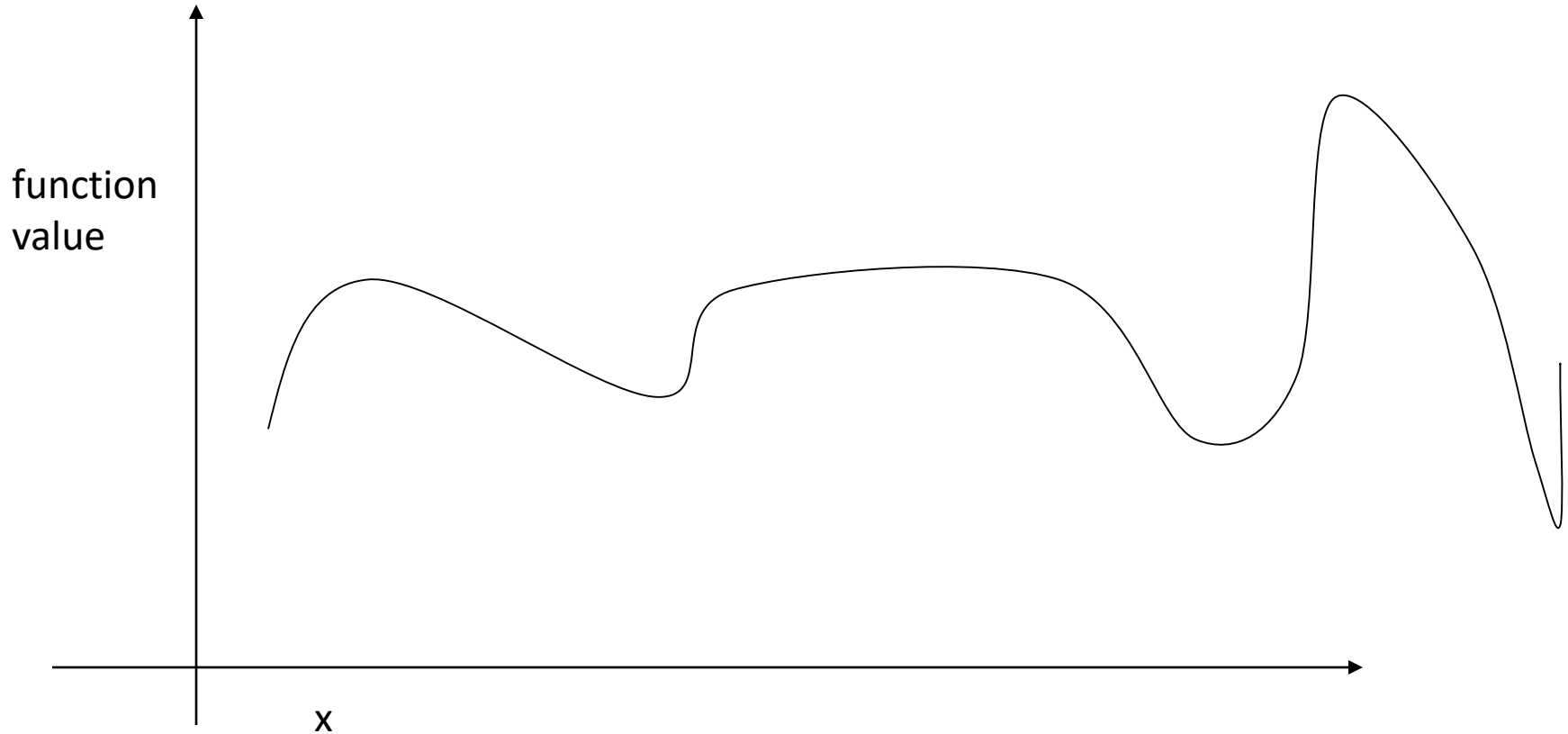
- Assume a state with many variables
- Assume some function that you want to maximize/minimize the value of
- Searching entire space is too complicated
 - Can't evaluate every possible combination of variables
 - Function might be difficult to evaluate analytically

Iterative improvement

- Start with a complete valid state
- Gradually work to improve to better and better states
 - Sometimes, try to achieve an optimum, though not always possible
- Sometimes states are discrete, sometimes continuous

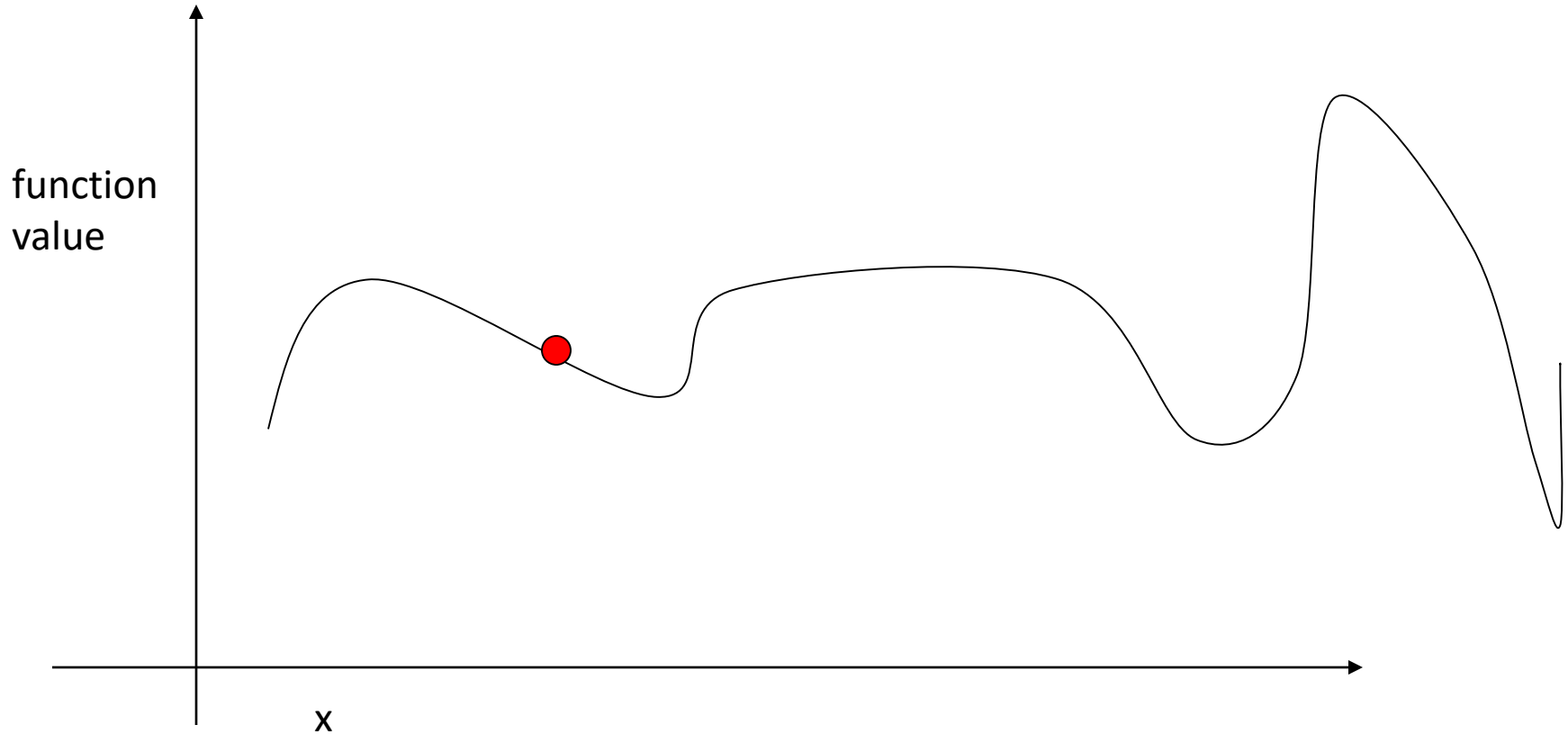
Simple Example

- One dimension (typically use more):



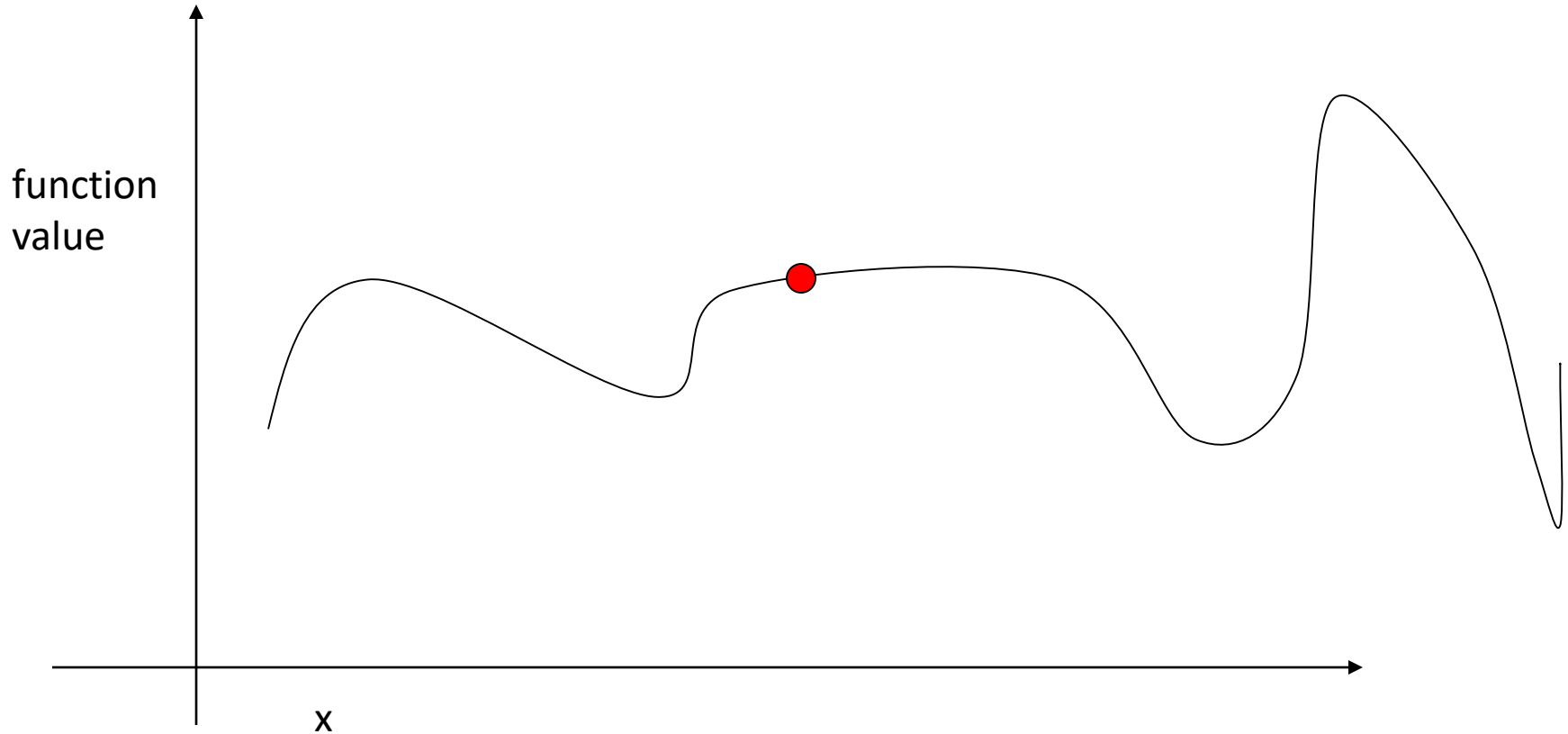
Simple Example

- Start at a valid state, try to maximize



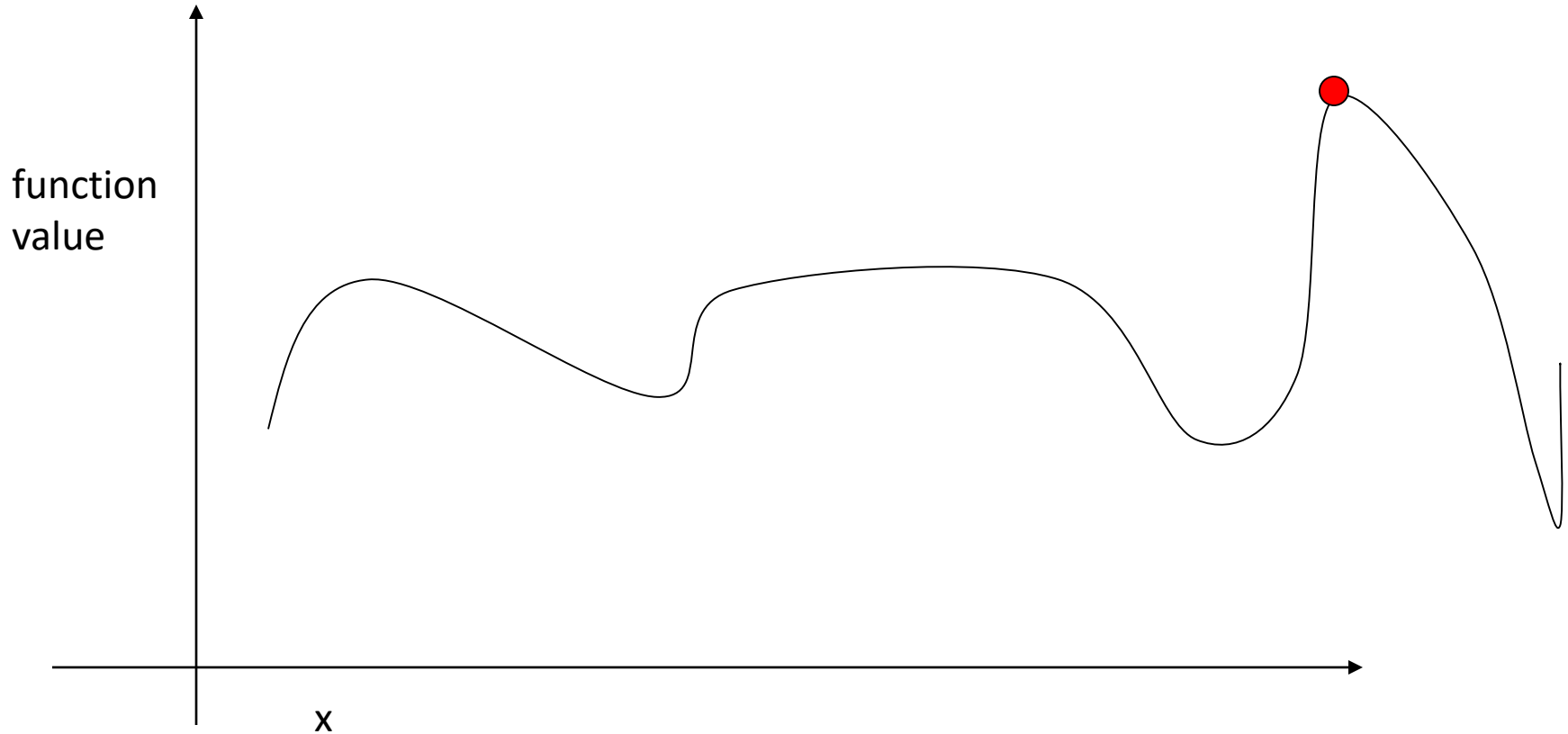
Simple Example

- Move to better state



Simple Example

- Try to find maximum



Hill-Climbing

Choose Random Starting State

Repeat

From current state, generate n random
steps in random directions

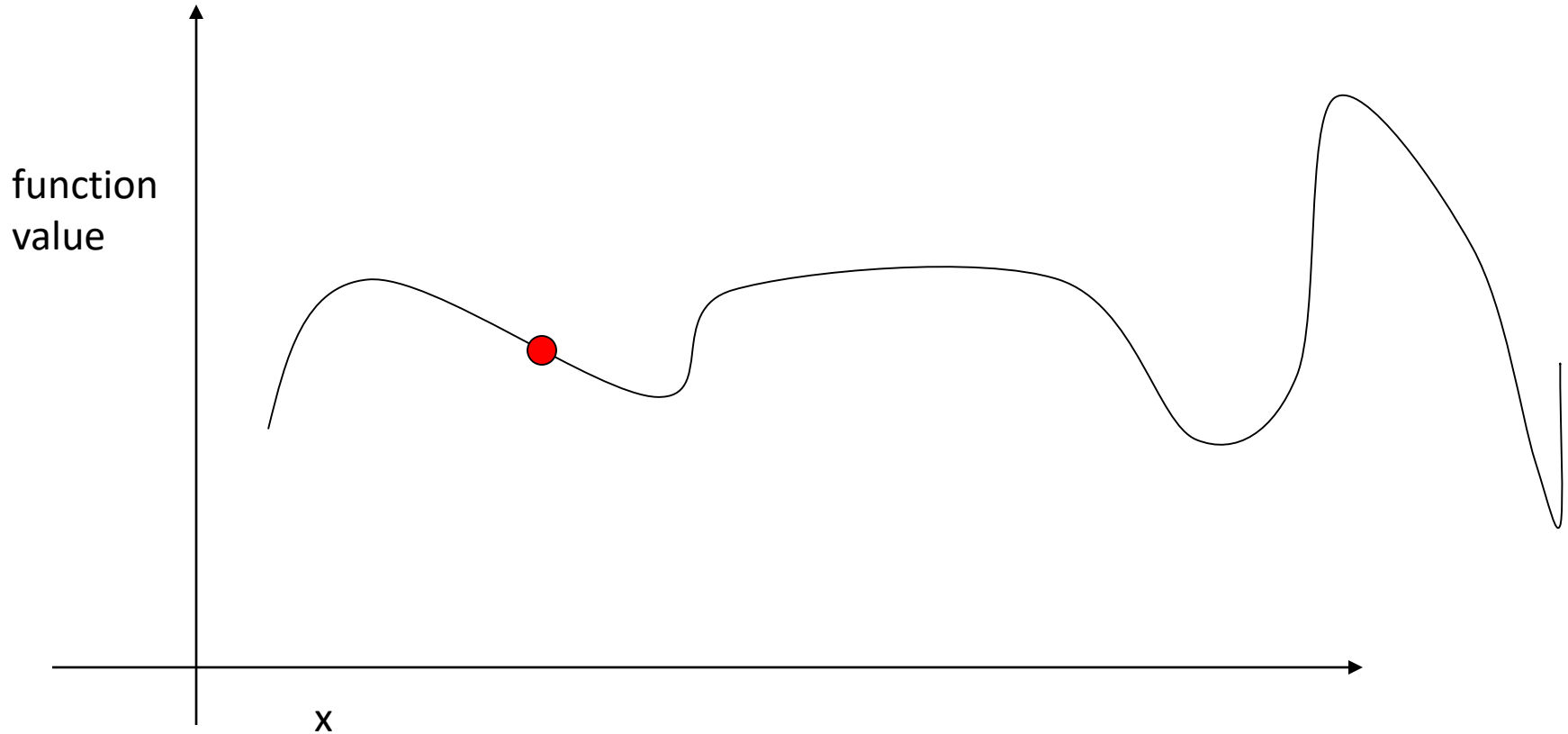
Choose the one that gives the best new
value

While some new better state found

(i.e. exit if none of the n steps were better)

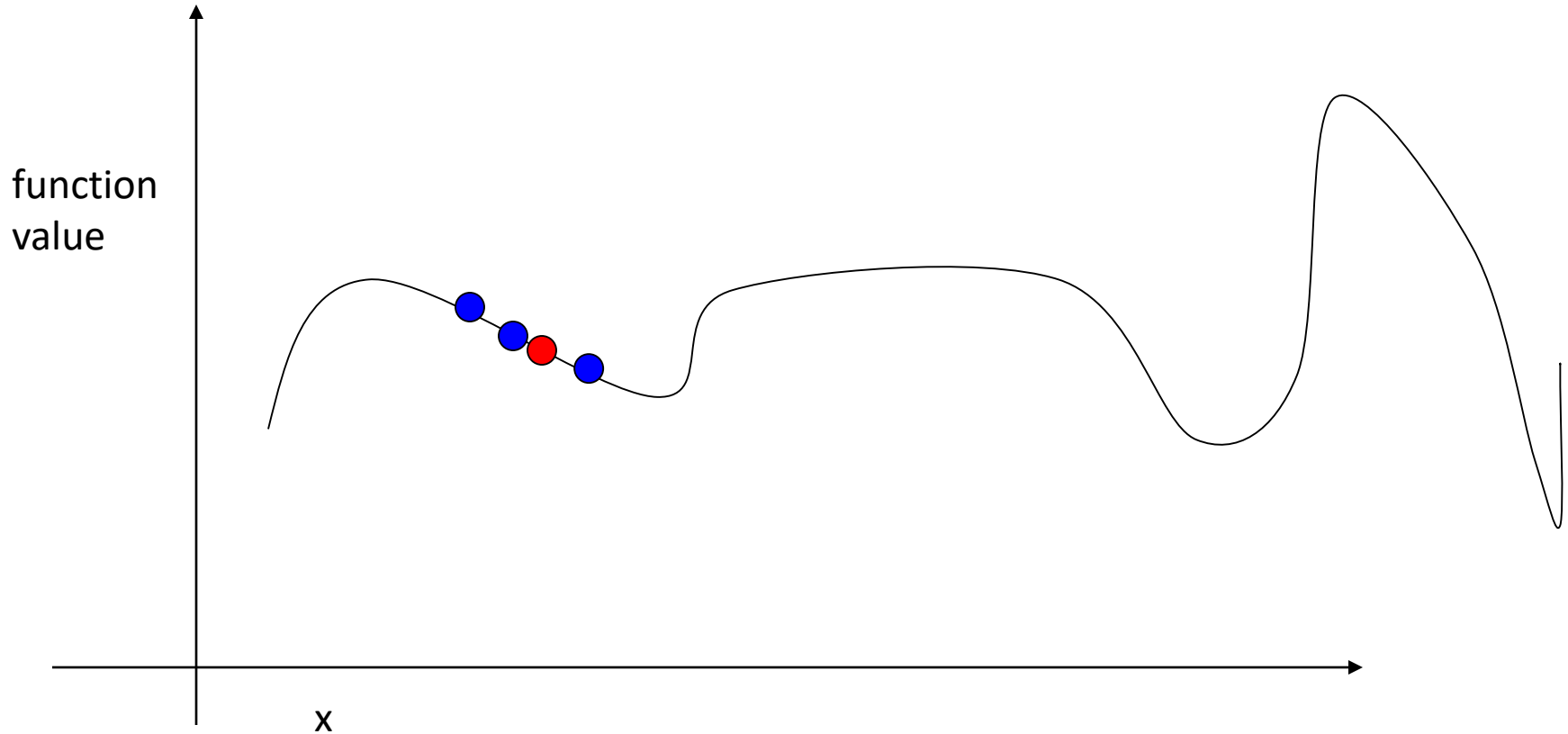
Simple Example

- Random Starting Point



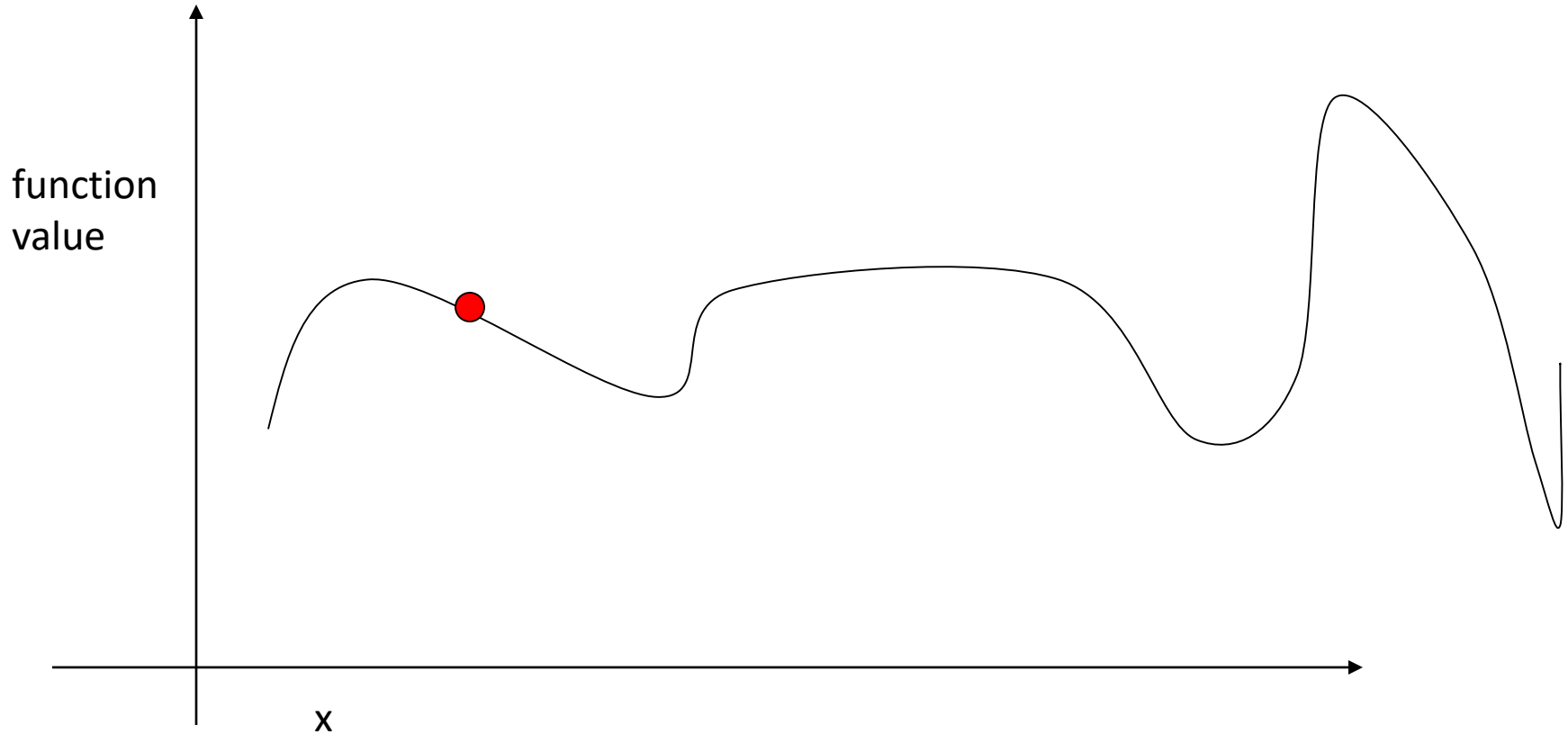
Simple Example

- Three random steps



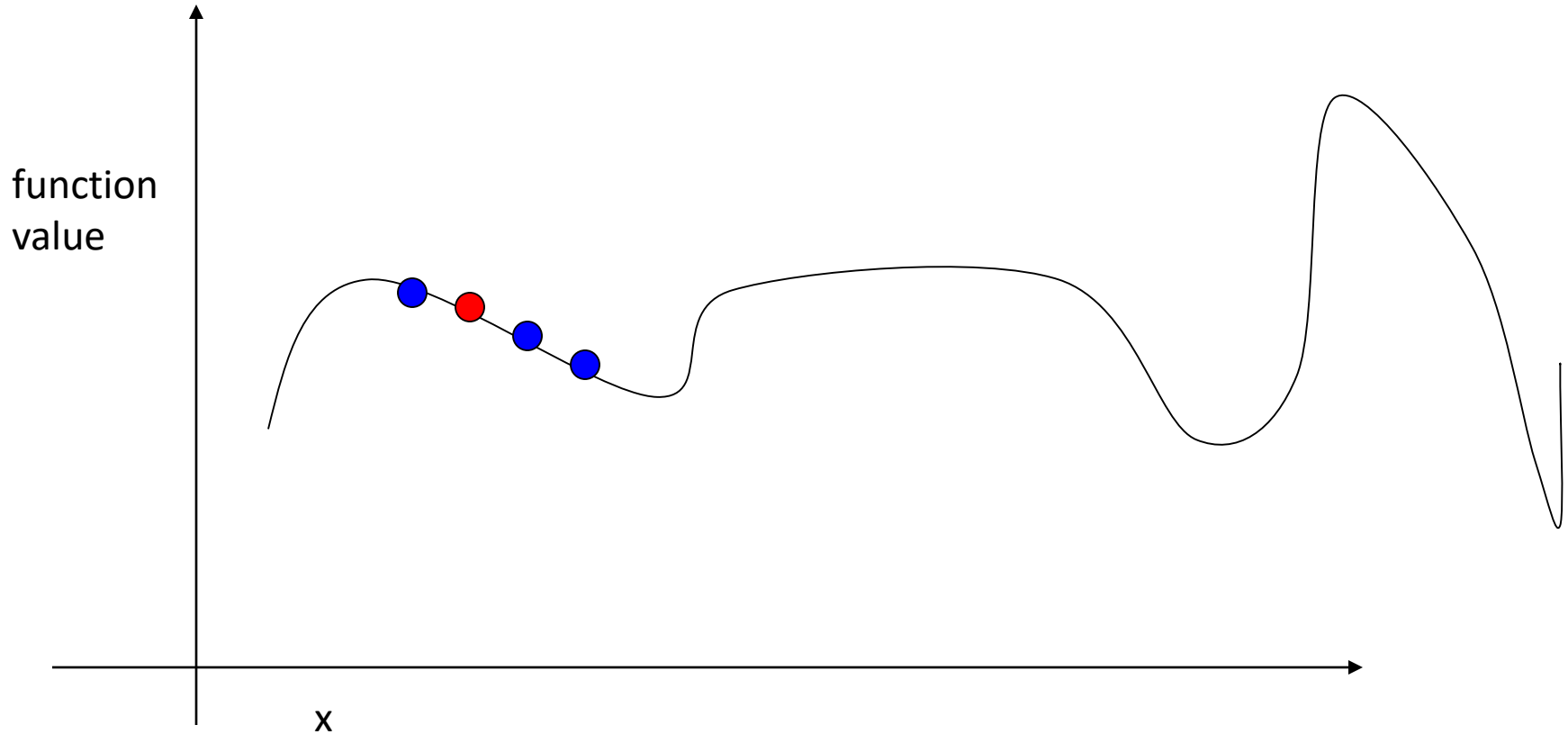
Simple Example

- Choose Best One for new position



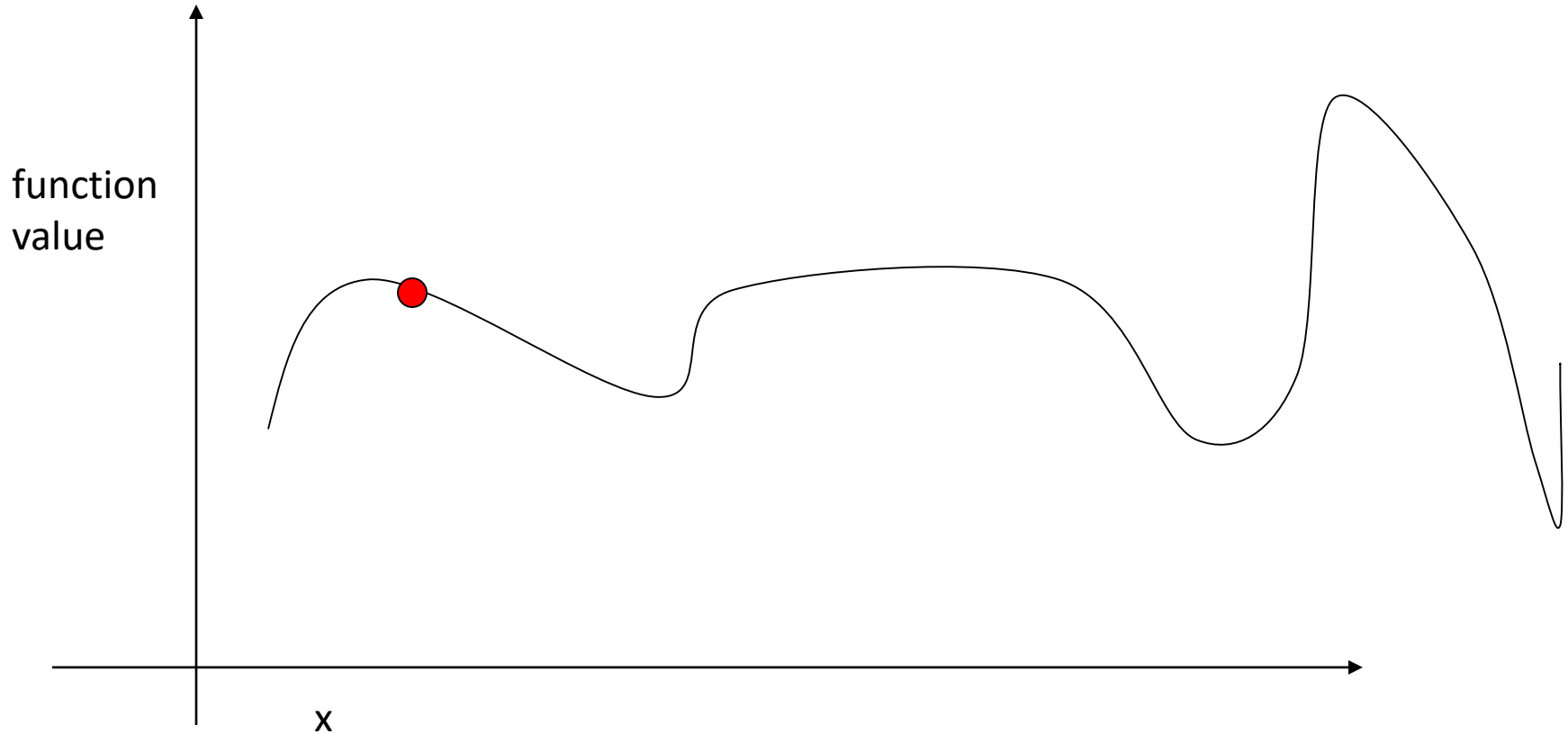
Simple Example

- Repeat



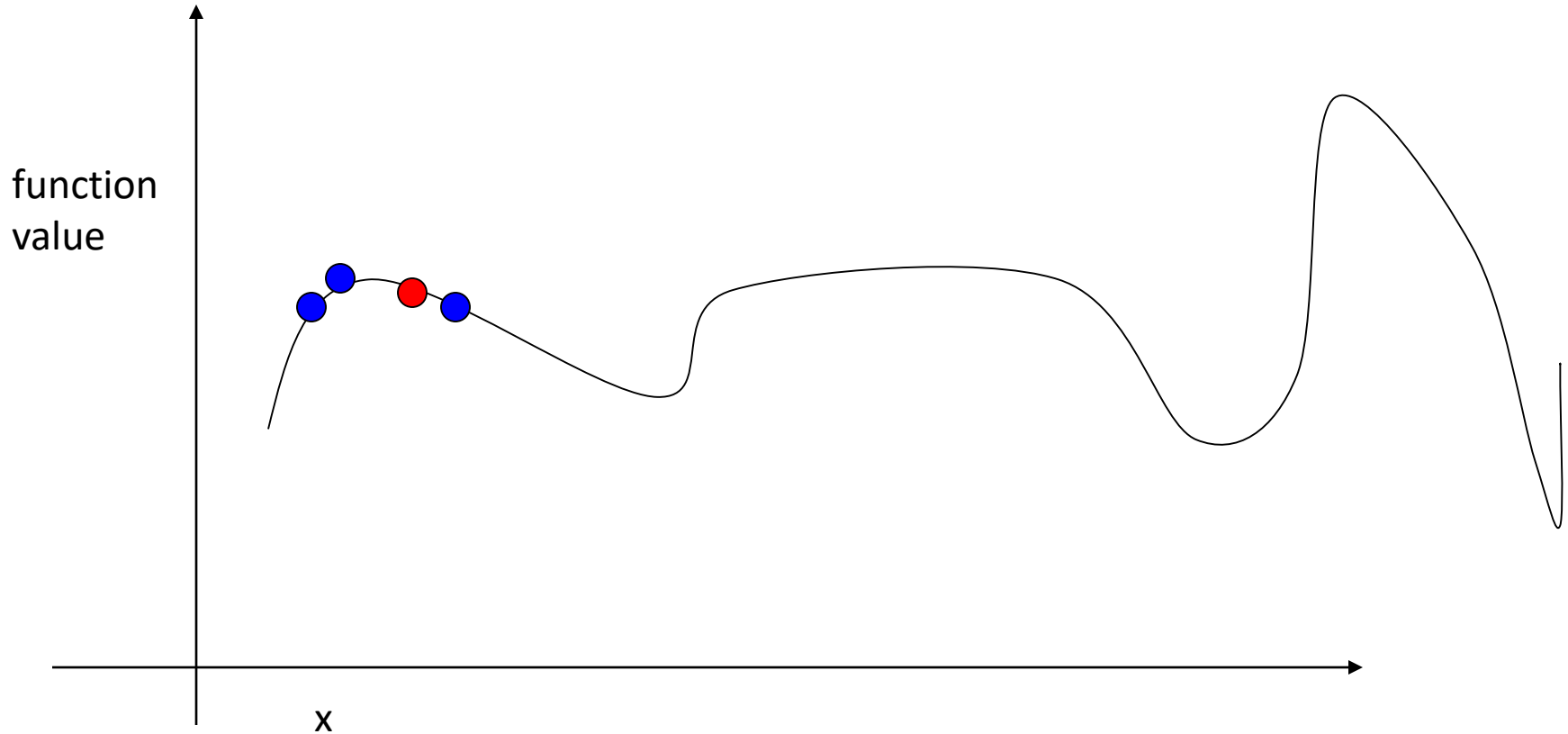
Simple Example

- Repeat



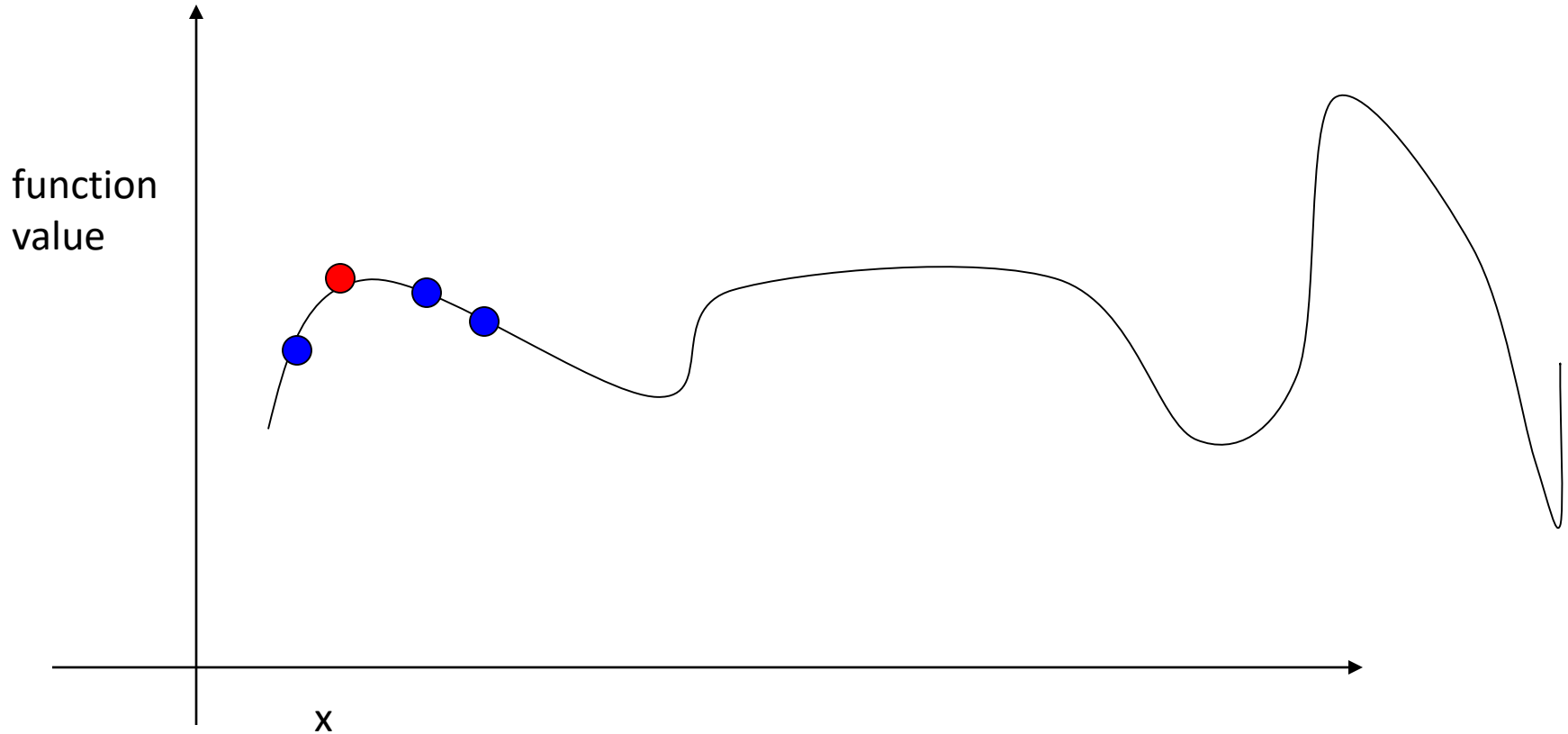
Simple Example

- Repeat



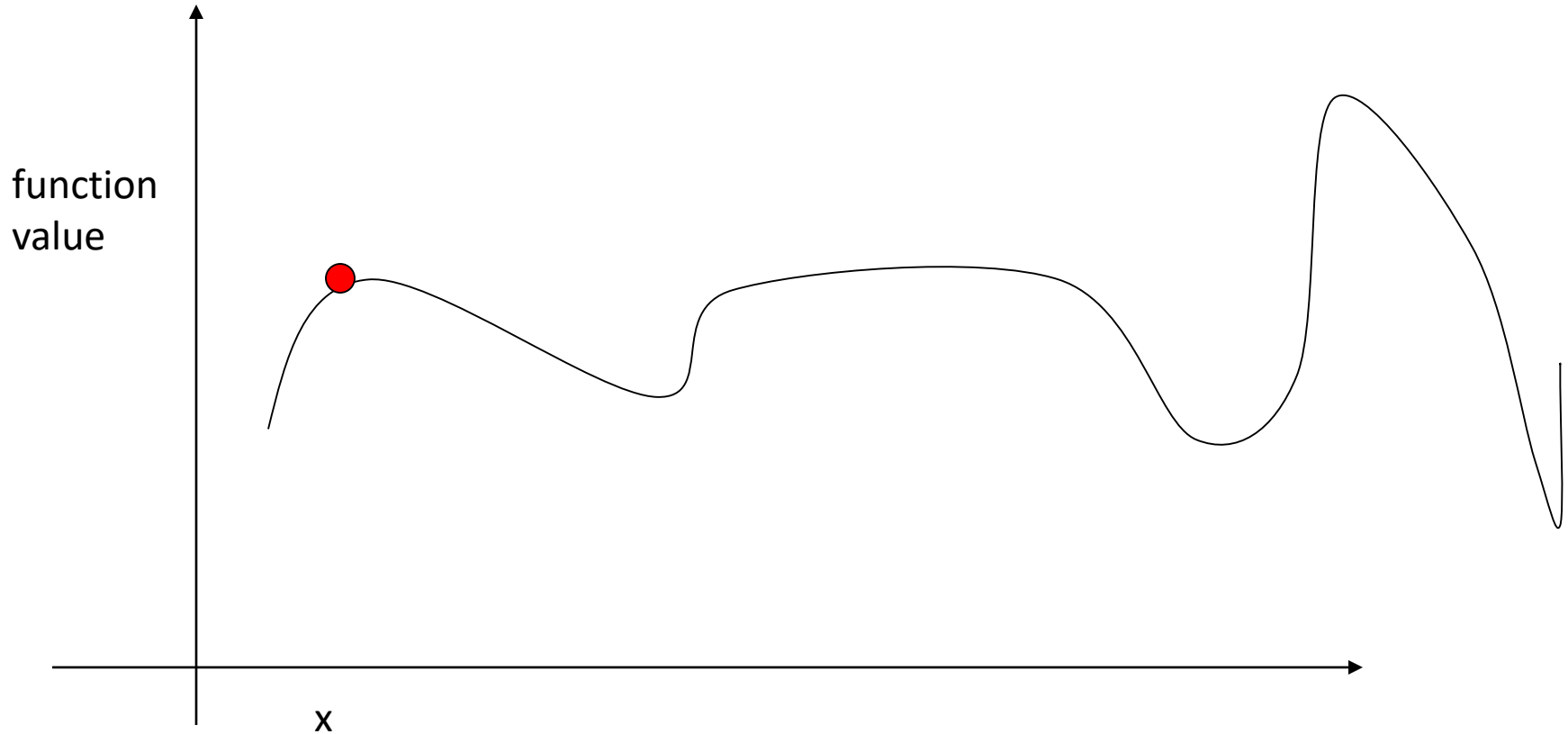
Simple Example

- Repeat



Simple Example

- No Improvement, so stop.



Problems With Hill Climbing

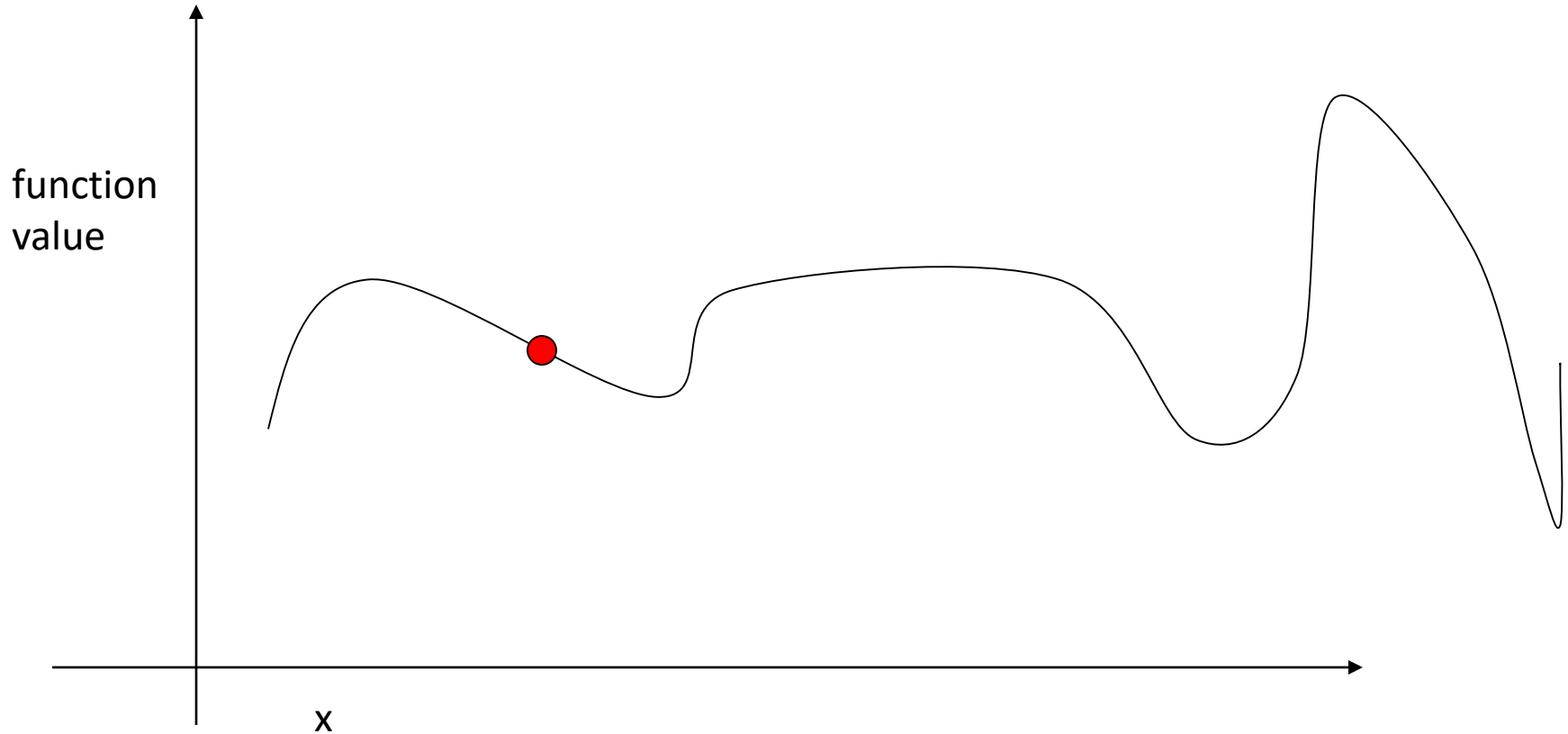
- Random Steps are Wasteful
 - Addressed by other methods
- Local maxima, plateaus, ridges
 - Can try random restart locations
 - Can keep the n best choices (this is also called “beam search”)
- Comparing to game trees:
 - Basically looks at some number of available next moves and chooses the one that looks the best at the moment
 - Beam search: follow only the best-looking n moves

Gradient Descent (or Ascent)

- Simple modification to Hill Climbing
 - Generally assumes a continuous state space
- Idea is to take more intelligent steps
- Look at local gradient: the direction of largest change
- Take step in that direction
 - Step size should be proportional to gradient
- Tends to yield much faster convergence to maximum

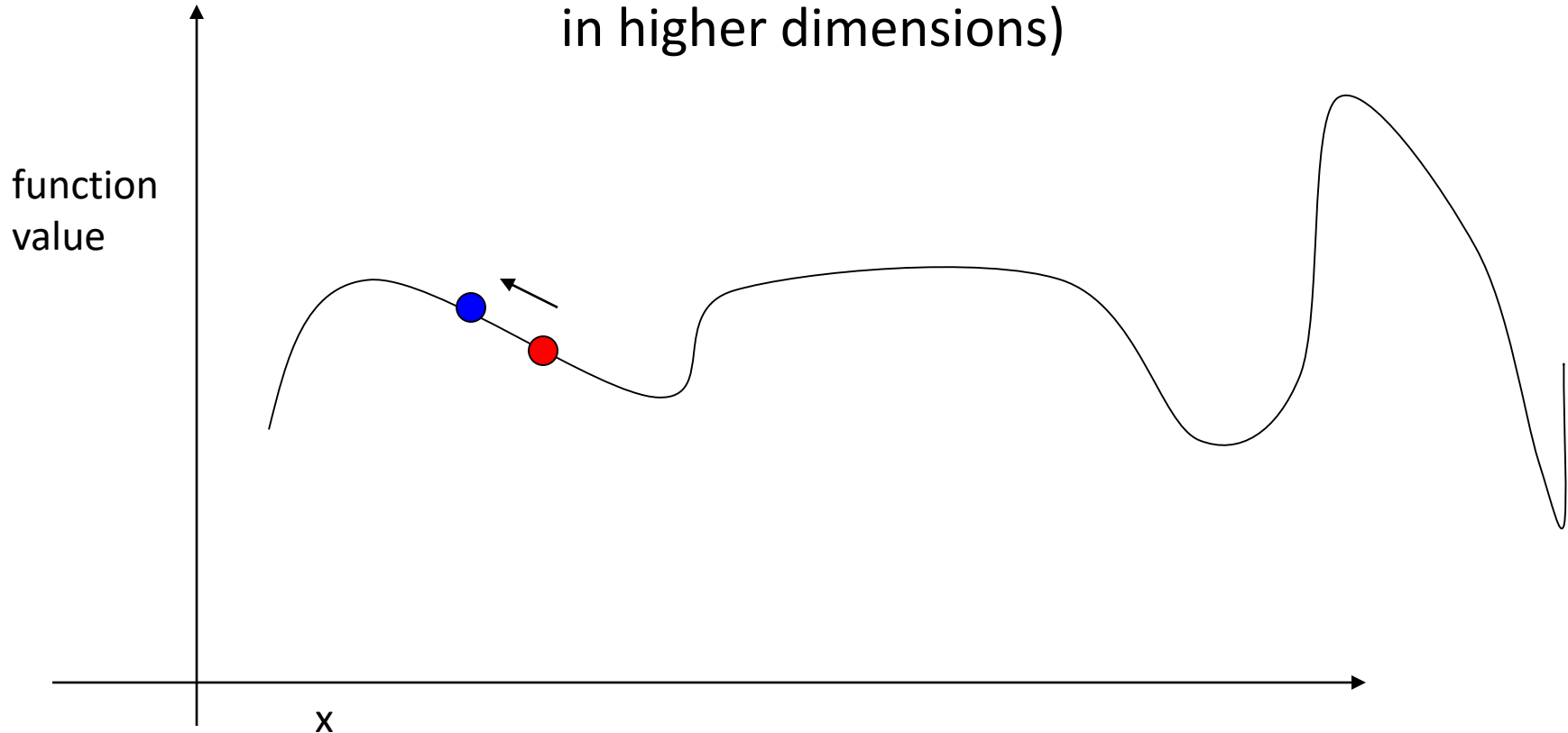
Gradient Ascent

- Random Starting Point



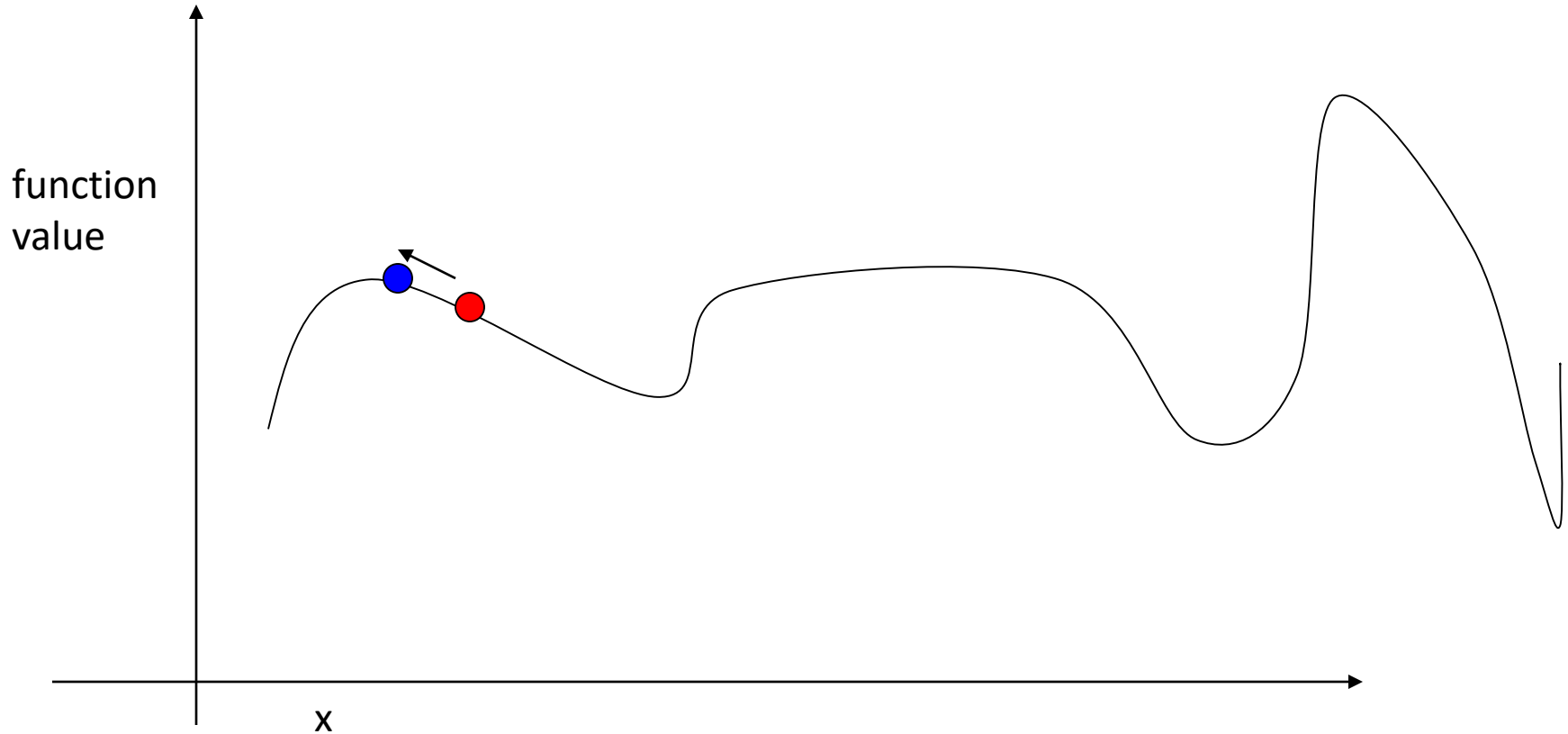
Gradient Ascent

- Take step in direction of largest increase
(obvious in 1D, must be computed
in higher dimensions)



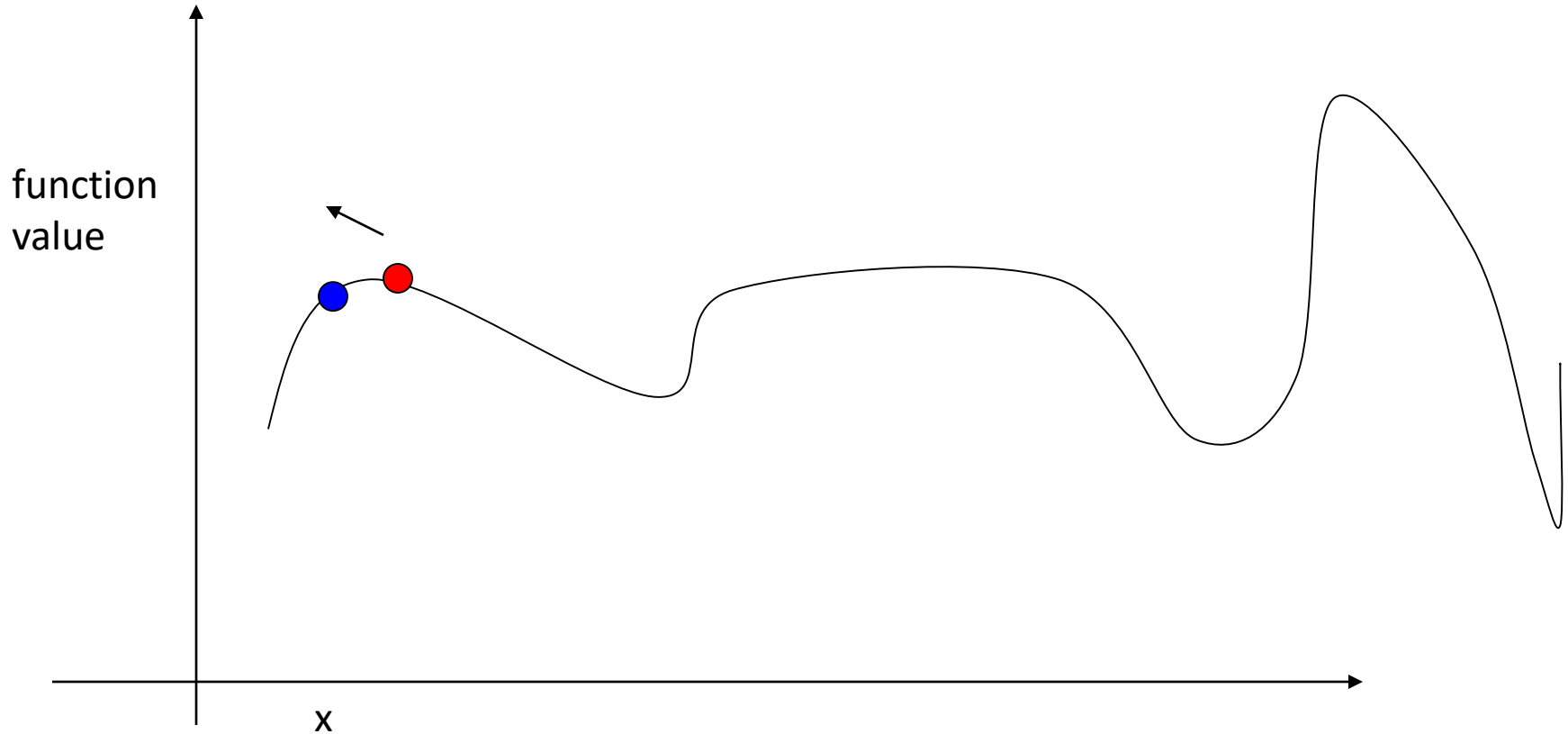
Gradient Ascent

- Repeat



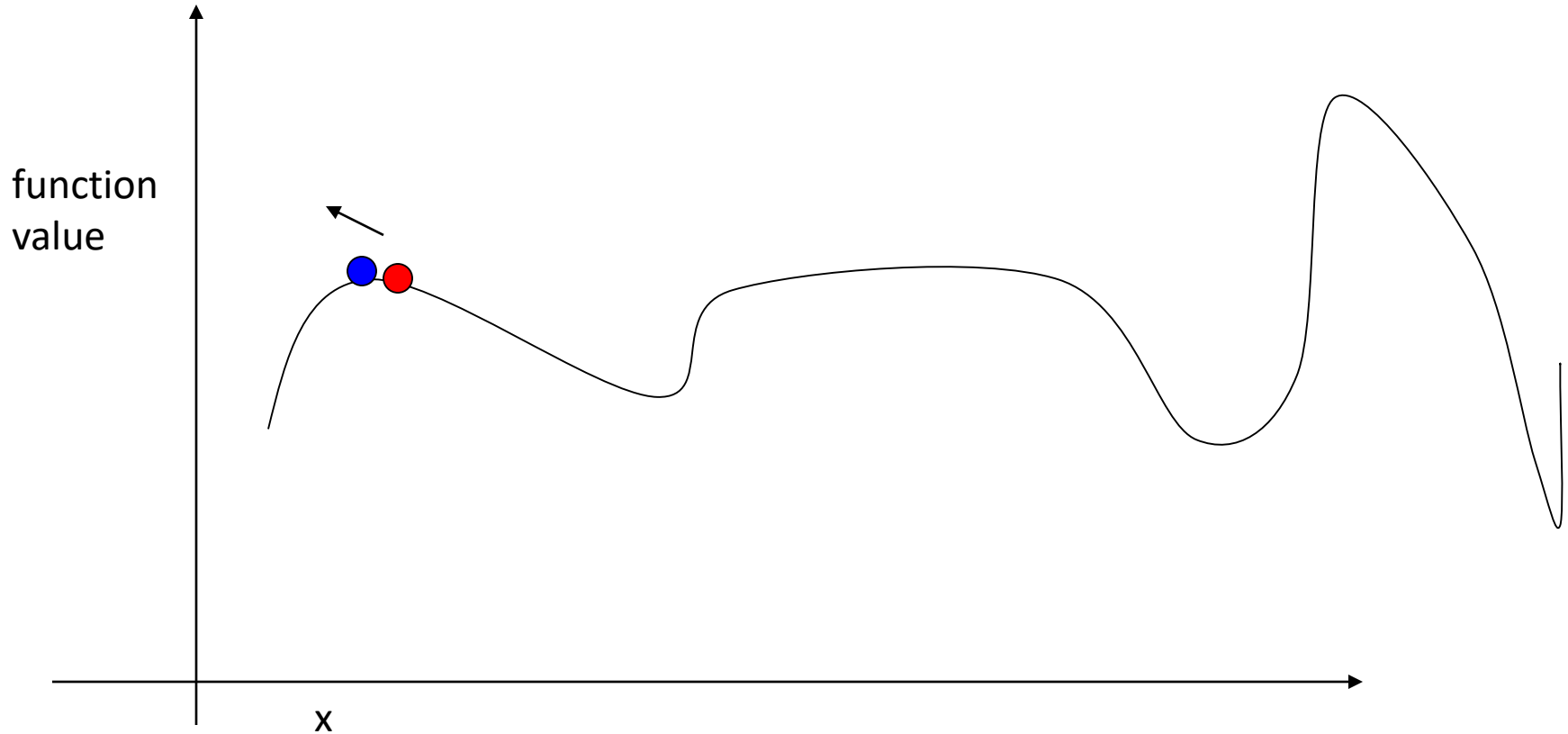
Gradient Ascent

- Next step is actually lower, so stop



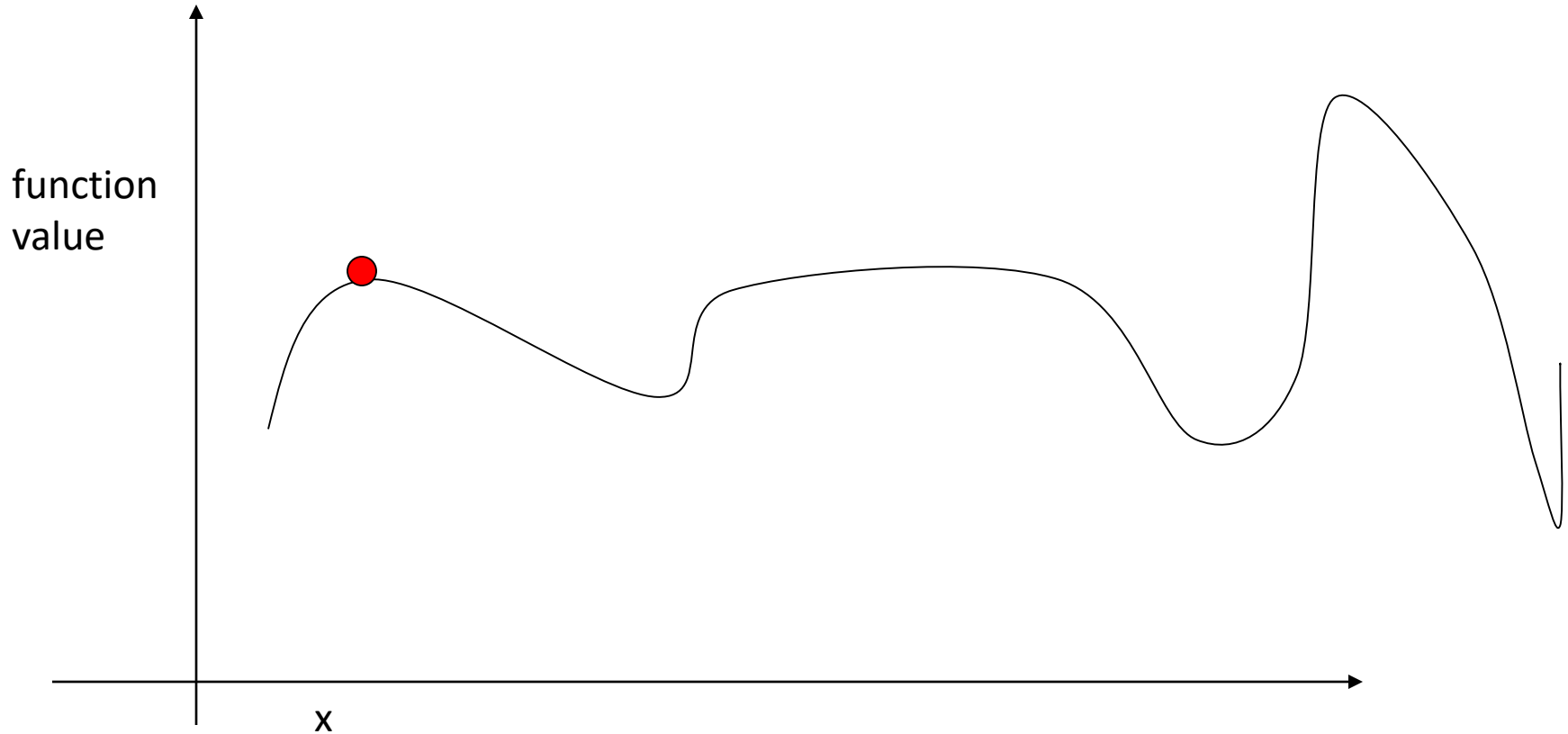
Gradient Ascent

- Could reduce step size to “hone in”



Gradient Ascent

- Converge to (local) maximum



Dealing with Local Minima

- Can use various modifications of hill climbing and gradient descent
 - Random starting positions – choose one
 - Random steps when maximum reached
 - Conjugate Gradient Descent/Ascent
 - Choose gradient direction – look for max in that direction
 - Then from that point go in a different direction
- Simulated Annealing

Nontraditional Optimization Algorithms:

They are found to be potential search and optimization algorithms for complex engineering optimization problems

- I. Genetic Algorithm (GA)
- II. Simulated Annealing (SA)

Genetic Algorithm

First developed by John Holland in 1970's

- Popularized largely by the work of David Goldberg
- Explosive growth in
 - Engineering design
 - Machine Learning/Artificial Intelligence
 - Data Mining
 - Model parameter fitting

GA.....

- Fall under the category of evolutionary computation
- Search and Optimization algorithms that mimic natural evolution
- Based on two fundamental principles
 - Exploration (variation)
 - Exploitation (survival of the fittest)

GA terminology

- Chromosome: consists of a binary string used to represent designs
 - Genes: individual binary variables
 - Alleles: individual binary variable values
- Genotype: *kary* representation of *ith* design
- Phenotype: Expressed Genotype
 - Parameter space
 - Fitness space

GA Mechanics

- Search point (solution) represented by chromosome
- GAs work by manipulating population of chromosomes
- Three fundamental operators
 - Selection → Exploitation
 - Crossover } → Exploration
 - Mutation }

GA Mechanics contd.

- Crossover and Mutation result in sampling over the solution space
- Selection needs a criterion
 - This is the objective function (fitness function in GA jargon)
 - Computer evaluates this function
 - Human makes decision (subjective function)
 - Co-evolved against predators and prey

GA Operators

- Selection
 - Darwinian survival of the fittest.
 - Better individuals have more children (more copies in mating pool)
 - Ways to do:
 - Roulette wheel or proportionate selection
 - Tournament selection (w/w.o. replacement)
 - Truncation

GA Operators

- Crossover
 - Combine bits and pieces of good parents
 - Speculate on, new, possibly better children
 - By itself, a random shuffle on chromosome
 - With population becomes a sampling of possible combinations (good for exploiting inherent solution patterns...)

GA Operators

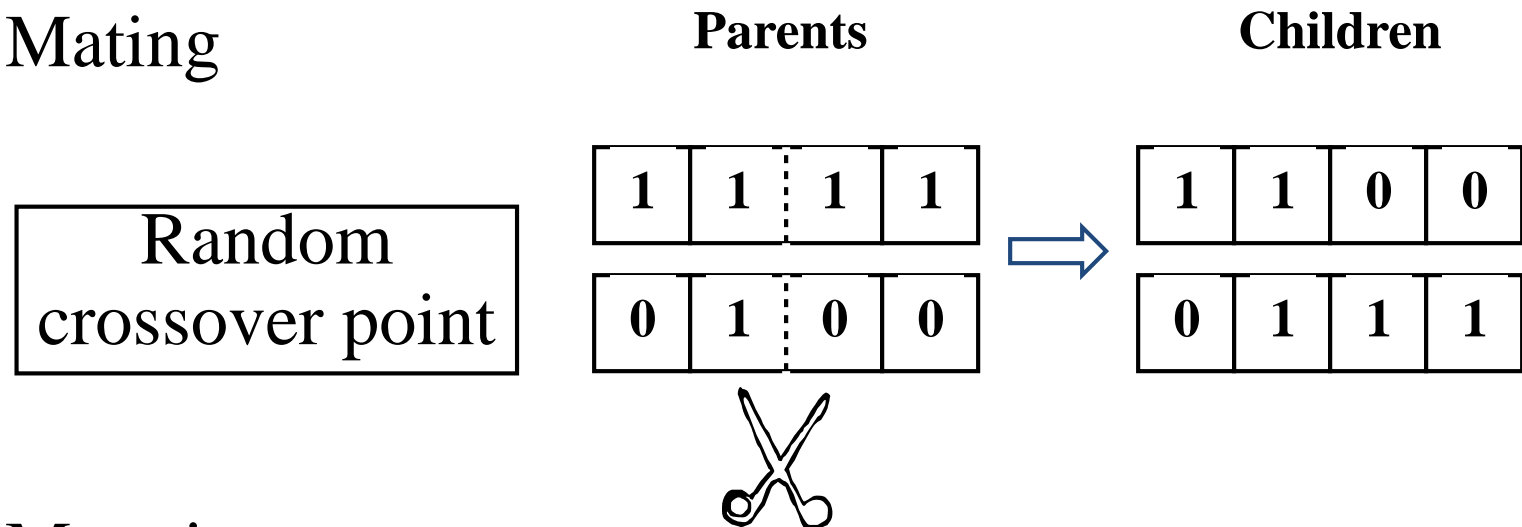
- Mutation
 - Mutation is a random alteration of a string
 - Change a gene, small movement in the neighborhood
 - By itself, a random walk
 - Helpful to prevent premature convergence
 - Normally allow at least one mutation in each population ($p_m = 1/n$)

GA Operators

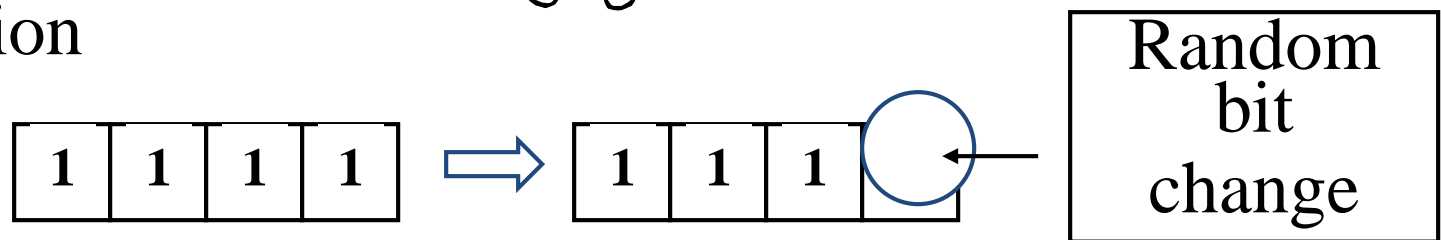
Selection

Population members compete to mate & pass traits

Mating



Mutation



GA flowchart

- Start with Initial Population
- Evaluate fitness of individuals
- Select better individuals form mating pool
- Members of mating pool interact forming children
- Mutate child population
- Replace parent with child
- Repeat till 'convergence criterion' met

Simulated Annealing (SA)

Simulated annealing was developed in the mid 1970's by Scott Kirkpatrick.

Resembles the cooling process of molten metals through annealing

Process of Annealing

1. Start by heating glass at high temperature, allowing molecules to move freely
2. Lower temperature of the glass slowly so that at each temperature the atoms can move just enough to begin adopting the most stable orientation.
3. Do this until temperature no longer alters glass.

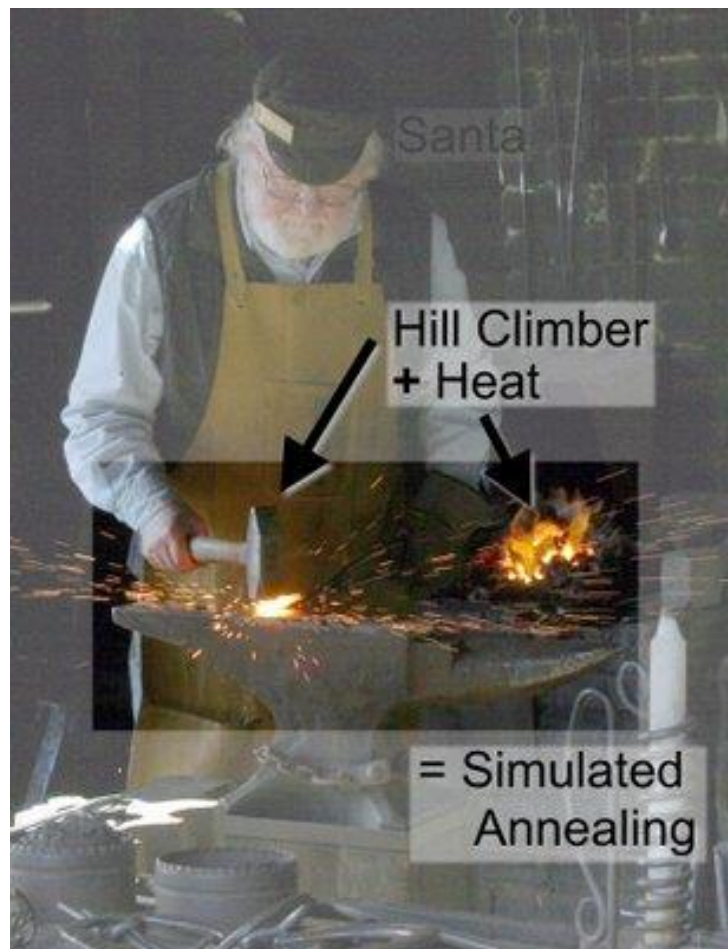
Main Ideas of Annealing

1. The temperature determines how much mobility the atoms have.
2. How slowly you cool glass is critical.
This rate is called the *cooling schedule (aka Annealing Schedule)*.
3. If the glass is cooled slowly enough, the atoms are able to "relax" into the most stable orientation.

What is Simulated Annealing?

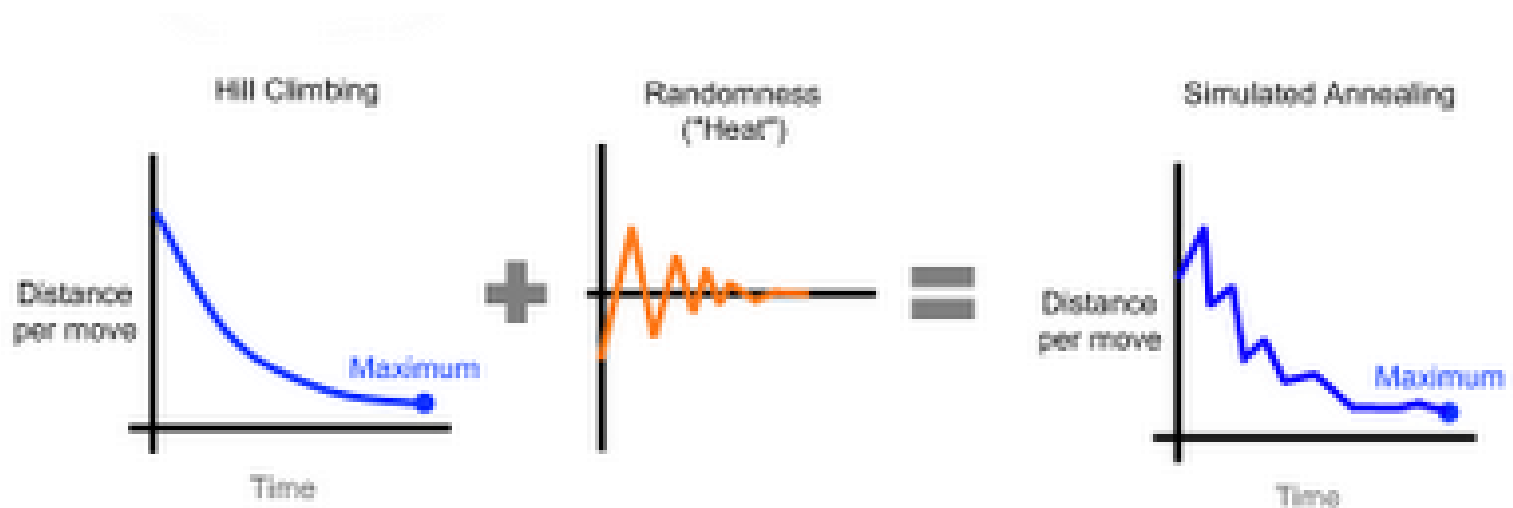
- Simulated Annealing (SA) uses the same ideas as regular annealing
- It is a *Metropolis Monte Carlo (MMC) Optimization Method*

(used especially when the global extrema are hidden amongst many local extrema).



The blacksmith's hammer guides the iron into the desired shape and density while the heat made the iron more malleable and responsive to the hammer. Essentially hill climbing is equivalent to a blacksmith hammering without heat.

Sim. annealing is hill climbing plus the addition of random jumps.



Exploring the Landscape

- **Local Maxima:** peaks that aren't the highest point in the space
- **Plateaus:** the space has a broad flat region that gives the search algorithm no direction (random walk)
- **Ridges:** flat like a plateau, but with drop-offs to the sides; steps to the North, East, South and West may go down, but a step to the NW may go up.

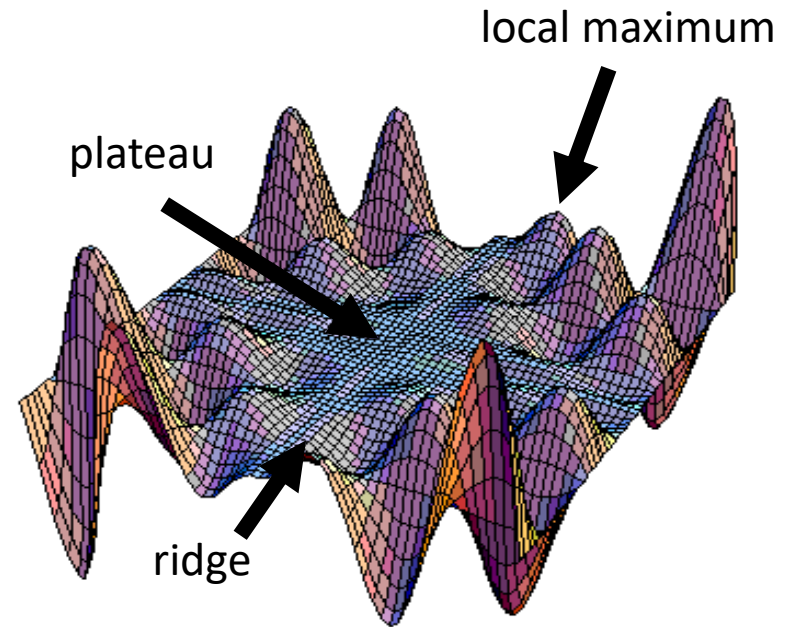


Image from:
<http://classes.yale.edu/fractals/CA/GA/Fitness/Fitness.html>

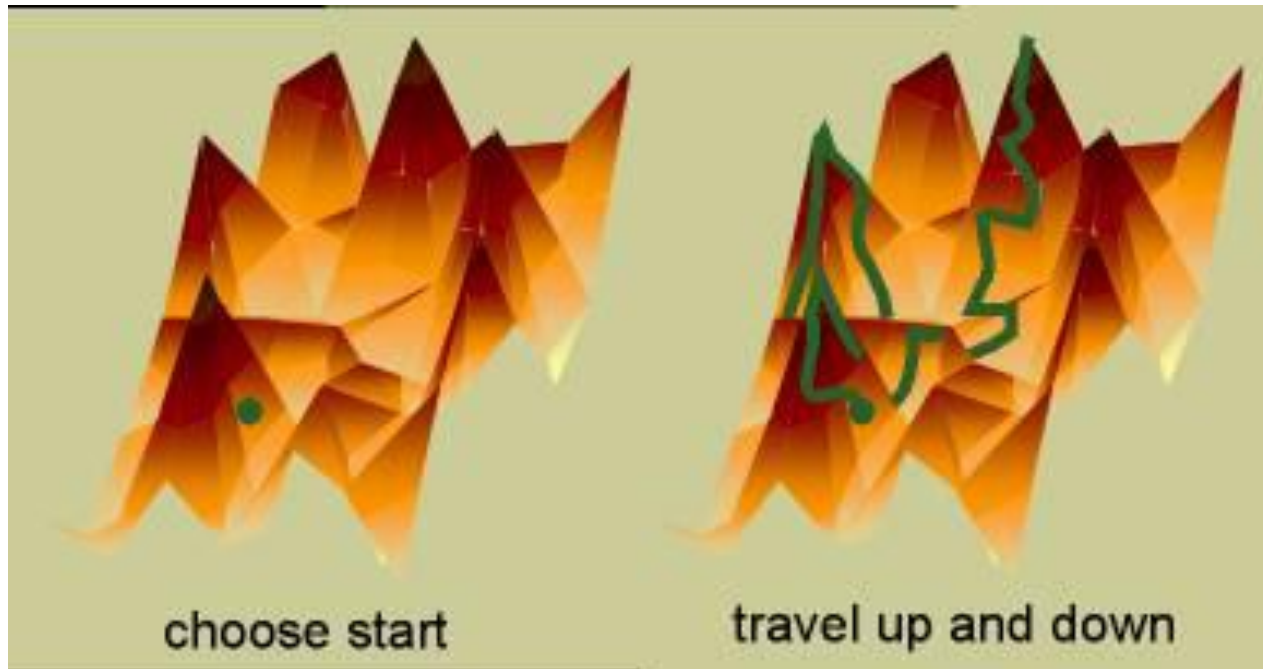
Drawbacks of hill climbing

- Problems: local maxima, plateaus, ridges
- Remedies:
 - **Random restart:** keep restarting the search from random locations until a goal is found.
 - **Problem reformulation:** reformulate the search space to eliminate these problematic features
- Some problem spaces are great for hill climbing and others are terrible.

SA intuitions

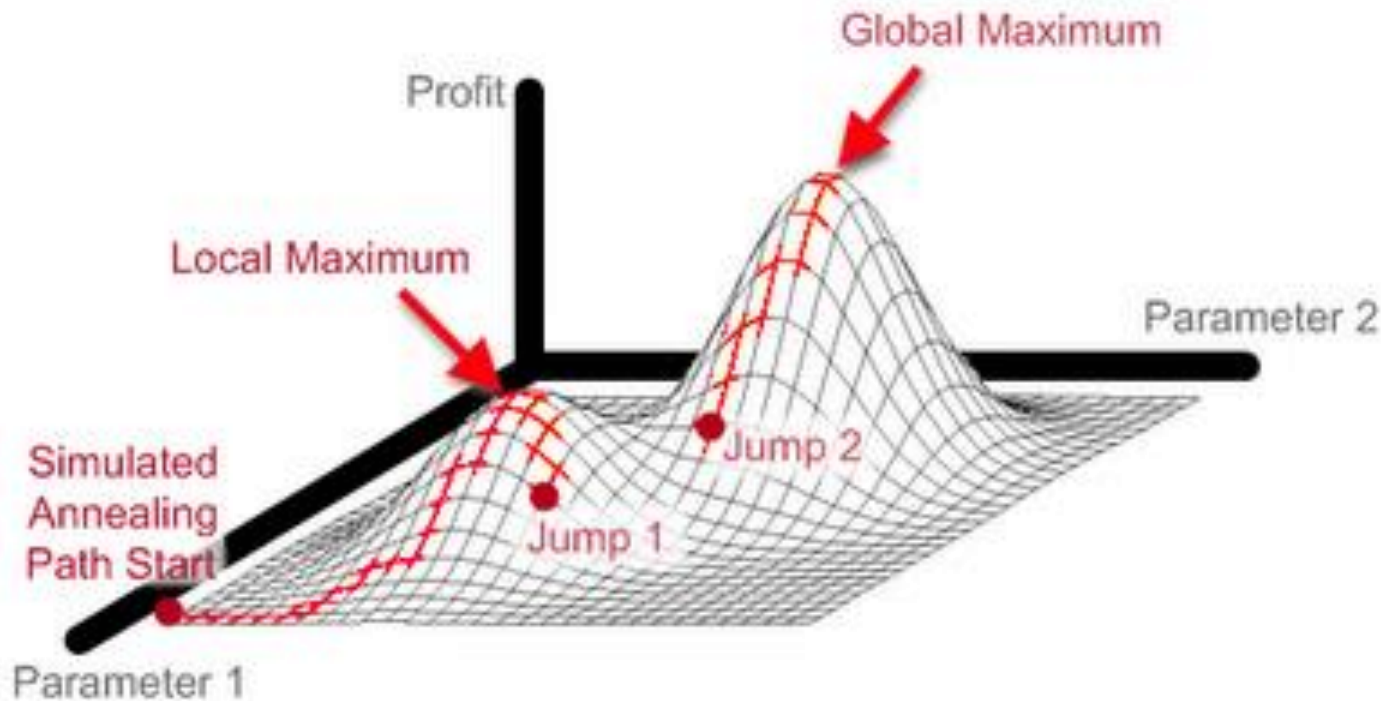
- combines hill climbing (efficiency) with random walk (completeness)
- Analogy: getting a ping-pong ball into the deepest depression in a bumpy surface
 - shake the surface to get the ball out of the local minima
 - not too hard to dislodge it from the global minimum
- Simulated annealing:
 - start by shaking hard (high temperature) and gradually reduce shaking intensity (lower the temperature)
 - escape the local minima by allowing some “bad” moves
 - but gradually reduce their size and frequency

Search Process

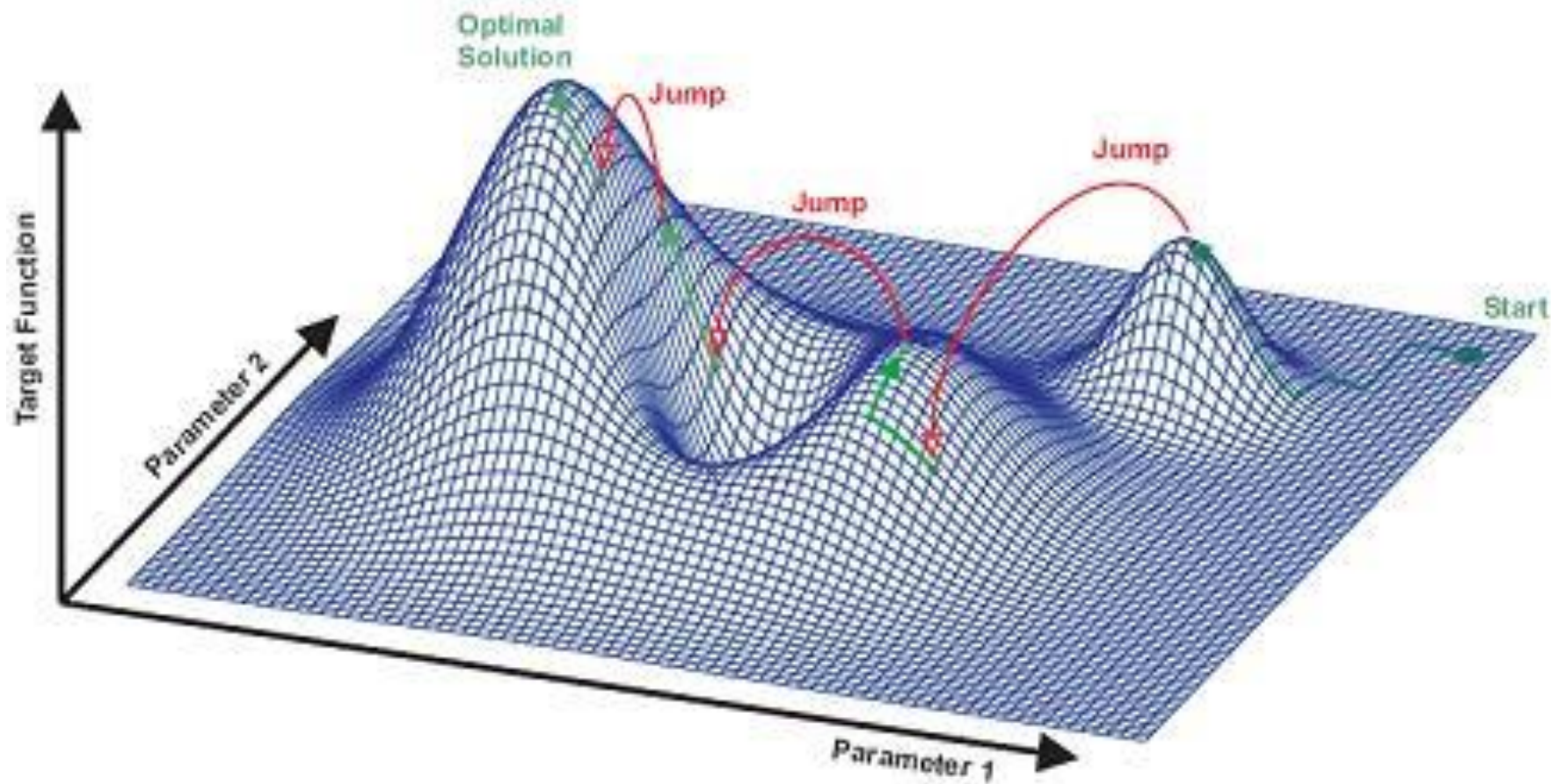


Simulated annealing will outperform hill climbing when the local maximum is near the global maximum. In this case one of the jumps may get far enough from the local max to reach the ascending slope of the global max:

Simulated Annealing can escape local minima with chaotic jumps



Simulated Annealing



Linchpin of SA

- During an MMC iteration, if at current guess for minima X
- Function value goes down, ACCEPT X.
- Function value goes up, ACCEPT X with probability

$$P(E(t+1)) = \min [1, \exp (-\Delta E/kT)]$$

- where:
 - T is the temperature of the system
 - k is the Boltzmann Constant (Metropolis)
 - ΔE is the difference in function value from the previous iteration

SA algo..

Step 1

Choose an initial point x^0

Termination criterion ε

Set Temperature T high and

Set n , and $t = 0$

Step 2

Calculate randomly created neighborhood point

$$x^{t+1} = N(x^t)$$

Step 3

If $\Delta E = E(x^{t+1}) - E(x^t) < 0$

Else create a random number (r) in the range $(0,1)$.

If $r \leq \exp(\Delta E / T)$ Set $t=t+1$;

Else go to Step 2

Step 4

If $|x^{t+1} - x^t| < \varepsilon$ and T is small,
Terminate;

Else if $(t \bmod n) = 0$ then $T = RT$.

Go to Step 2

Else go to Step 2

AN EXAMPLE
on
GROUNDWATER MONITORING

Groundwater Monitoring

- Selection of sampling points and
- Temporal sampling frequency

To determine:

physical, chemical, and
biological characteristics of groundwater.

Motivation

- Designing effective and efficient LTM plans can be difficult, especially at sites with any of the following:
 - Many wells
 - Many possible constituents that could be sampled
 - Different types of samples with different costs and effectiveness
 - Traditional well-based samples
 - Indicator samples
 - Sensor data
- Mathematical optimization can help in identifying effective plans

Why Optimize?

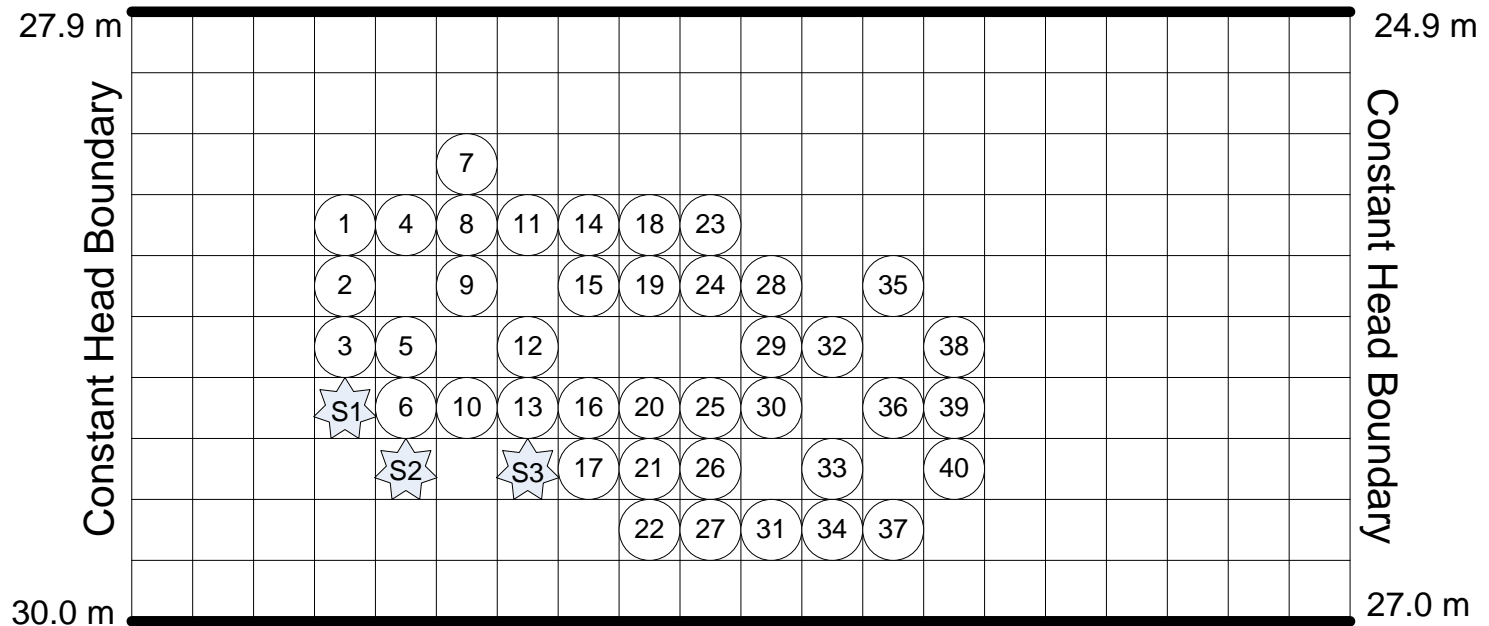
- The number of possible sampling plans in one monitoring period is

$$2^m$$


where m is the product of

- Number of possible sampling locations
- Number of constituents at each well
- Number of types of samples

Study Area for Analysis



 Source

 Potential Monitoring Well

Why Optimize (Contd.)?

- For example, a site with 10 wells and 3 possible constituents to measure at each well would have

possible sampling plans **2^{30} or 1 billion!**

- Any trial-and-error method is unlikely to identify the most effective sampling plans
- Mathematical optimization can efficiently identify the most effective sampling plans to satisfy any monitoring objective that can be quantified

Components of an optimization formulation

- **Decision Variables:**

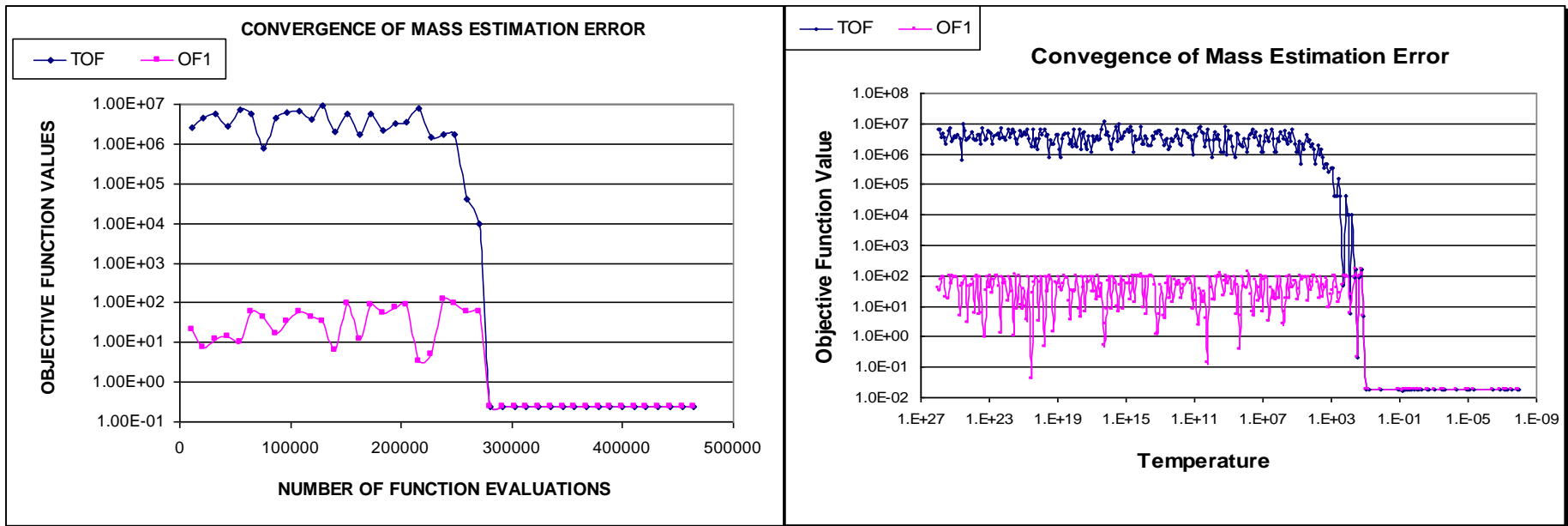
What we are determining optimal values for?

- **Objective function:**

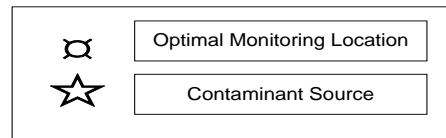
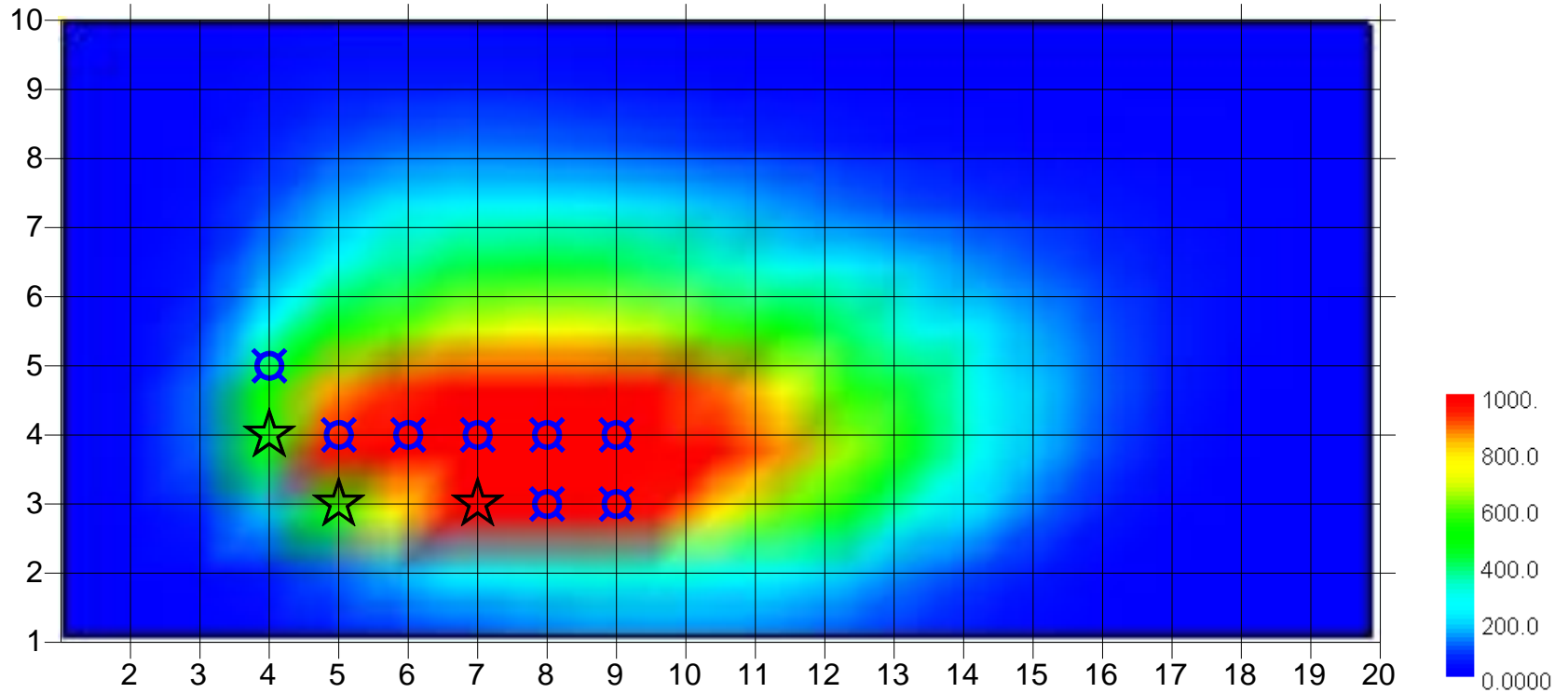
1. Values can be computed once the value of each decision variable is specified.
2. The mathematical equation being minimized or maximized.
3. Serves as the basis for comparing one solution to another.

- **Constraints:** Limits on values of the decision variables, or limits on other values that can be calculated once the value of each decision variable is specified.

Sensitivity Analysis

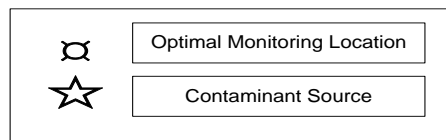
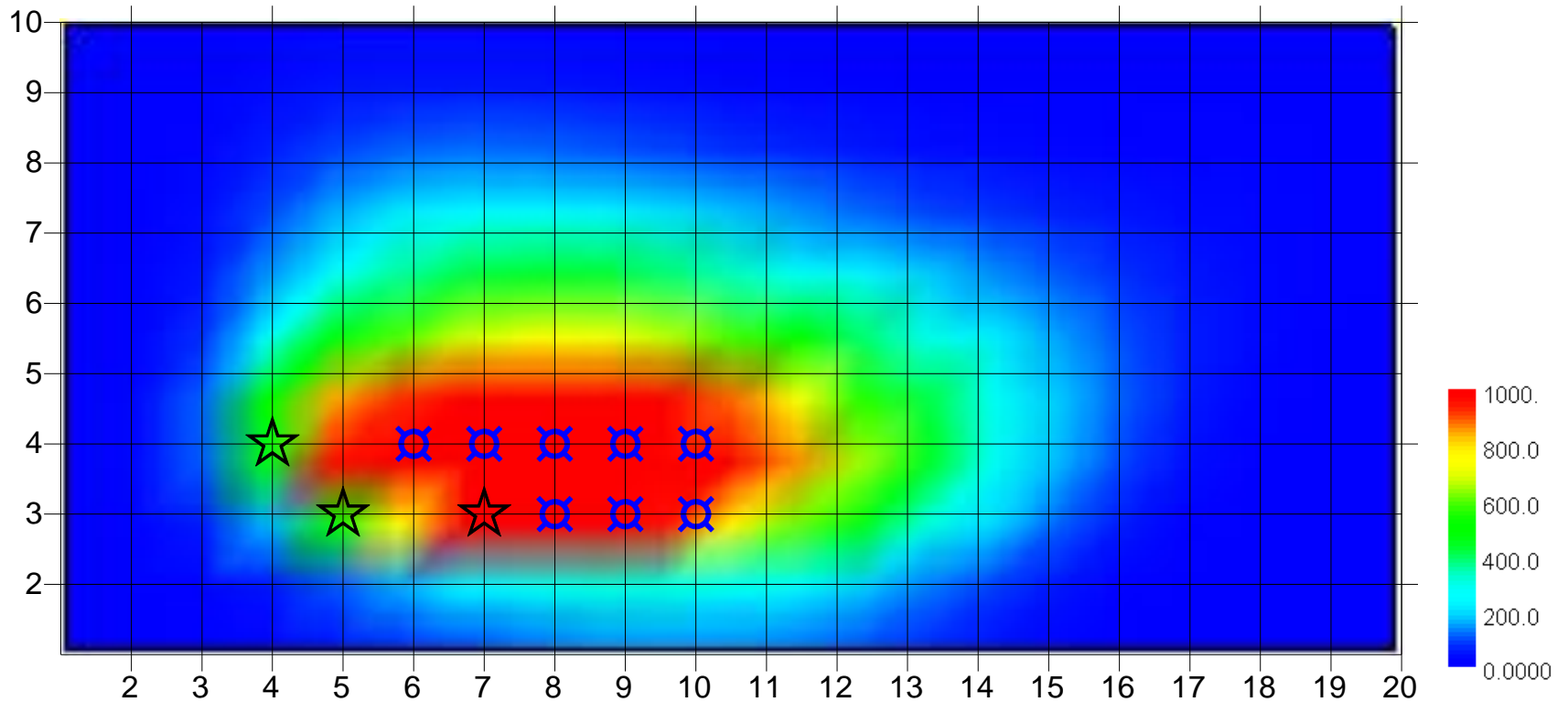


management period I (GA)



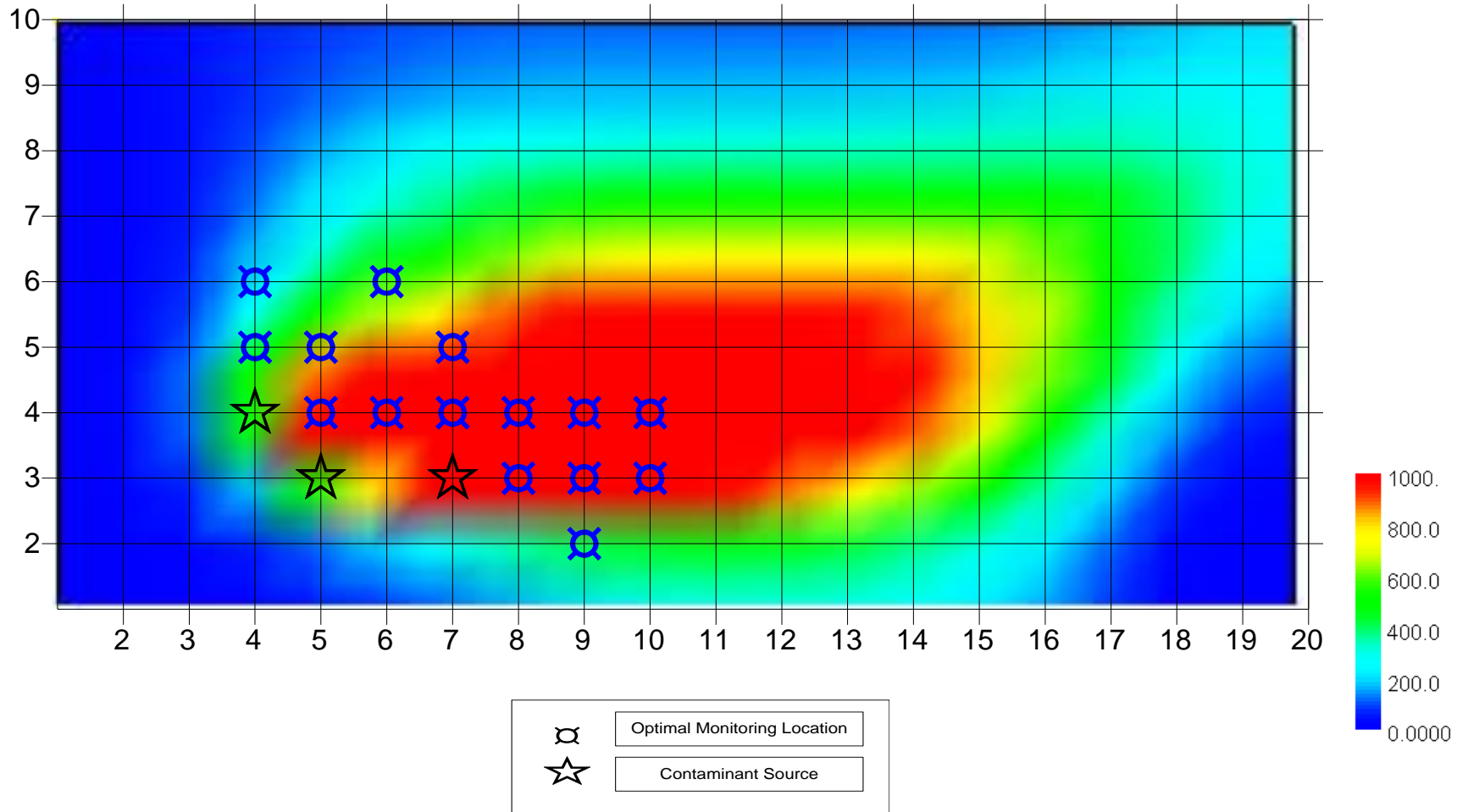
Optimal location of 8 wells

management period I (SA)



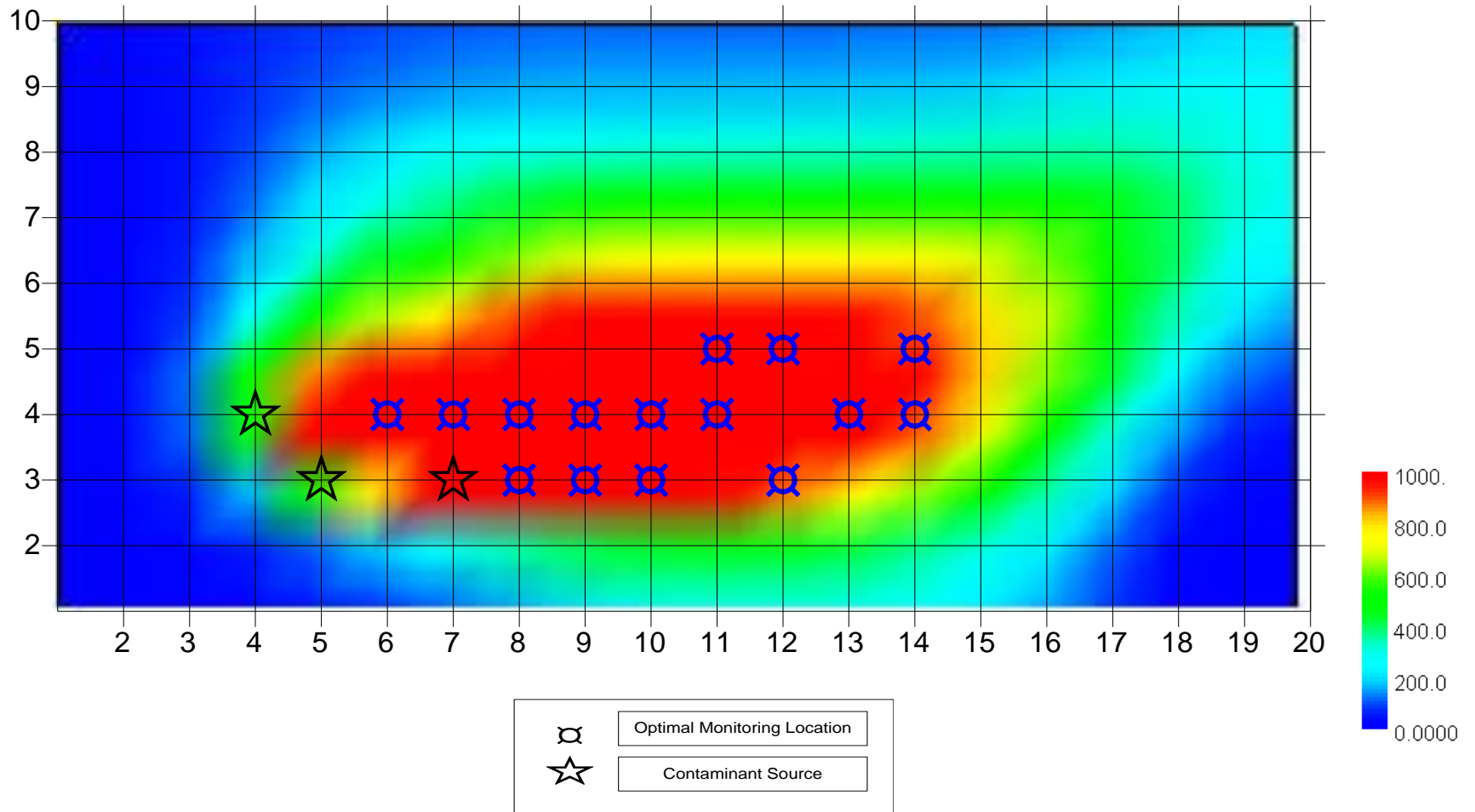
Optimal location of 8 wells

management period II(GA)



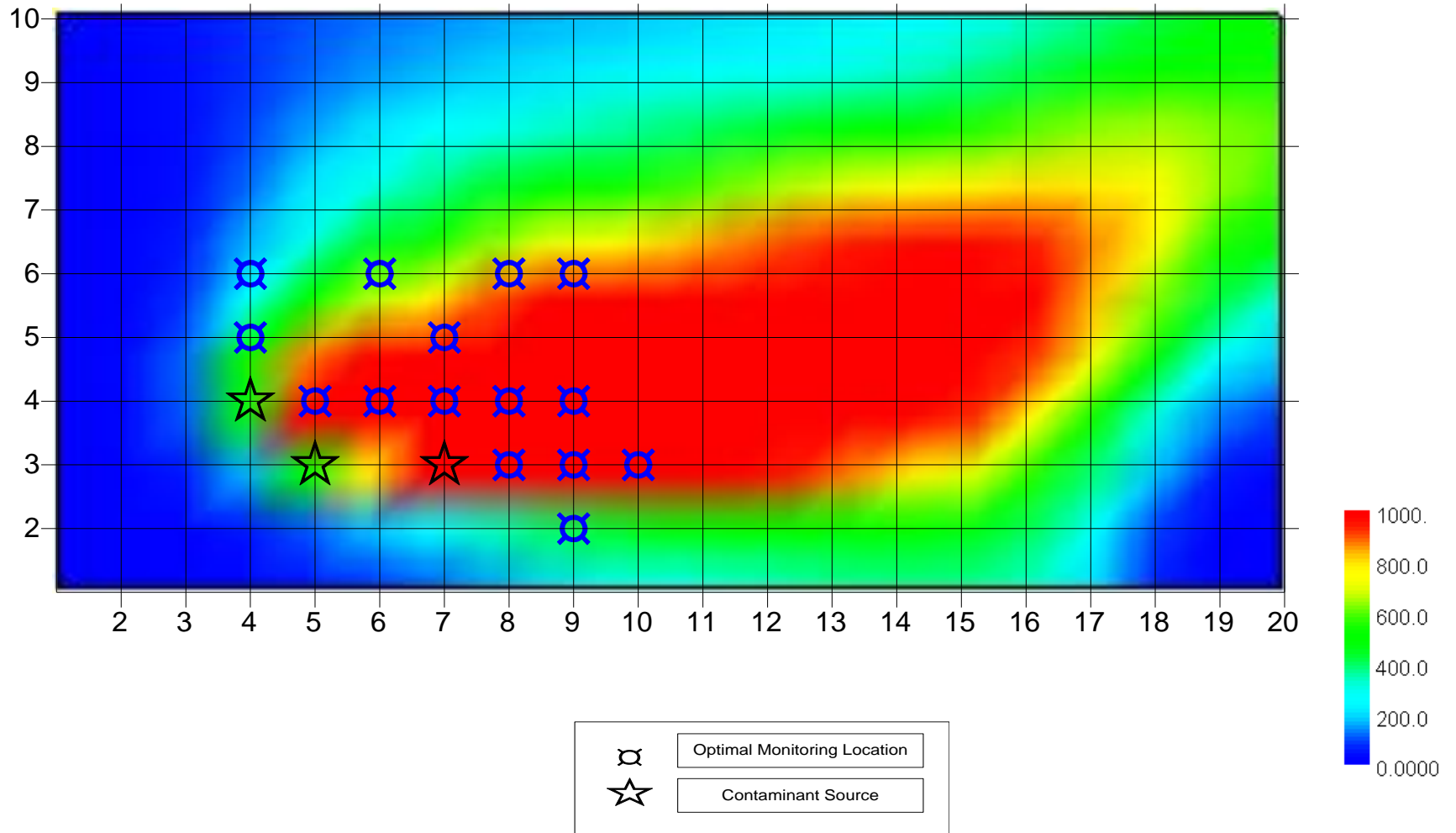
Optimal location of 15 wells

management period II (SA)



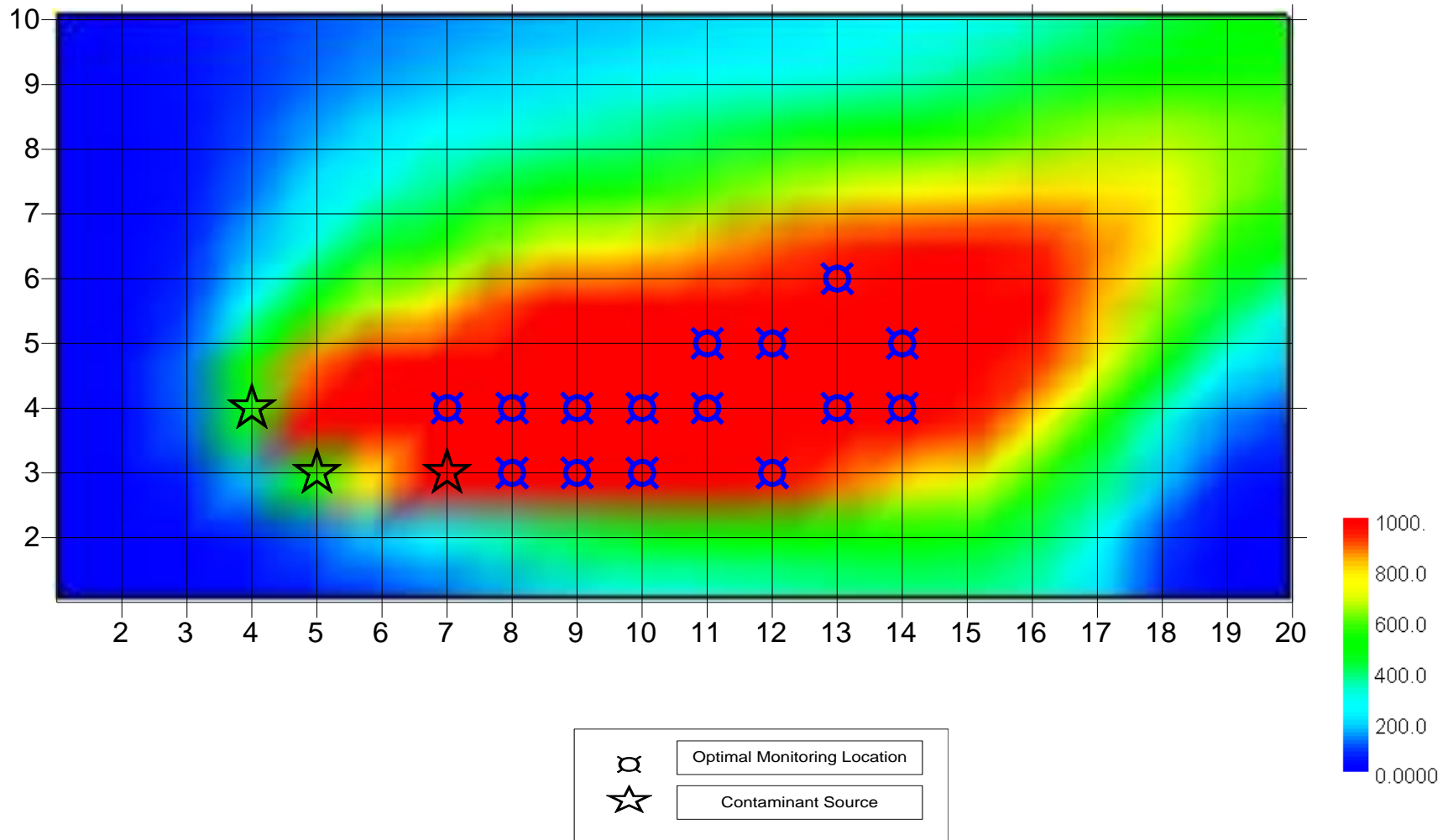
Optimal location of 15 wells

management period III (GA)



Optimal location of 15 wells

management period III (SA)



Optimal location of 15 wells

GA & SA

- The **genetic** process of the standard algorithm uses a "crossover" as do chromosomes in living organisms.
- For two parameters that are close to each other in the coding, a child is likely to get both from one of its parents. While for parameters that are far apart, the child is likely to get one from each parent.
- If the parameters have been transformed to binary, then some pairs of bits should usually inherit from the same parent -- but the algorithm will not know which ones those are.
- If no transformation has been made, then each location should inherit independently of all others.

GA & SA

- In **SA** algorithm one solution is held at a time, and random steps away from this solution are taken.
- If the random step results in a better solution, then that becomes the new solution about which random steps are taken.
- As the optimization proceeds, the average size of the steps gradually decreases.
- The simulated annealing algorithm accepts all new points that lower the objective, but also, with a certain probability, points that raise the objective.
- By accepting points that raise the objective, the algorithm avoids being trapped in local minima, and is able to explore globally for better solutions

GA & SA

- With SA, one usually talks about *solutions*, their *costs*, and *neighbors* and *moves*;
- While with GA, one talks about *individuals* (or *chromosomes*), their *fitness*, and *selection*, *crossover* and *mutation*.
- SA can be thought as GA where the population size is only *one*. The current solution is the only individual in the population. Since there is only one individual, there is no crossover, but only mutation.

Conclusions

- SA and GA are quite close relatives, and much of their difference is superficial.
- The problem of groundwater monitoring is framed as Integer programming and SA outperforms GA.
- The scope of SA is still to be explored for various other engineering application.



Thank You